

PTAS for ETSP

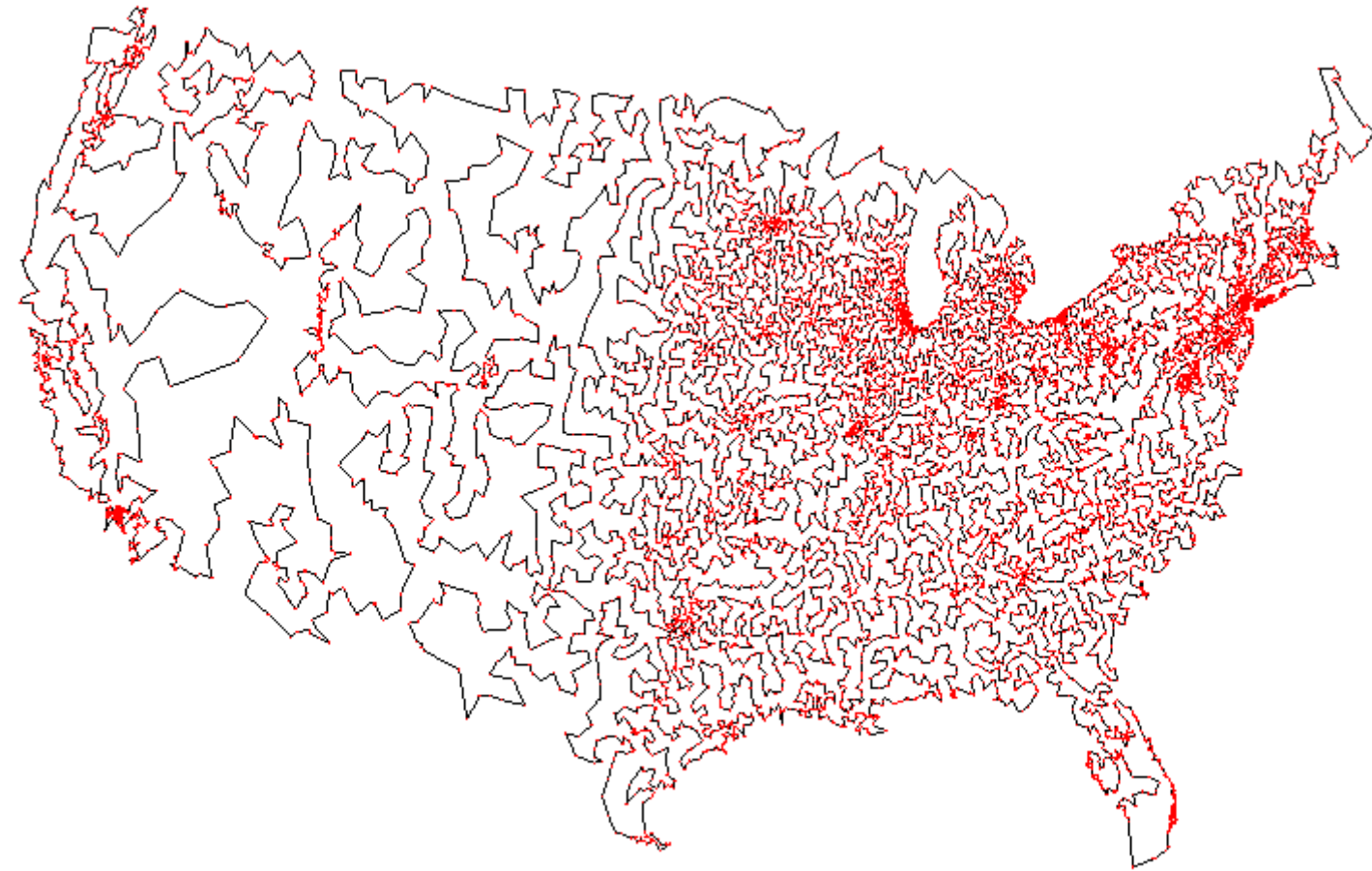
Polynomial-time approximation scheme for the
Euclidean Traveling Salesperson Problem

The Problem

Euclidean Traveling Salesperson Problem (ETSP)

Input: set of points P in \mathbb{R}^2

Output: a shortest TSP tour of P



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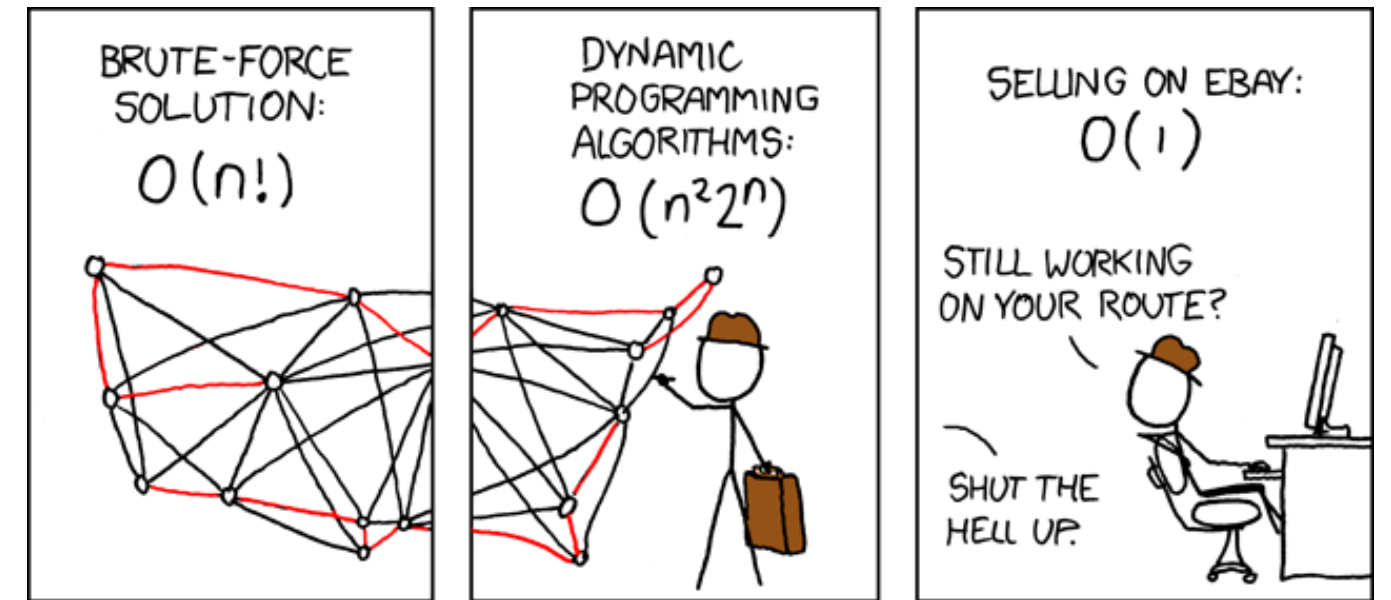


Today: A polynomial-time approximation scheme (PTAS) for the ETSP

Gives for any fixed $\varepsilon > 0$ a polynomial-time $(1 + \varepsilon)$ -algorithm

Motivation

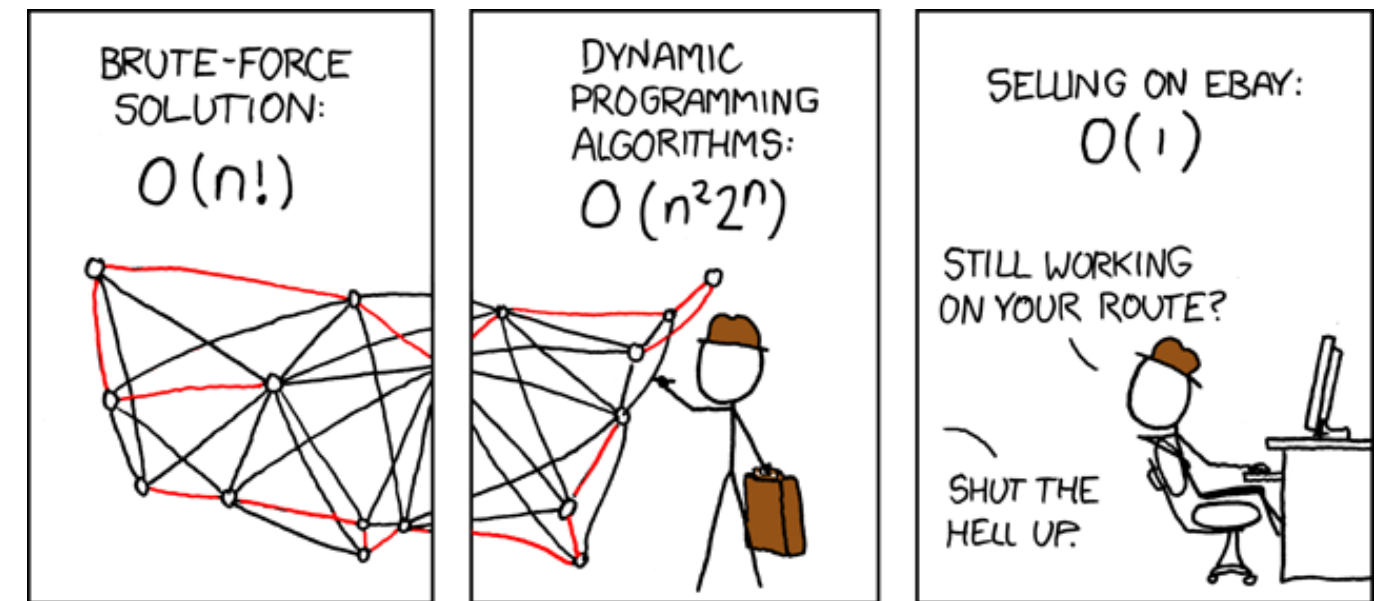
TSP: classic NP-hard optimization problem



<https://xkcd.com/399/>

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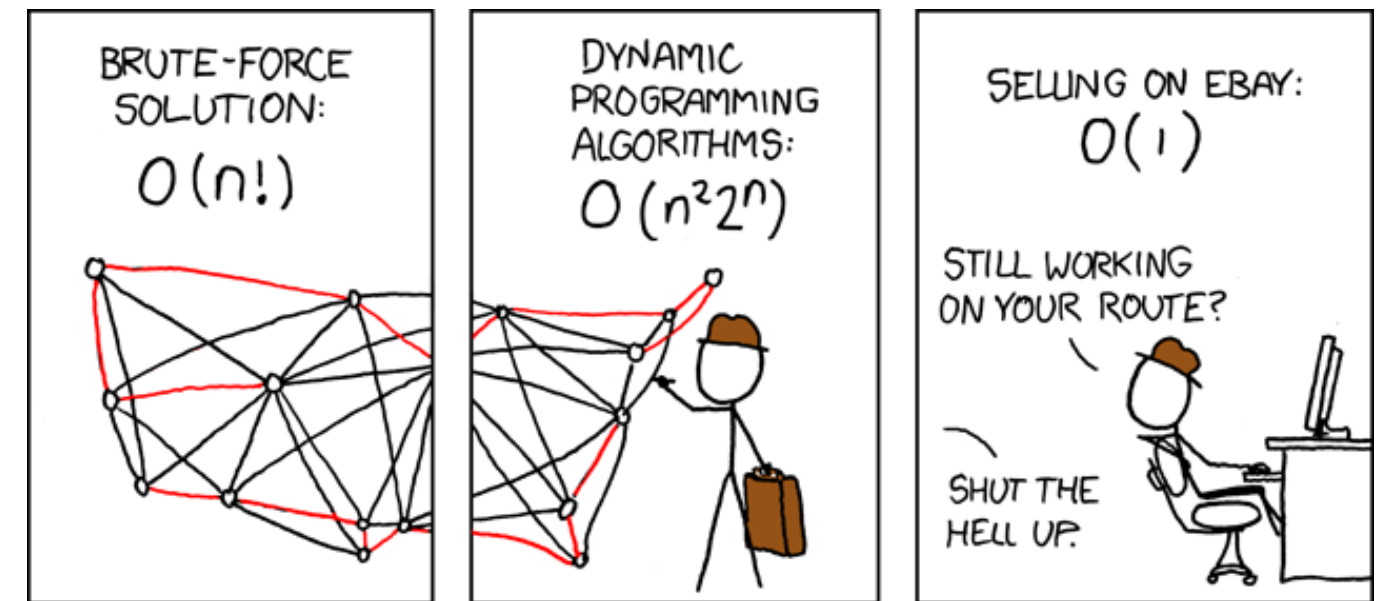
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Polynomial time approximation algorithms for TSP

- for general TSP: not possible

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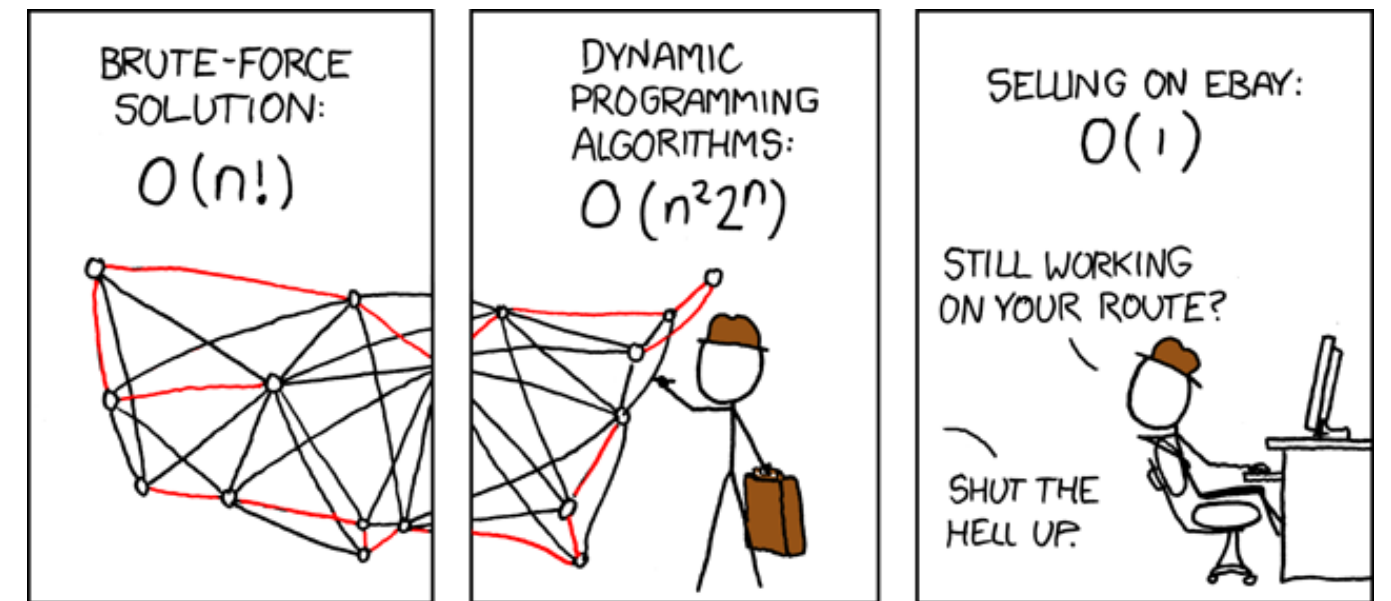
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Polynomial time approximation algorithms for TSP

- for general TSP: not possible
- for metric TSP: not possible with approximation factor $< 123/122 \approx 1.008$,
Christofides: 1.5-approximation, first improved in 2020: $1.5 - 10^{-36}$

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Polynomial time approximation algorithms for TSP

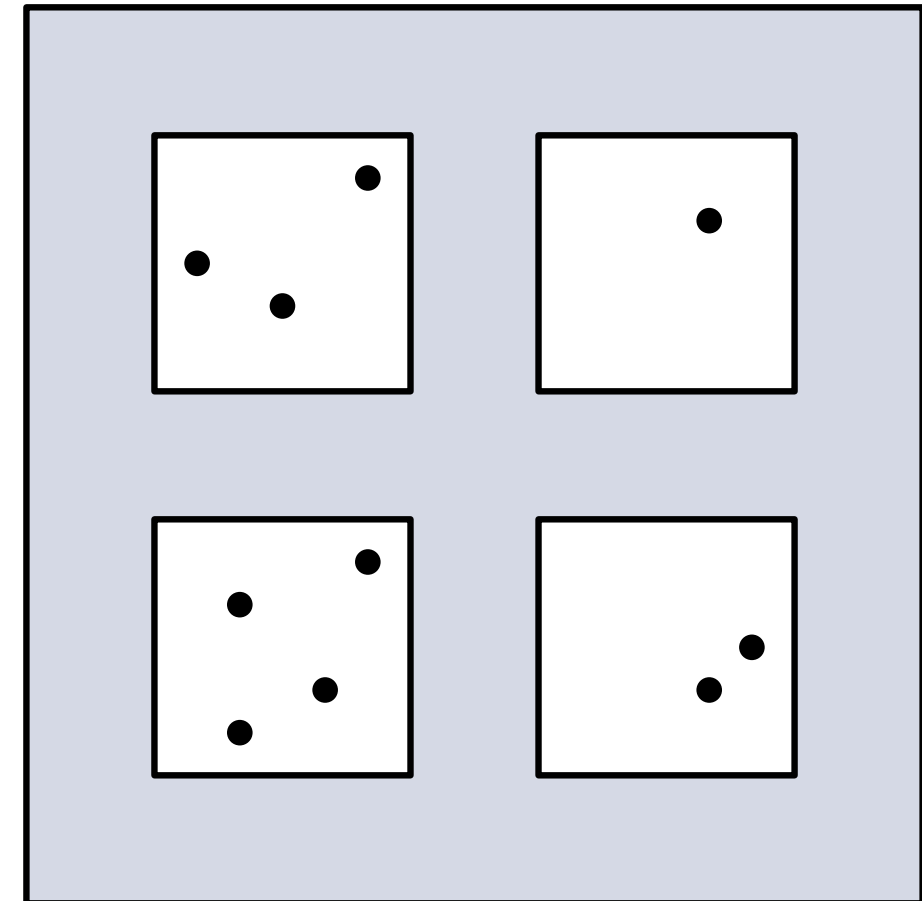
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- for ETSP: PTASs by Sanjeev Arora [1998] and Joe Mitchell [1999]
→ Gödel prize in 2010
today: [Arora's algorithm](#)

Overview

1. Intuition
2. Subproblems
3. Algorithm
4. Running time
5. Quality of approximation

Intuition - Approach

Dynamic programming on **quadtrees**

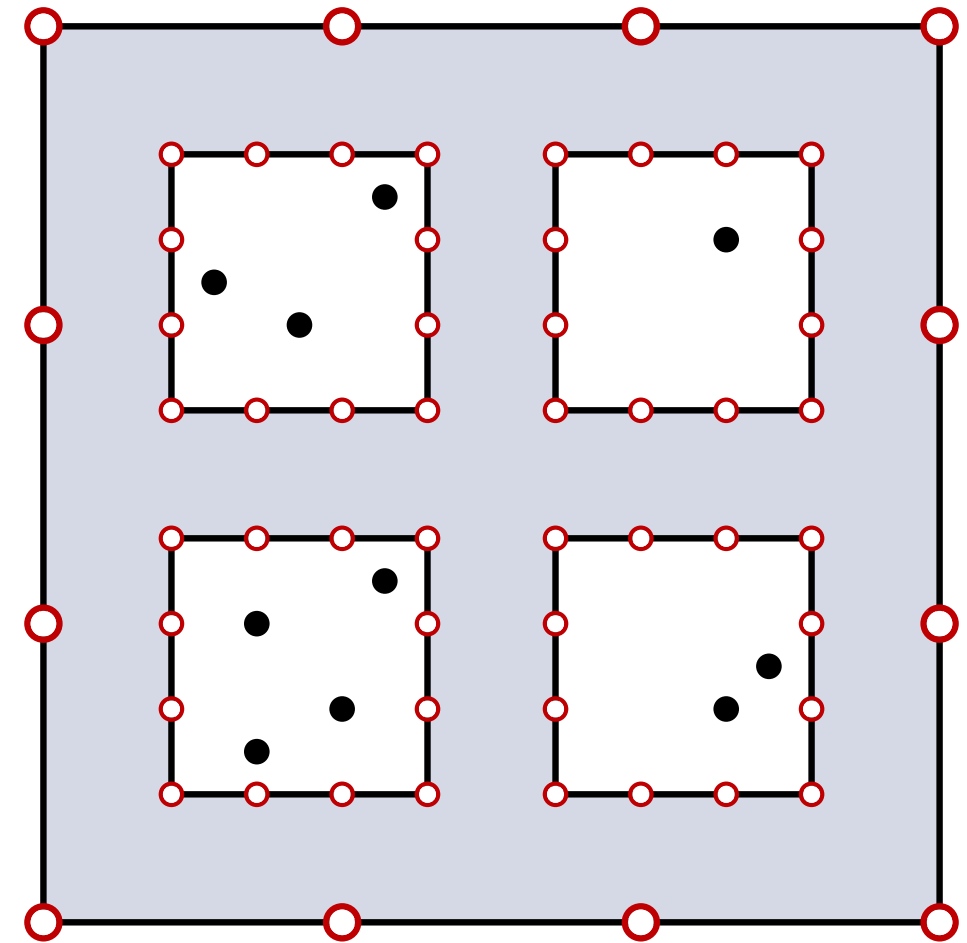


Intuition - Approach

Dynamic programming on **quadtrees**

Portals on the boundaries

Evenly placed and on each corner



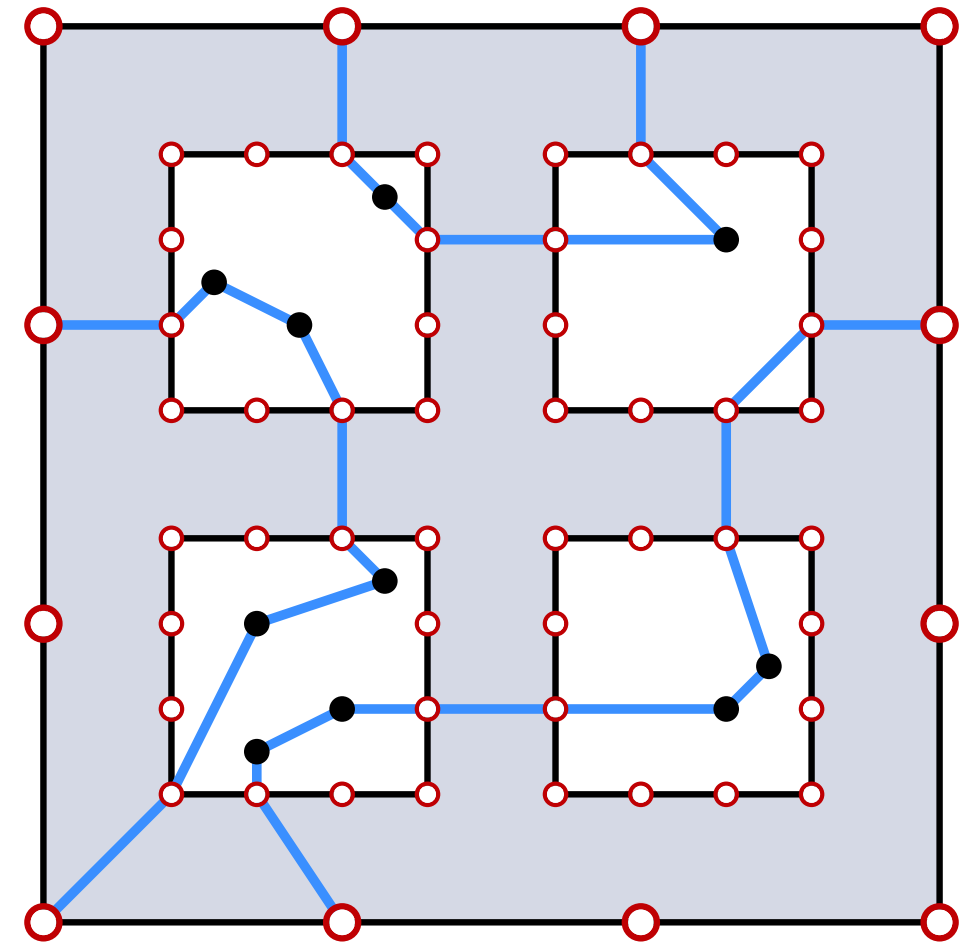
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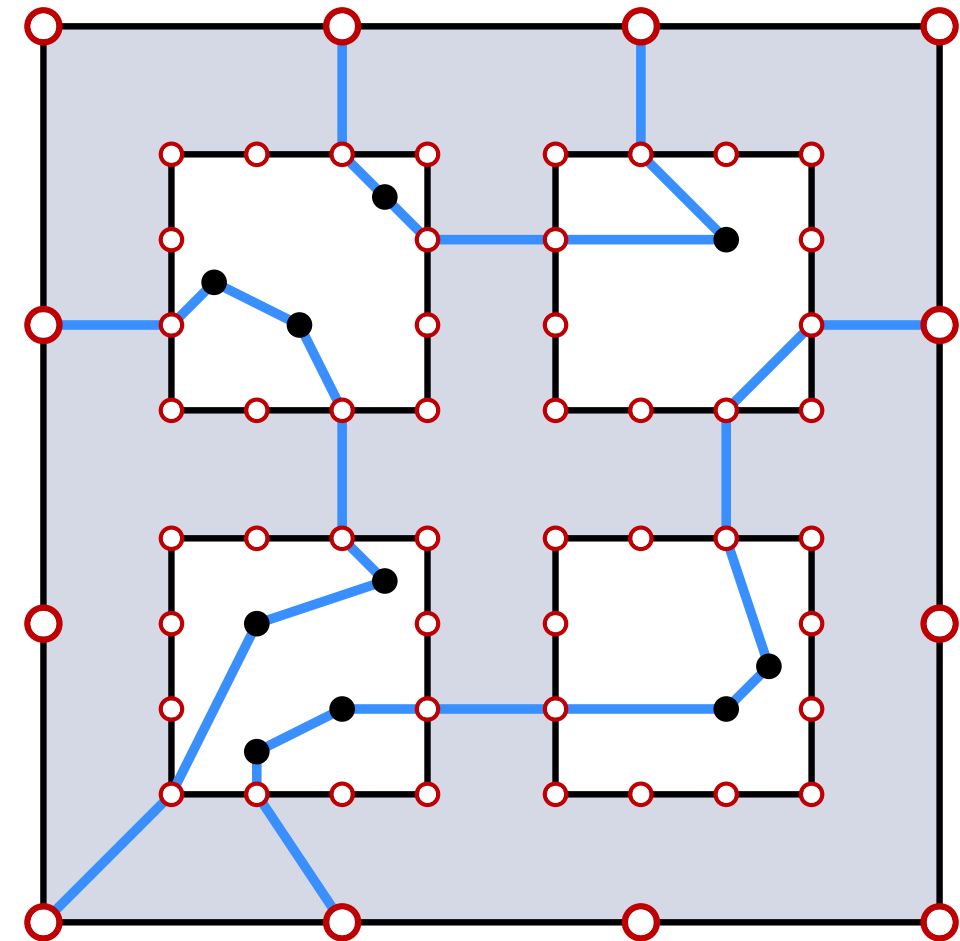
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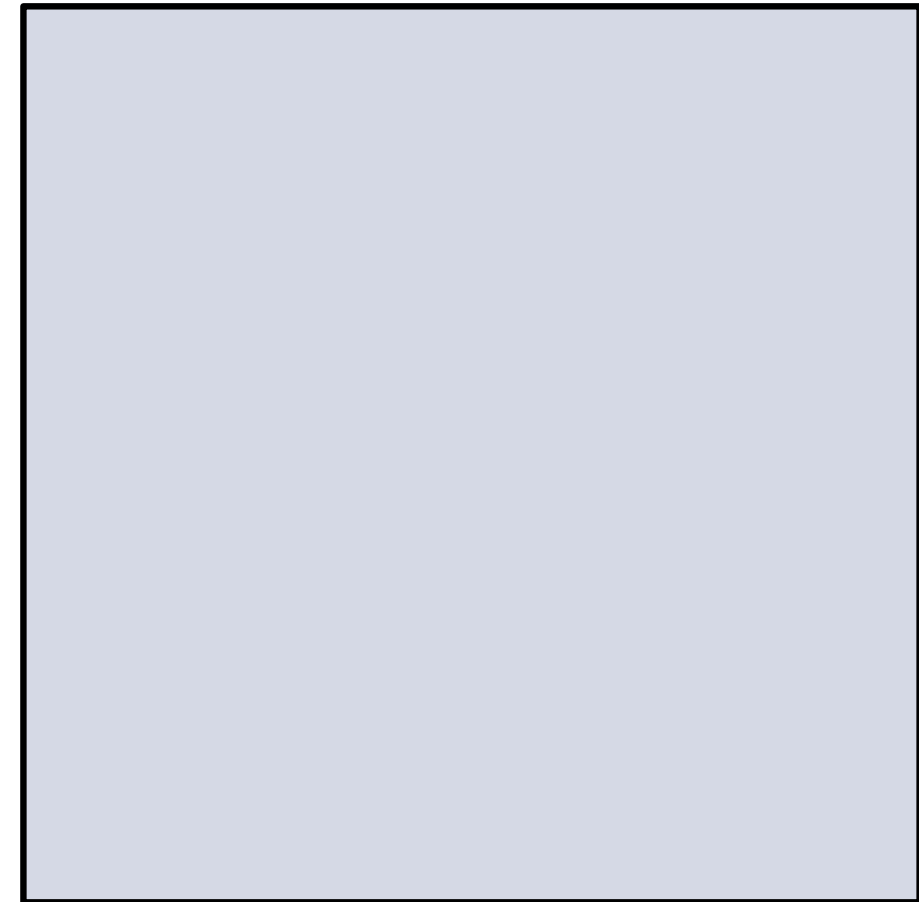
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What defines a subproblem?



Subproblems

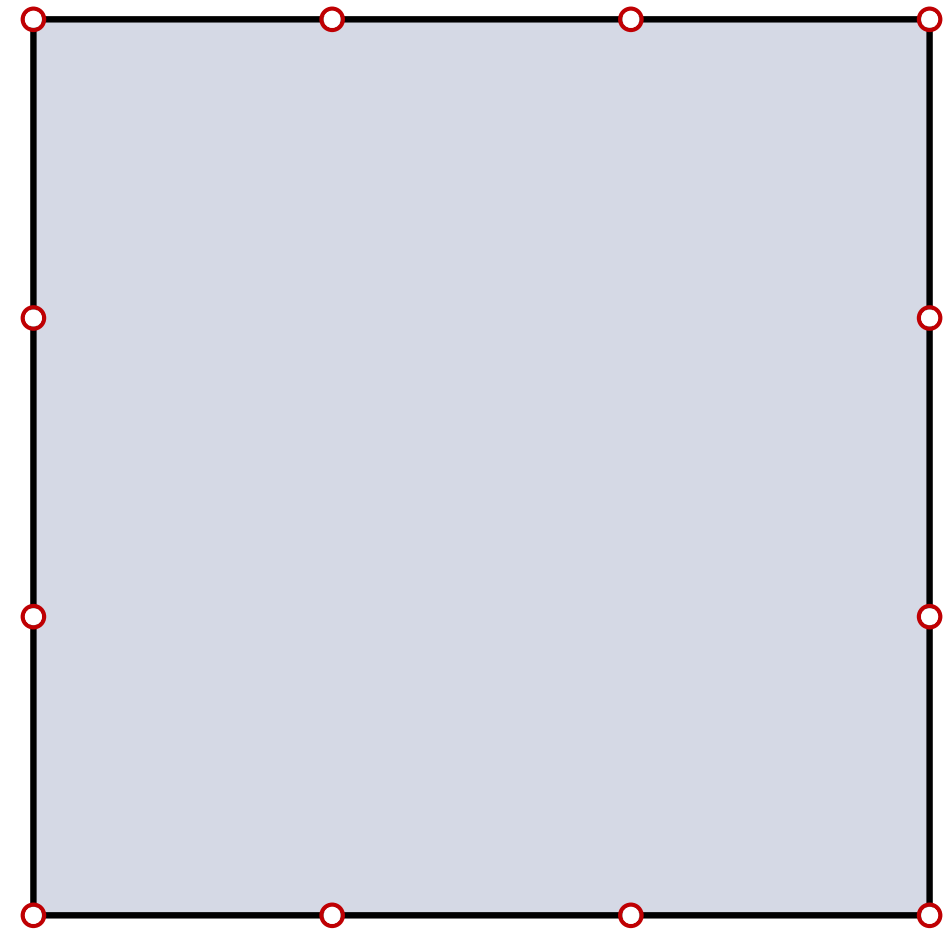
Square S



Subproblems

Square S

The $m + 2$ **portals** on each edge of S

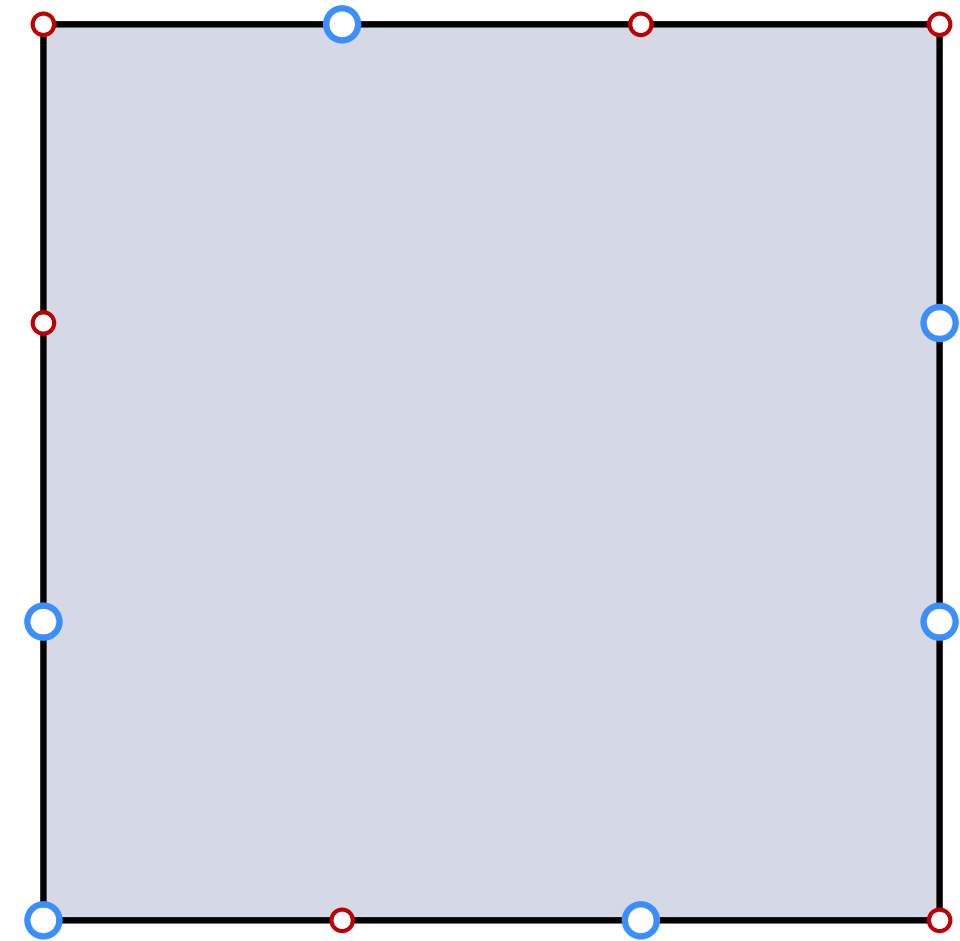


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Which portals are **used**



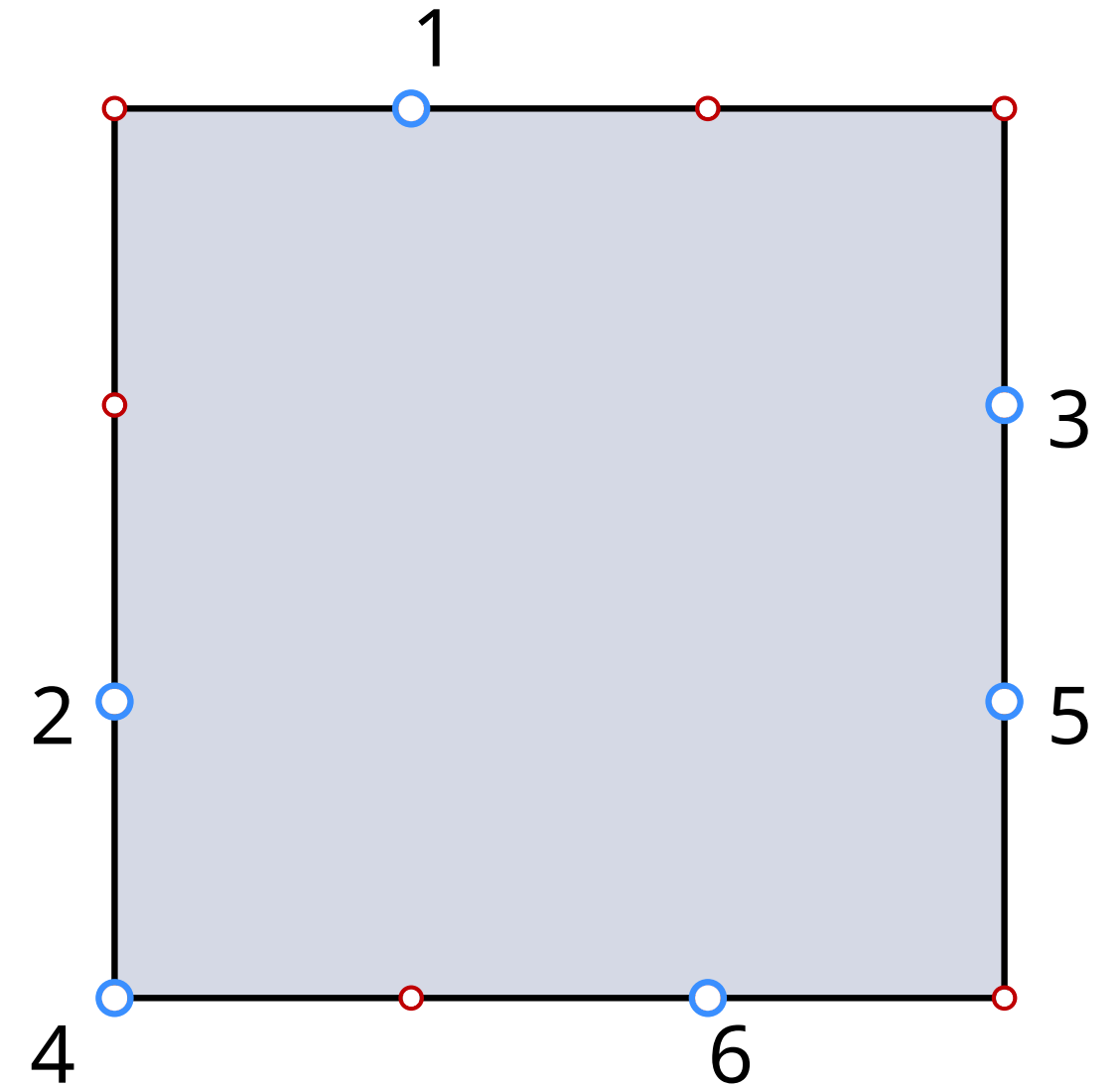
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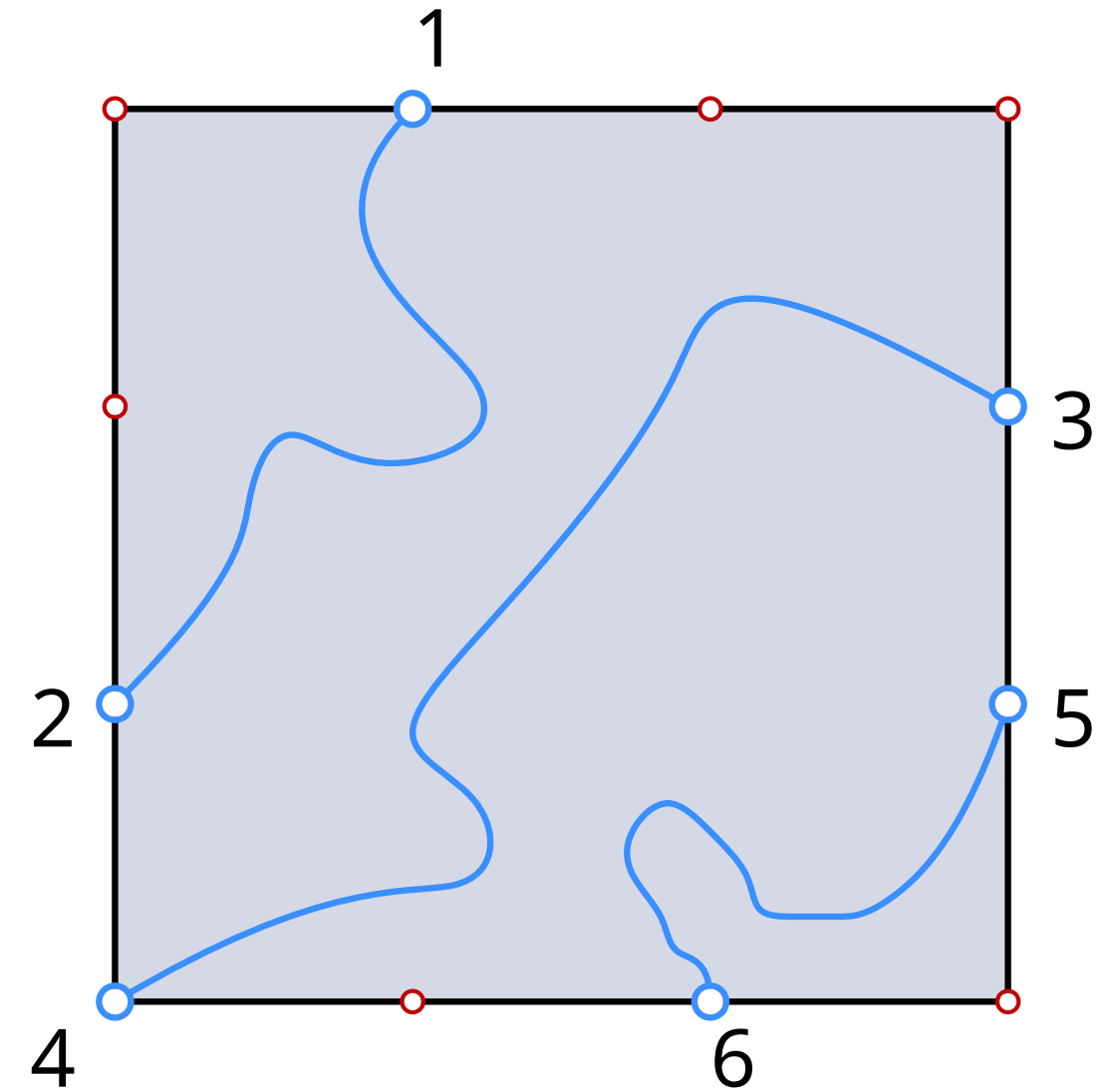
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Subproblem denoted (S, M)

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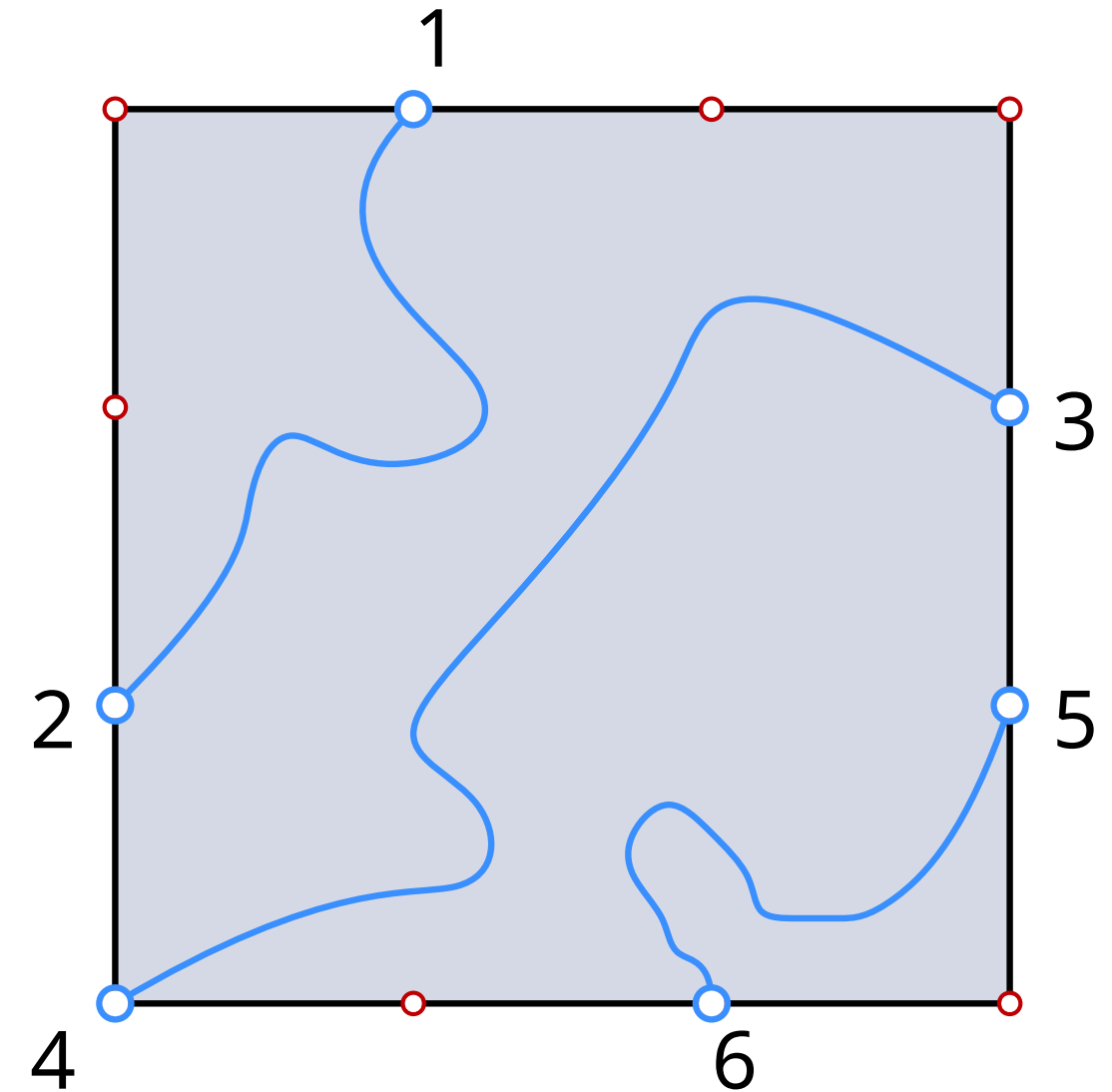
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Restrictions:

The solution takes each portal at most twice (**patching lemma** \rightarrow later)

Per side of S at most k portals can be used



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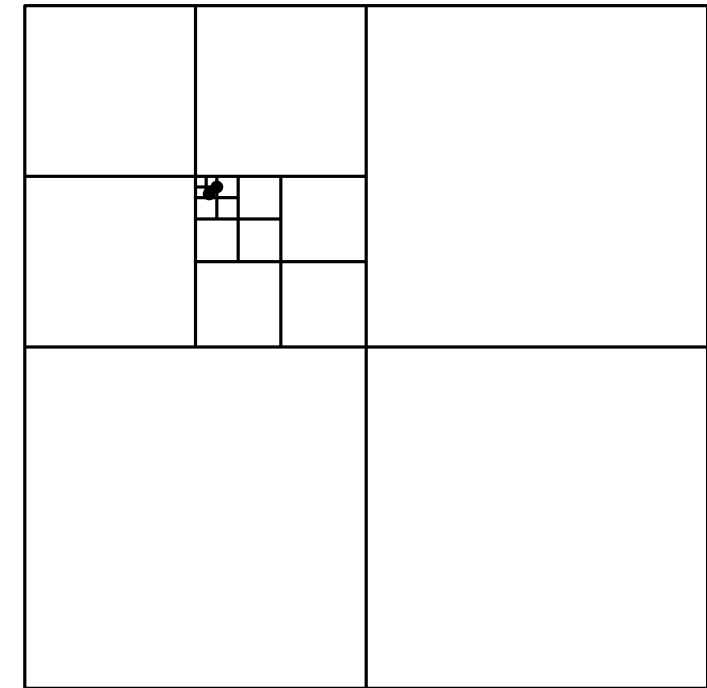
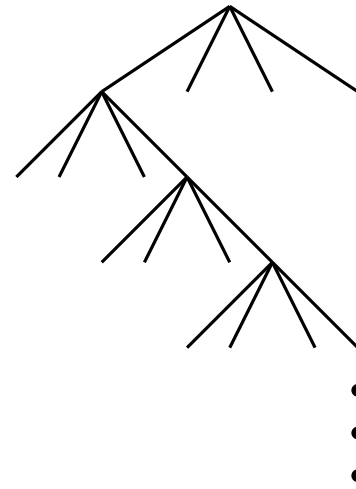
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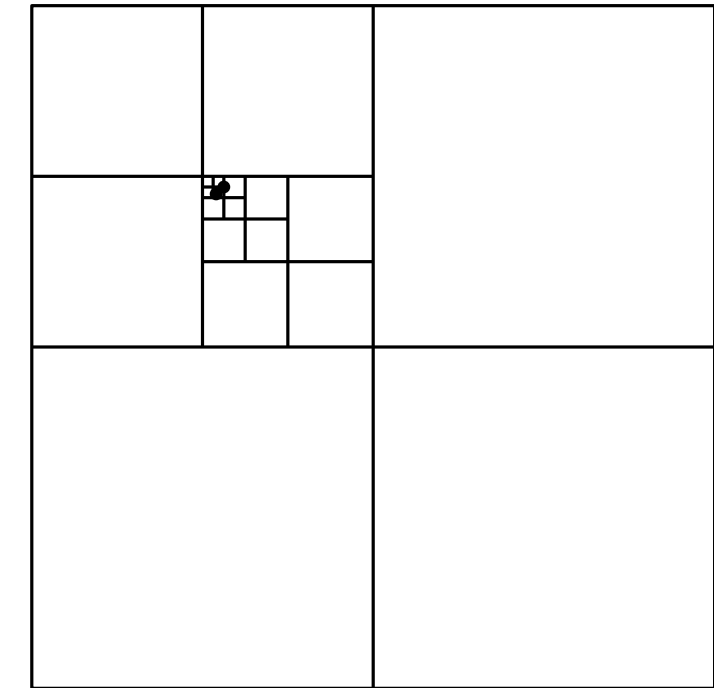
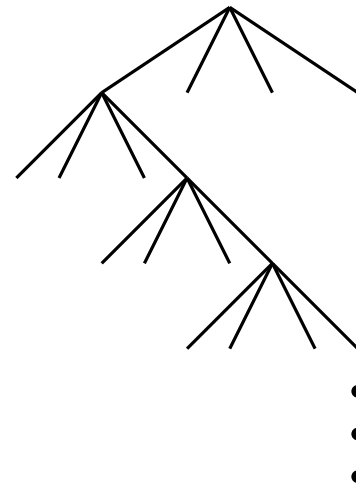
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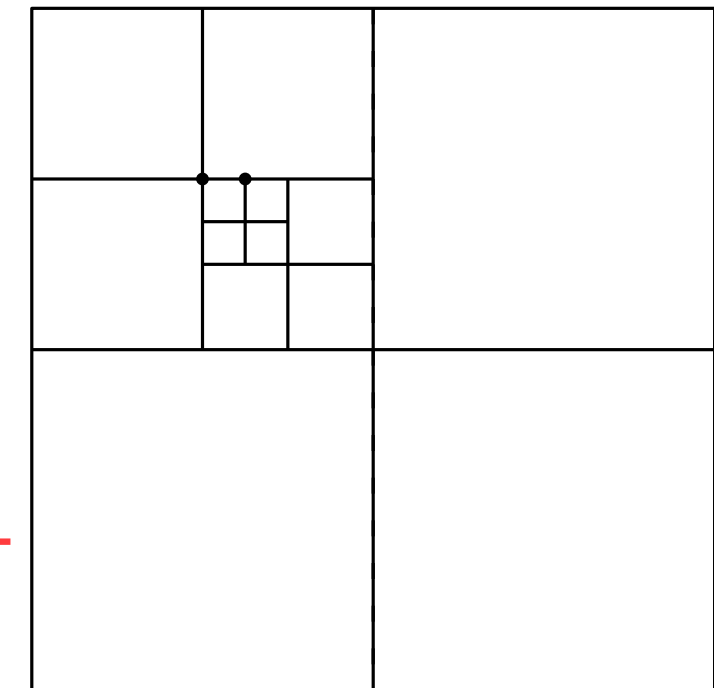
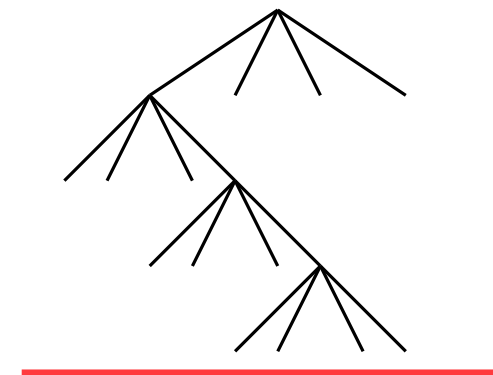
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Solution

1. Snap points to a grid



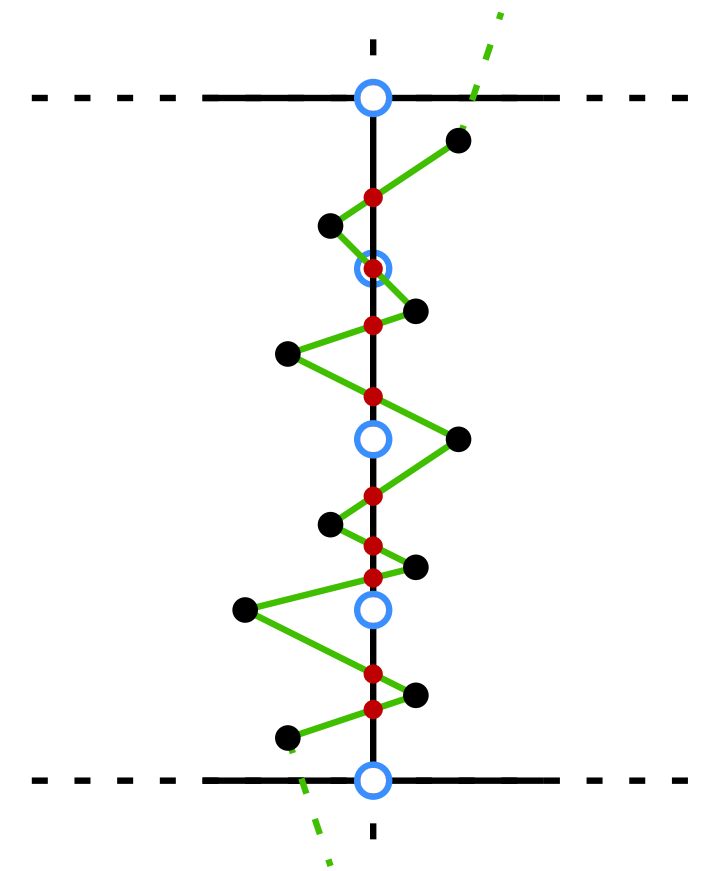
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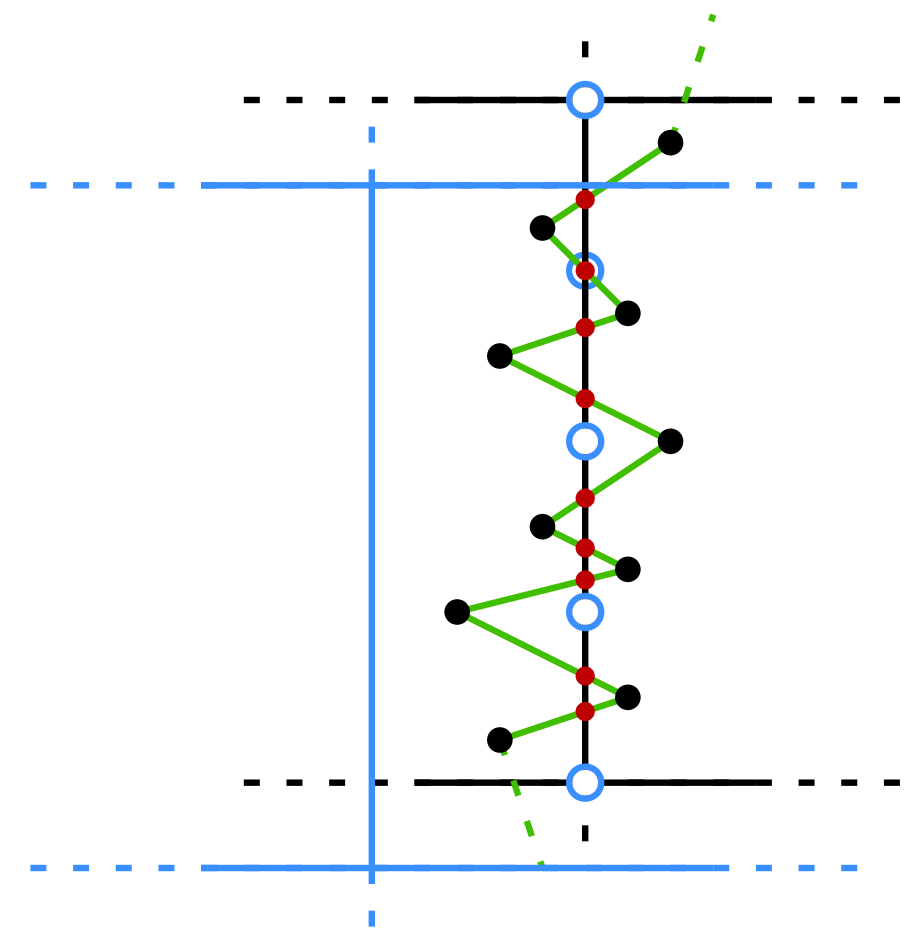
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Problems with constructing a quadtree on P directly?

1. Depth not bounded
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Solution

1. Snap points to a grid
2. Randomize the position of the initial square



A Good Quadtree - Grid

Restrictions on the problem

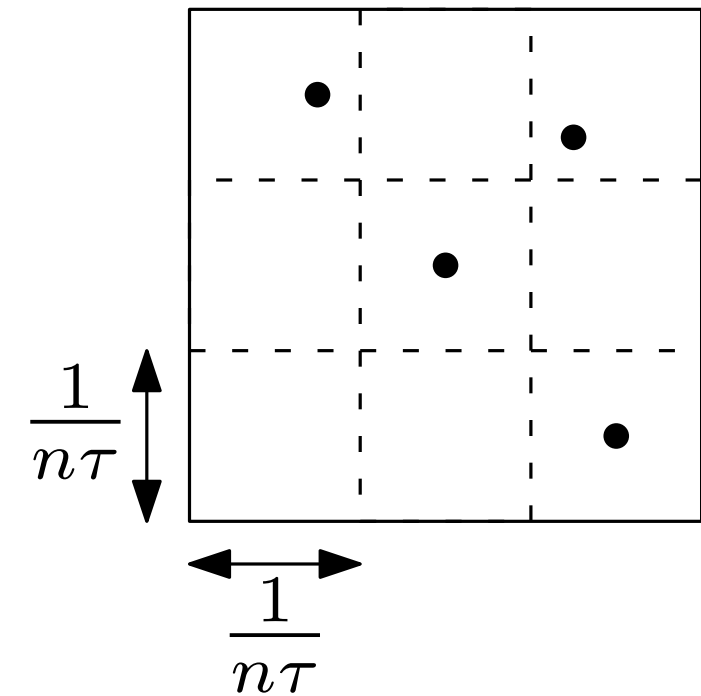
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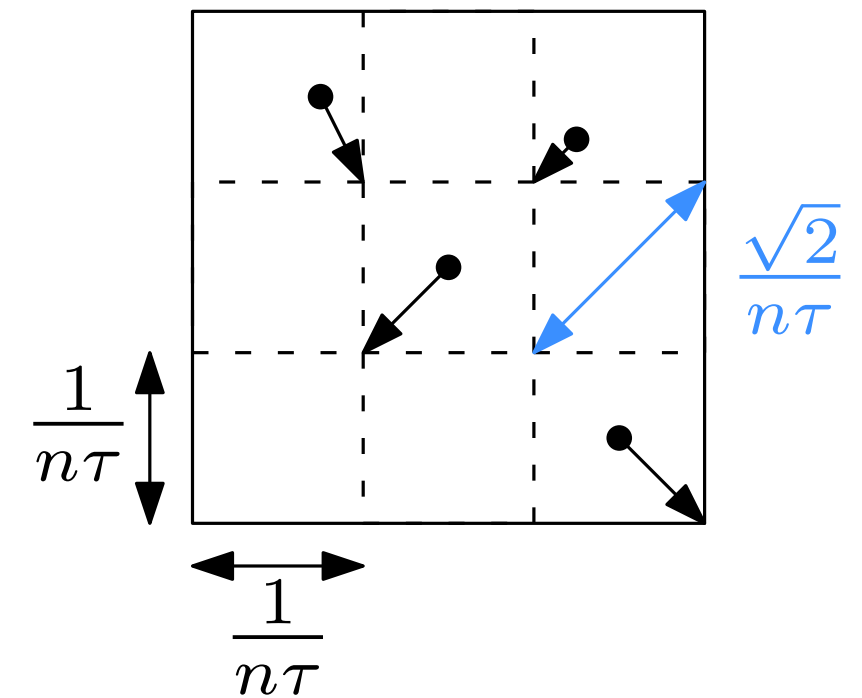
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Let Q be P with snapped to nearest gridpoints

Each point was moved at most $\frac{\sqrt{2}}{2n\tau}$



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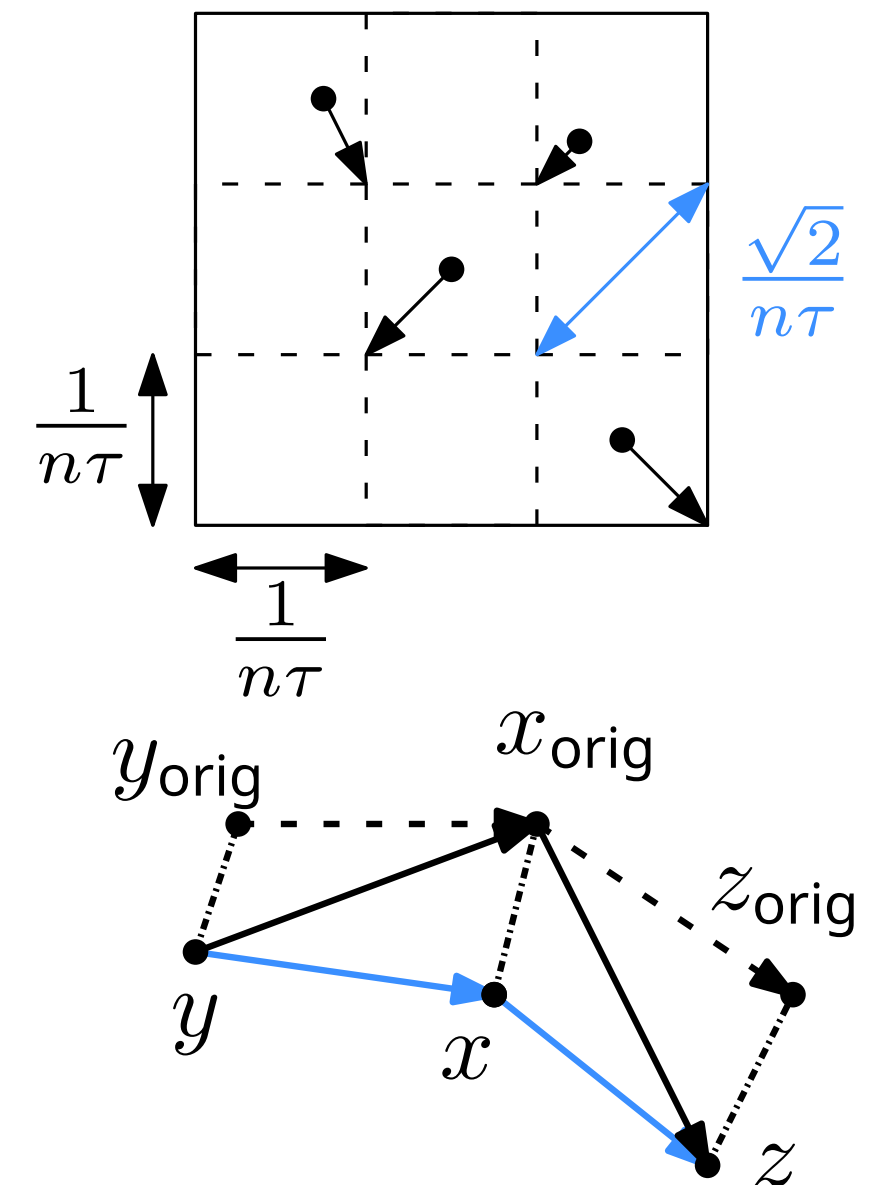
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Solution for Q can be converted to solution for P

Additional cost: $\leq 2n \cdot \frac{\sqrt{2}}{2n\tau}$



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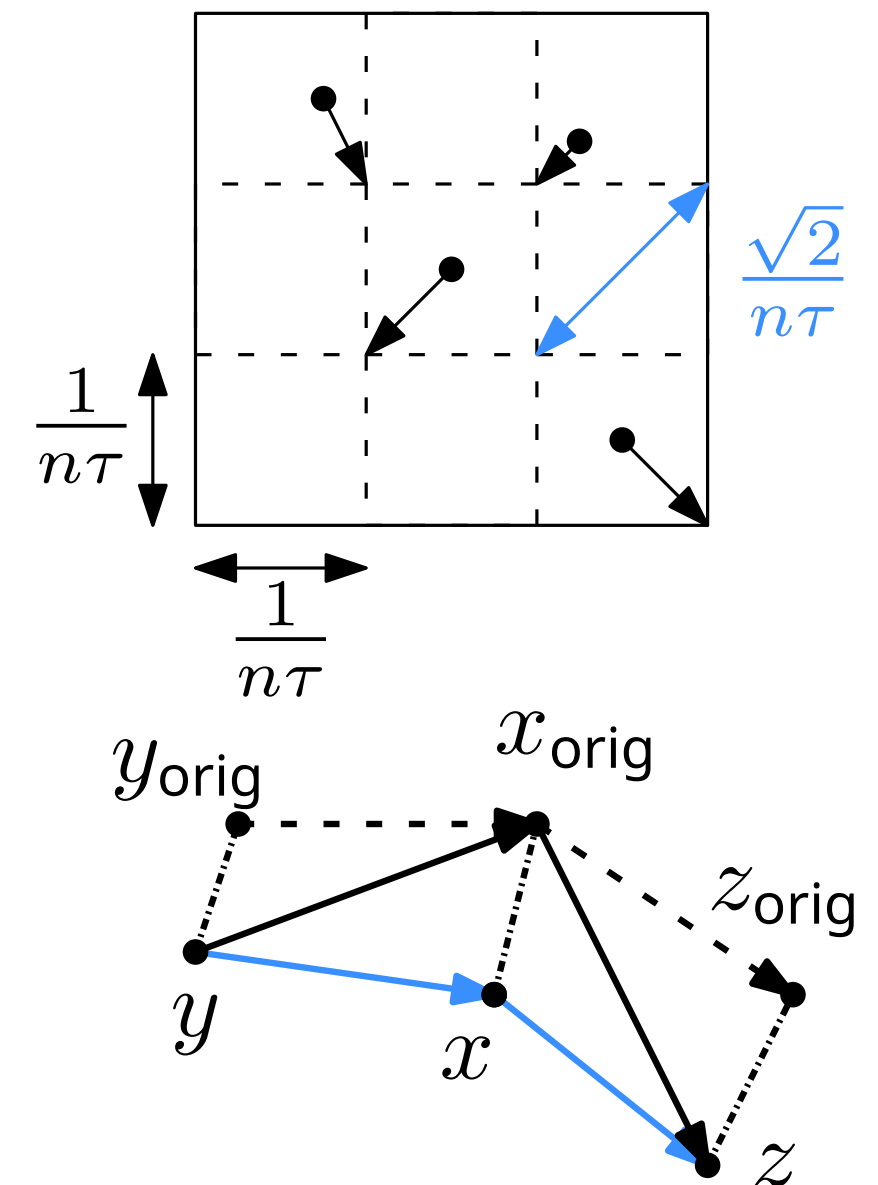
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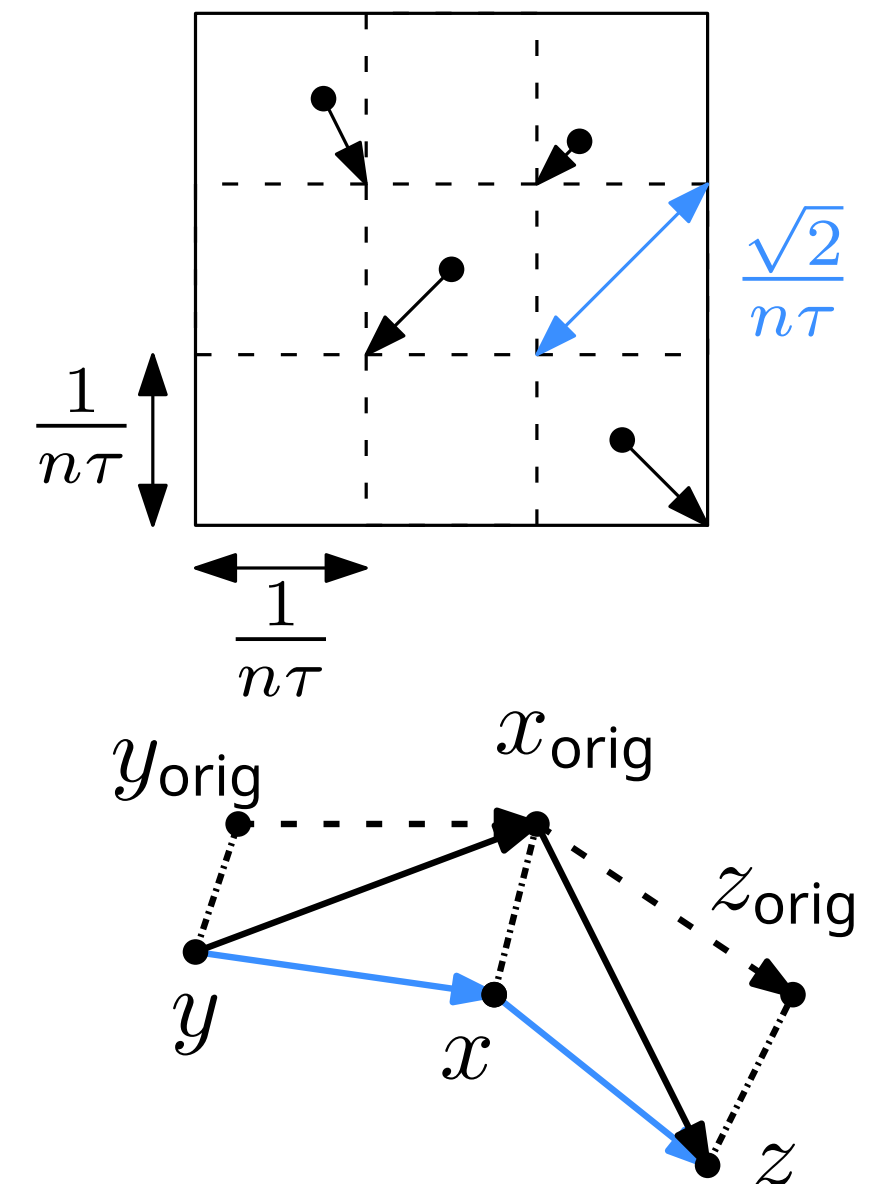
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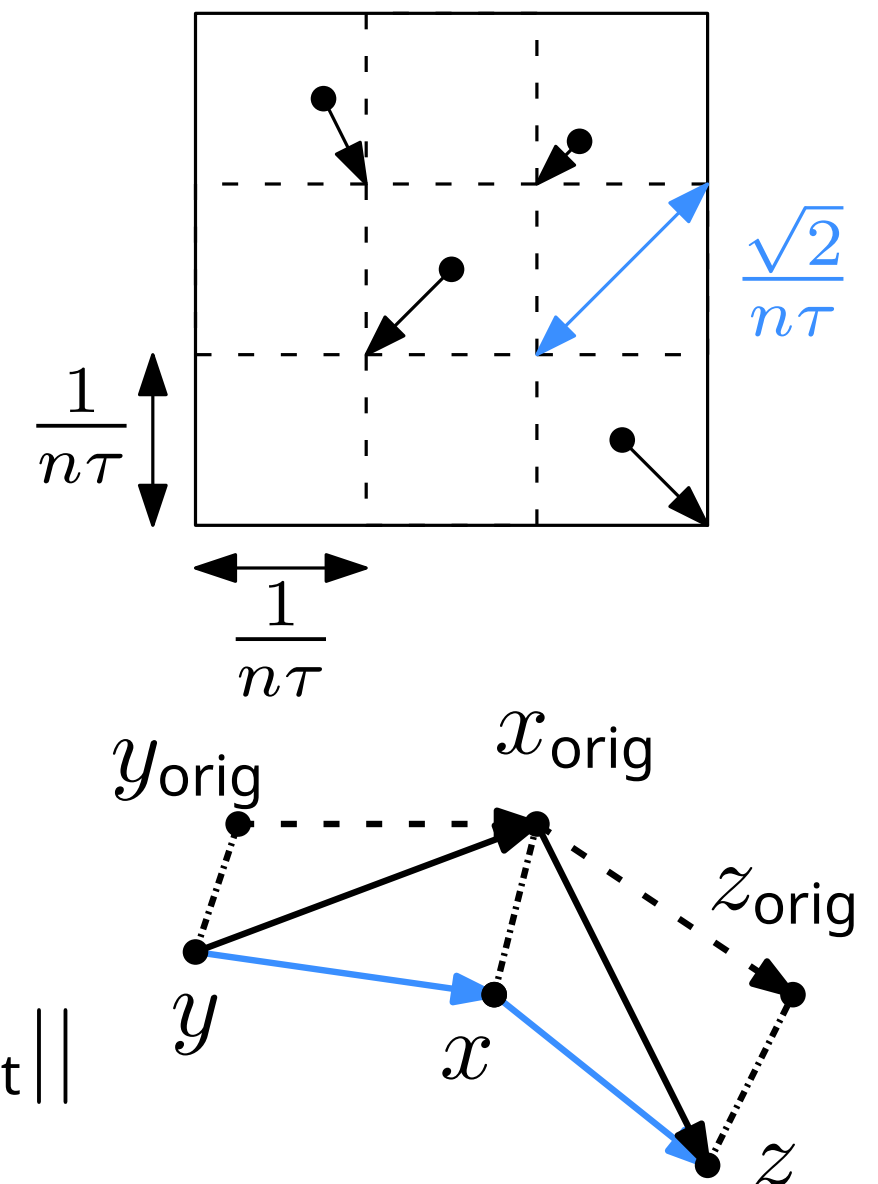
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Diameter of P is at least $\frac{1}{4}$, so an optimal solution must be at least as large



A Good Quadtree - Height

Recall: Q contained in $[\frac{1}{2}, 1]^2$ and on grid of width $\frac{1}{n\tau}$

spread: $\Phi(Q) = \frac{\max_{p,q \in Q} \|p-q\|}{\min_{p,q \in Q} \|p-q\|} = \frac{\sqrt{2}/2}{1/(n\tau)} = \frac{n\tau\sqrt{2}}{2}$

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$$\text{Height } H = \mathcal{O}\left(\log \frac{n\tau\sqrt{2}}{2}\right) = \mathcal{O}\left(\log \frac{n}{\varepsilon}\right) = \mathcal{O}(\log n)$$

Similarly running time and storage of $\mathcal{O}(n \log n)$ follow

Algorithm

Initialization(Q):

Construct quadtree \mathcal{T} over Q with height H

Let $k = \frac{90}{\varepsilon} = \mathcal{O}(\frac{1}{\varepsilon})$, $m \geq \frac{20H}{\varepsilon} = \mathcal{O}(\varepsilon^{-1} \log n)$

Recursive(S, M):

1. **if** $|Q_S| = \mathcal{O}(\frac{1}{\varepsilon})$ **then return** BruteForce(S, M)
2. $\min_{\text{length}} \leftarrow \infty$
3. **for each** combination $C = [C_1, C_2, C_3, C_4]$ of subproblems of children at S :
4. **if** C is **valid** **then**:
5. $\text{cost} \leftarrow \text{ParentConnect}(C, S, M) + \sum_{i=1}^4 \text{Recursive}(C_i)$
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7. **return** \min_{length}

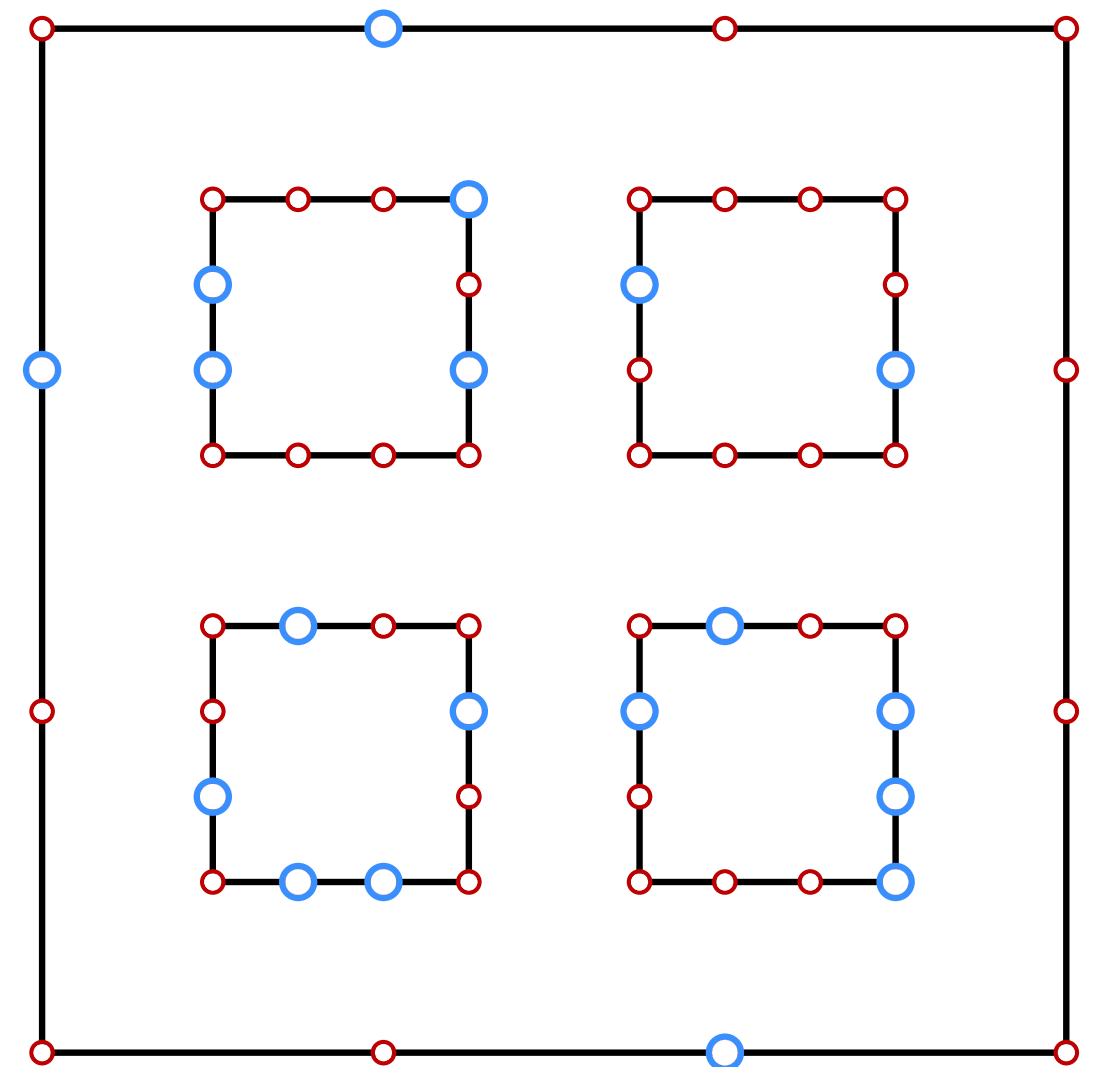
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Recursive(S, M):

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C_i is an arbitrary subproblem for child i

C contains one subproblem for each child



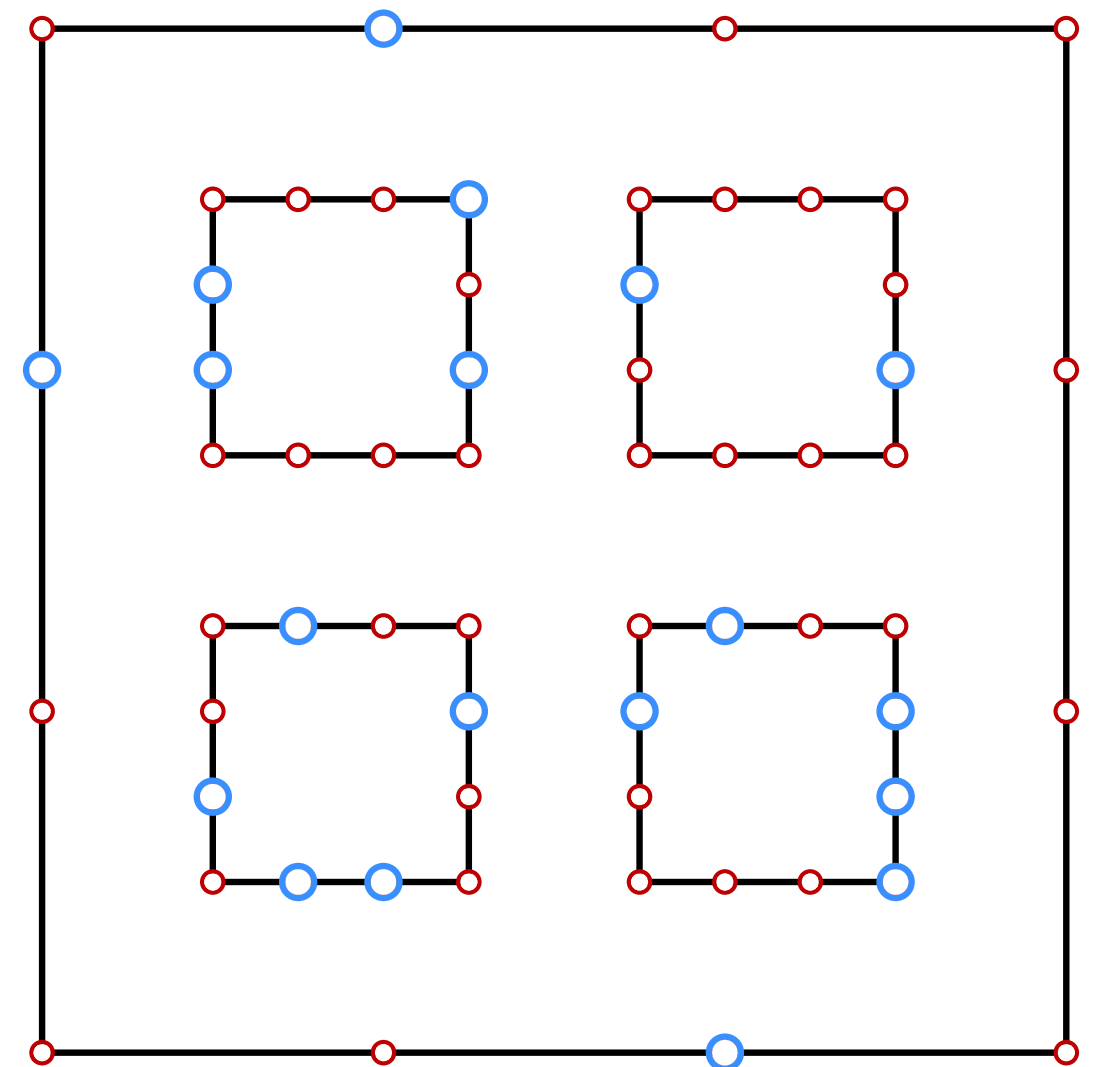
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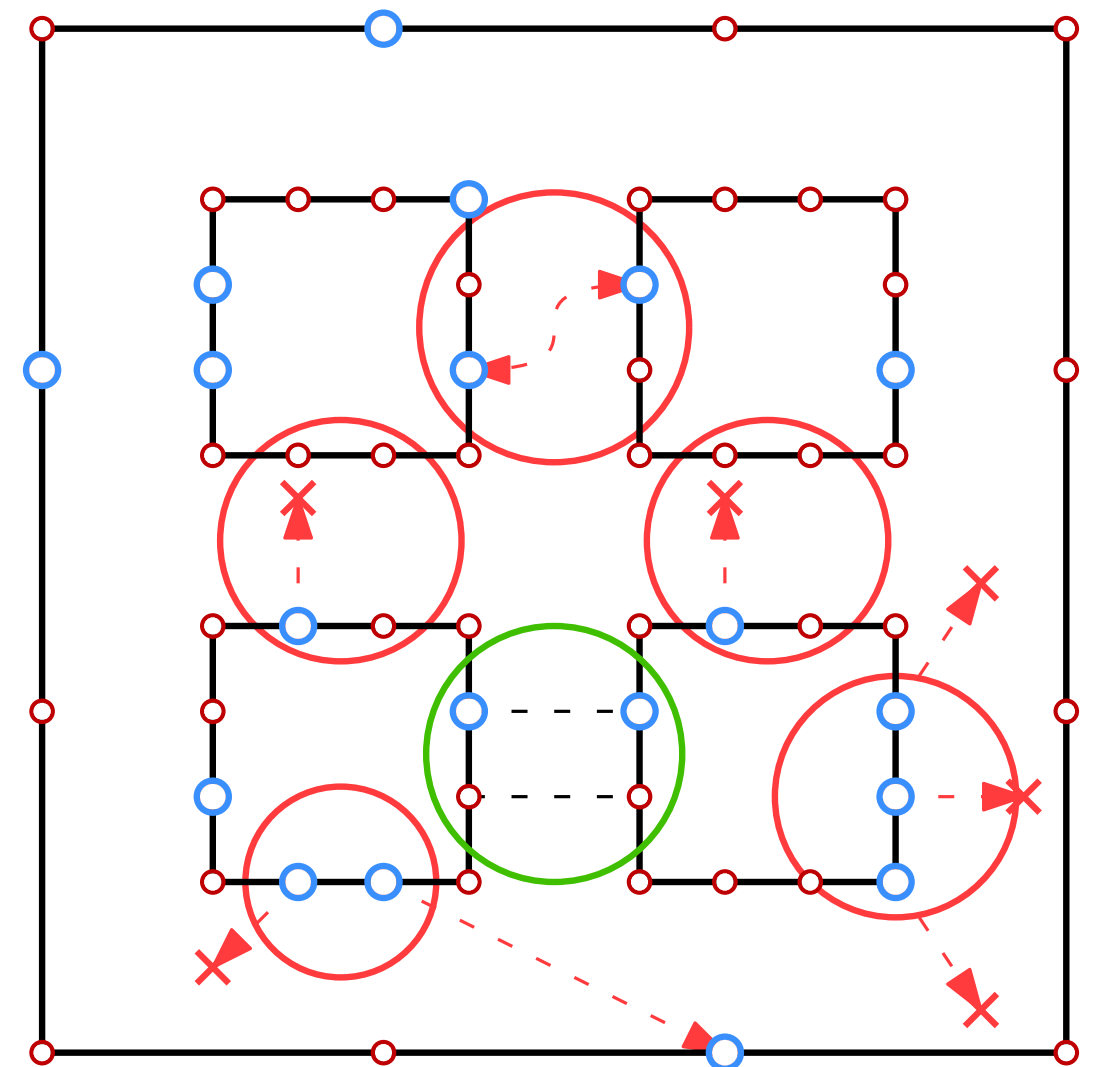
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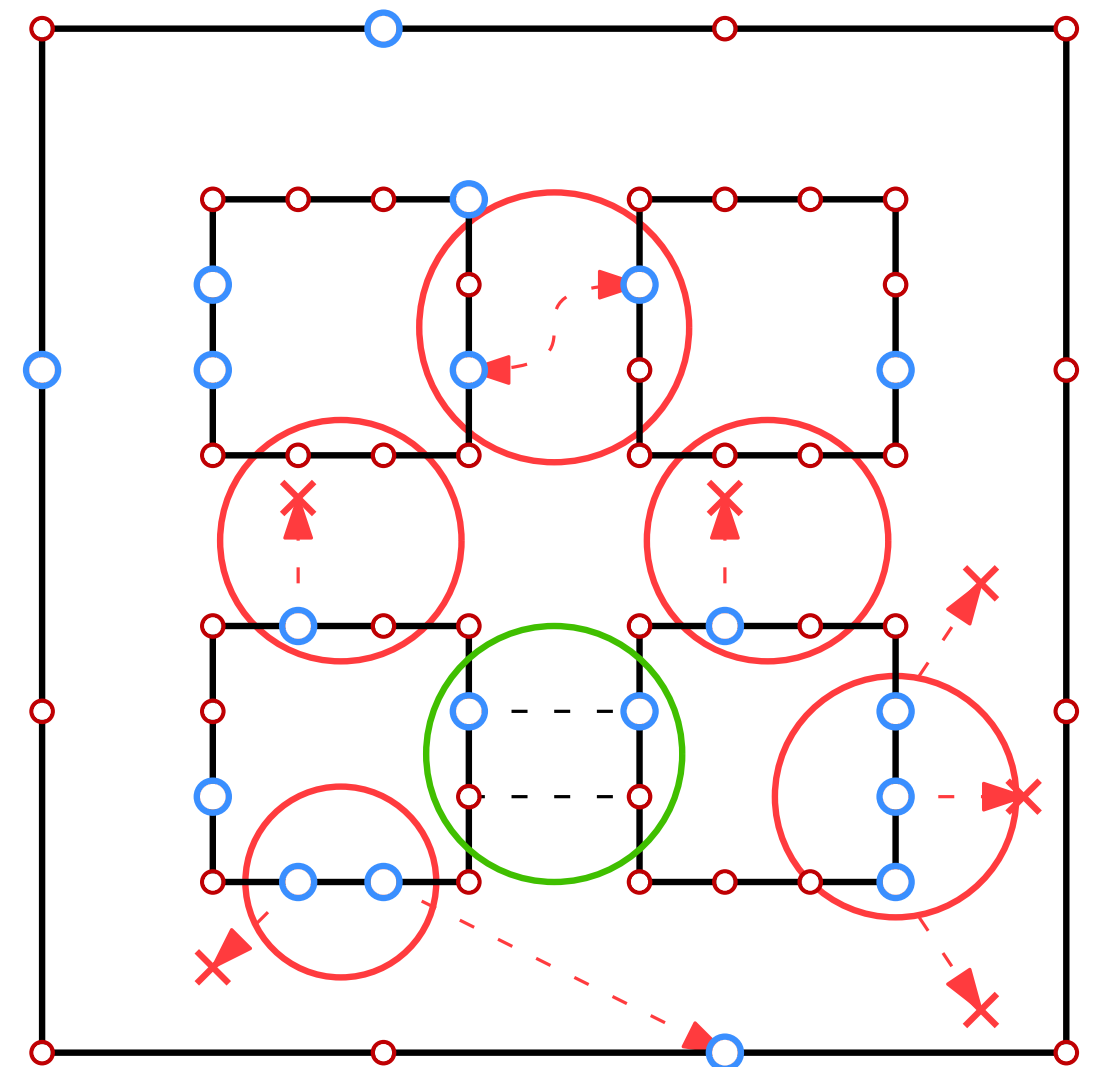
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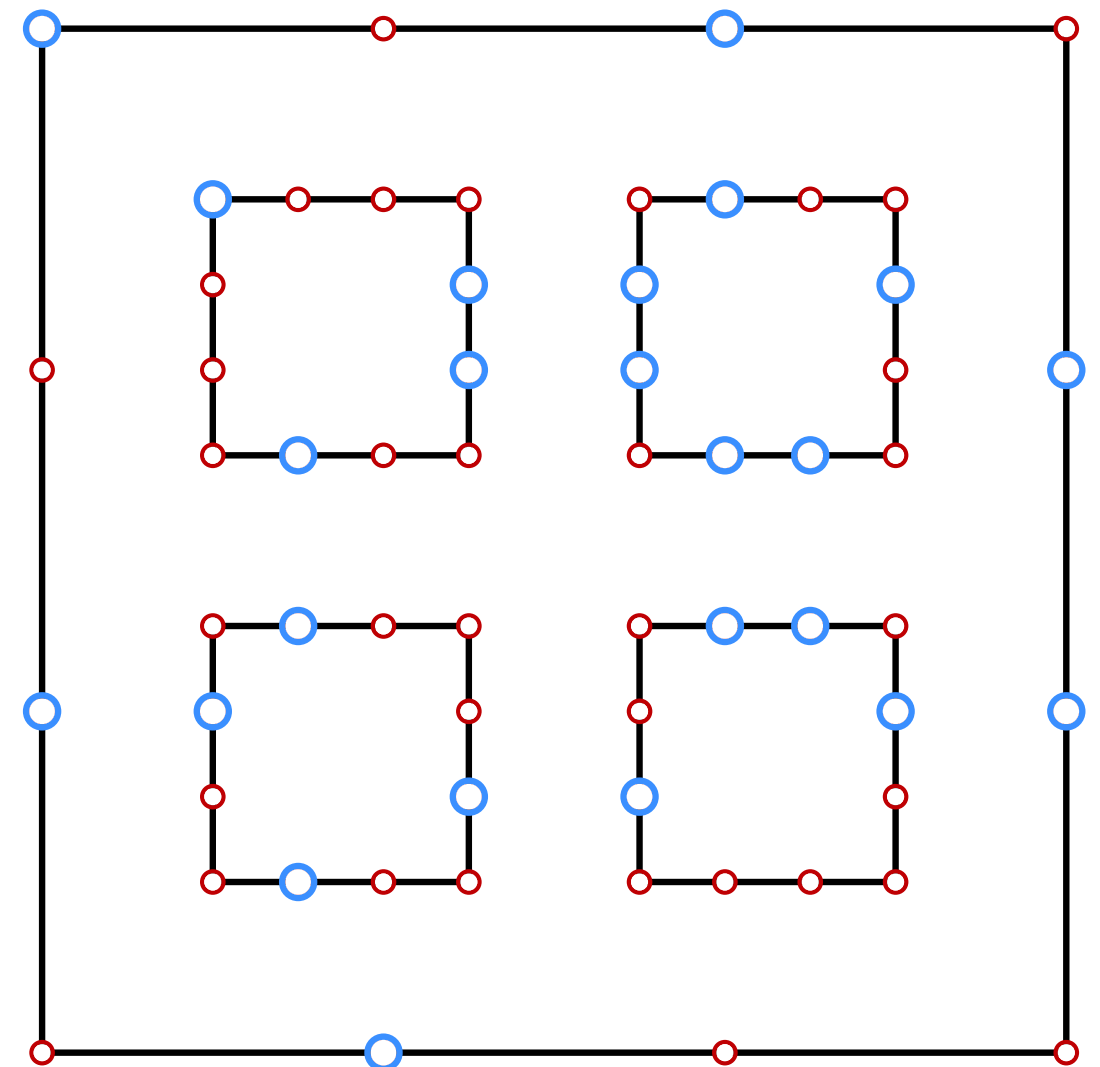
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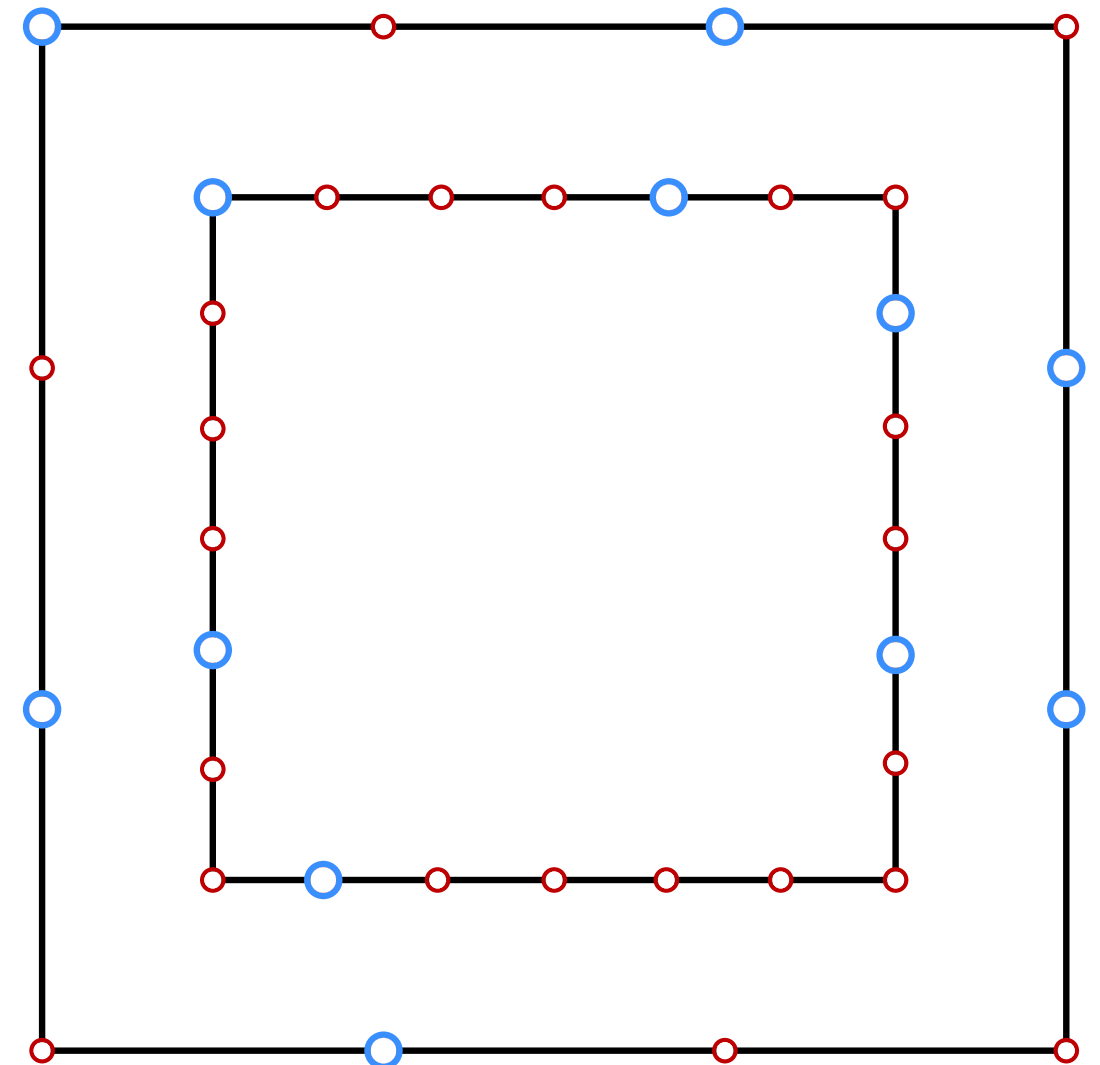
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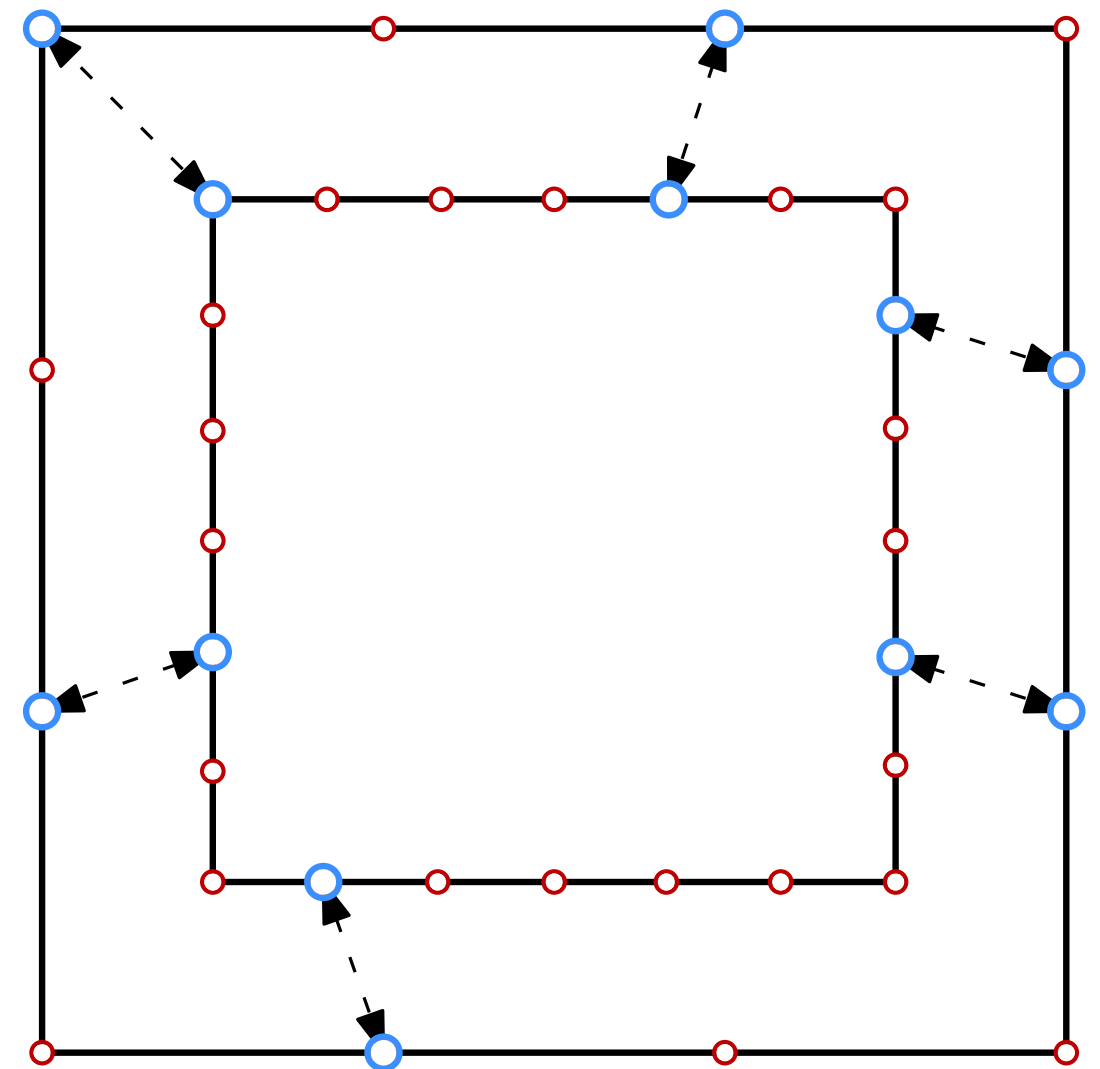
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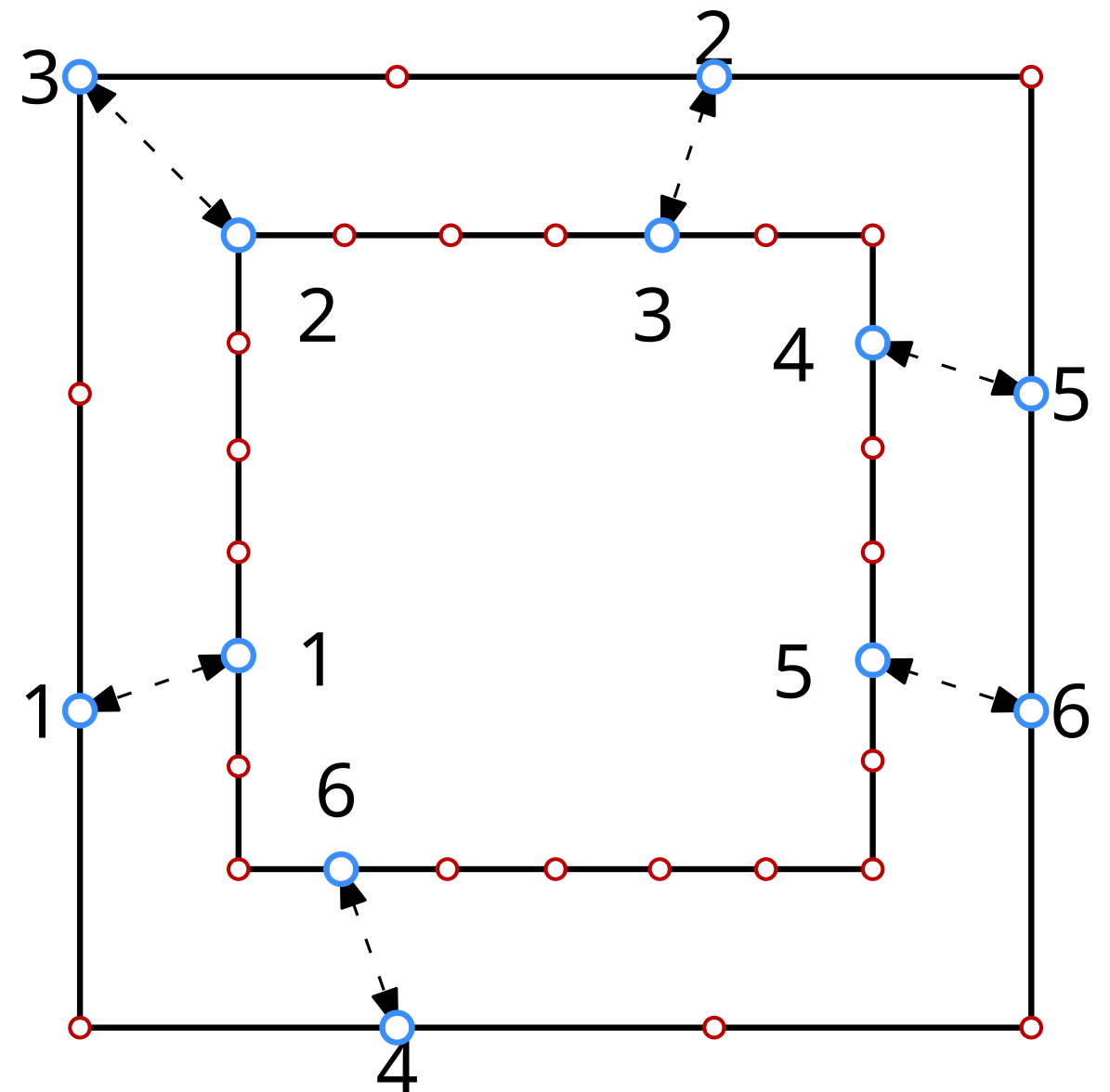
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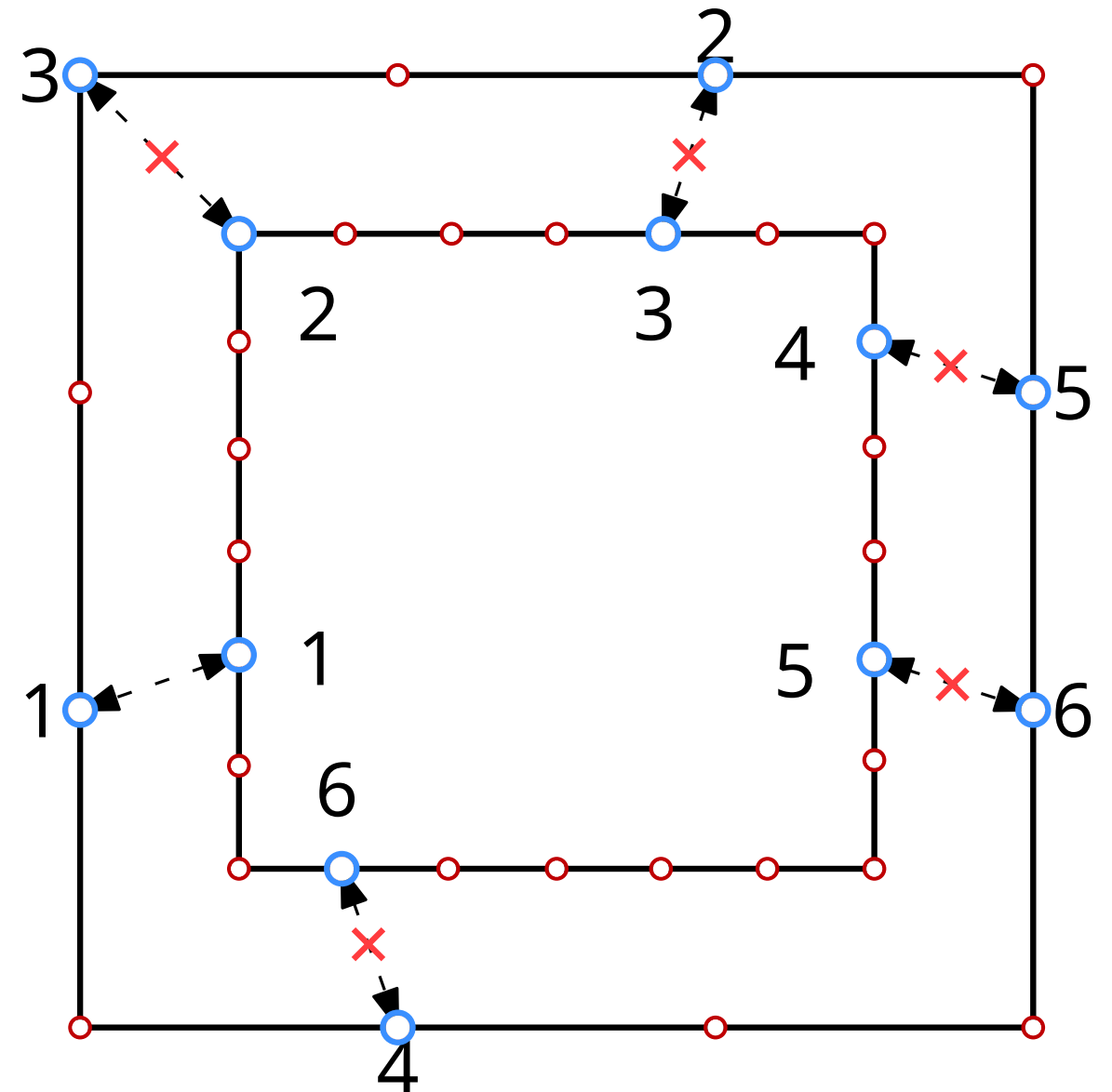
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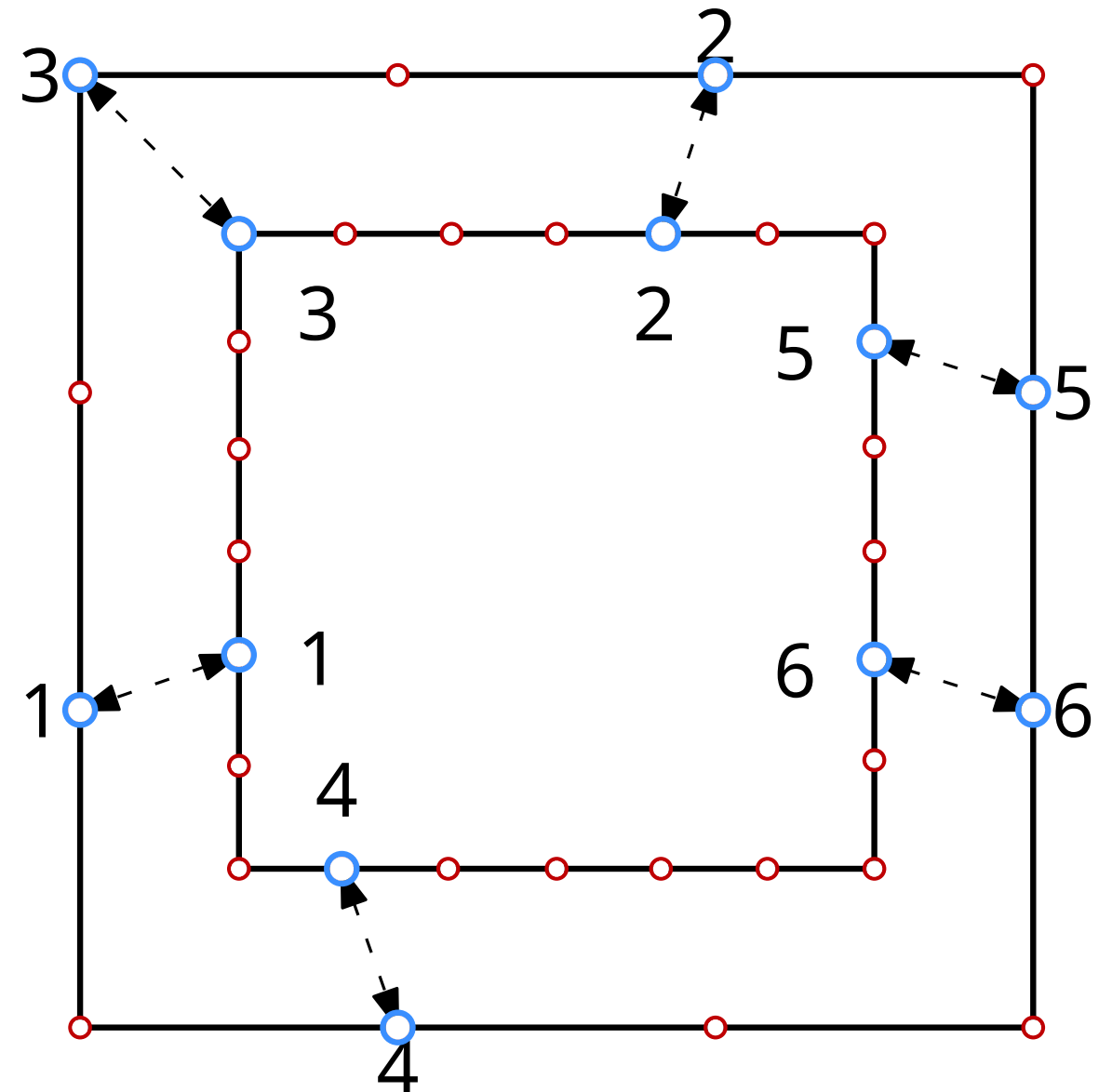
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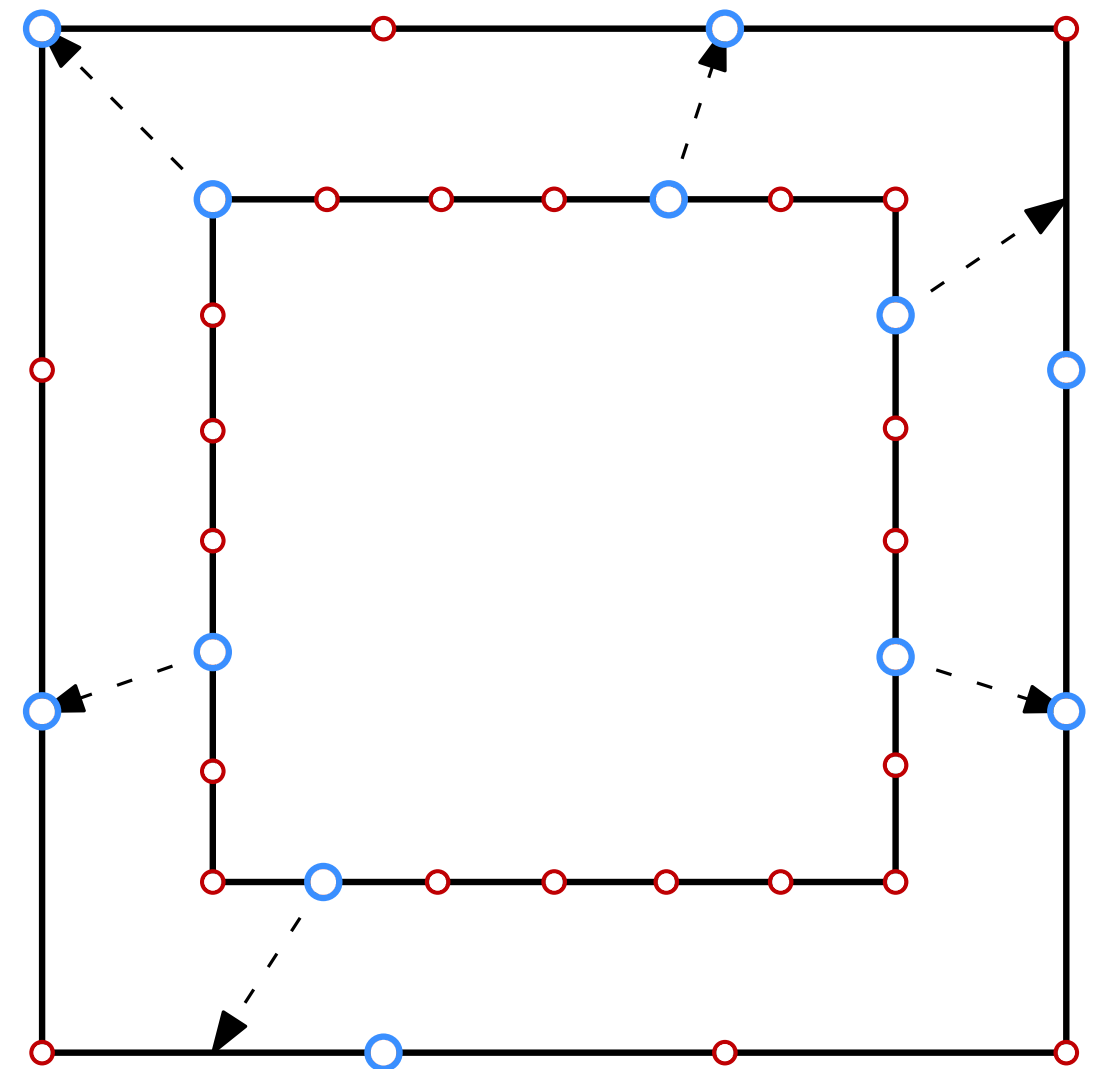
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5. $\text{cost} \leftarrow \text{ParentConnect}(C, S, M) + \sum_{i=1}^4 \text{Recursive}(C_i)$

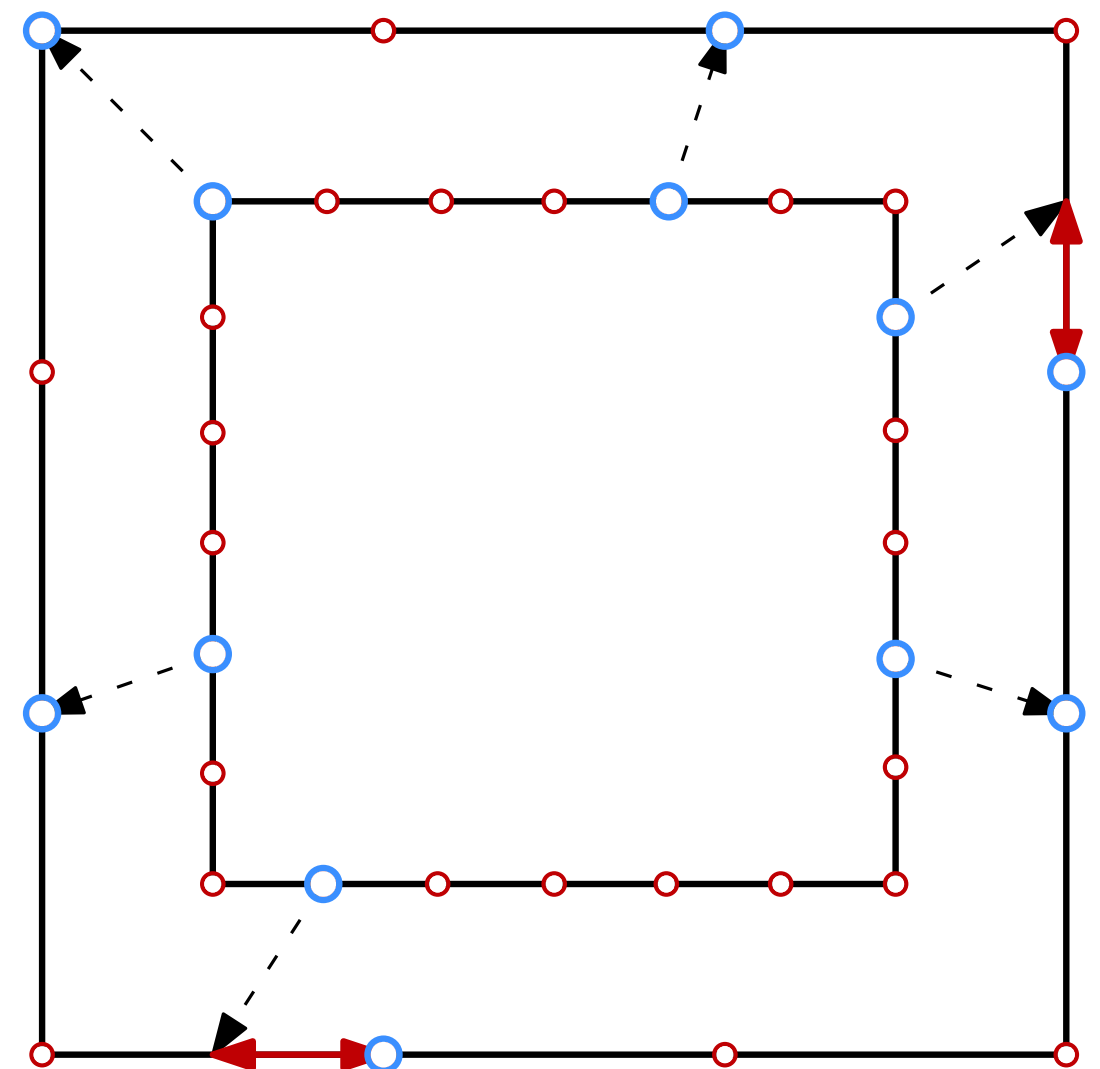
C_i is an arbitrary subproblem for child i

C contains one subproblem for each child

Valid: even number of portals per child. Portals between children match and number of portals on outside match with parent portals.

Outside portals have same order as parent

ParentConnect(C, S, M): total misalignment between parent and child portals



Algorithm

Initialization(Q):

Construct quadtree \mathcal{T} over Q with height H

Let $k = \frac{90}{\varepsilon} = \mathcal{O}(\frac{1}{\varepsilon})$, $m \geq \frac{20H}{\varepsilon} = \mathcal{O}(\varepsilon^{-1} \log n)$

Recursive(S, M):

1. **if** $|Q_S| = \mathcal{O}(\frac{1}{\varepsilon})$ **then return** BruteForce(S, M)
2. $\min_{\text{length}} \leftarrow \infty$
3. **for each** combination $C = [C_1, C_2, C_3, C_4]$ of subproblems of children at S :
4. **if** C is valid **then**:
5. $\text{cost} \leftarrow \text{ParentConnect}(C, S, M) + \sum_{i=1}^4 \text{Recursive}(C_i)$
6. $\min_{\text{length}} \leftarrow \min(\min_{\text{length}}, \text{cost})$
7. **return** \min_{length}

Use memoization to make it a DP algorithm

Overview

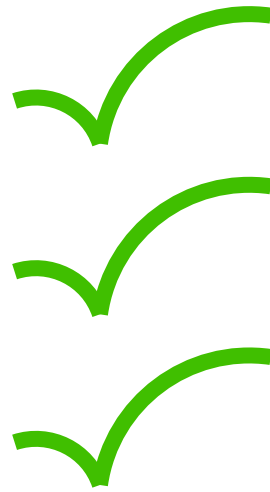
1. Intuition

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3. Algorithm

4. Running time

5. Quality of approximation

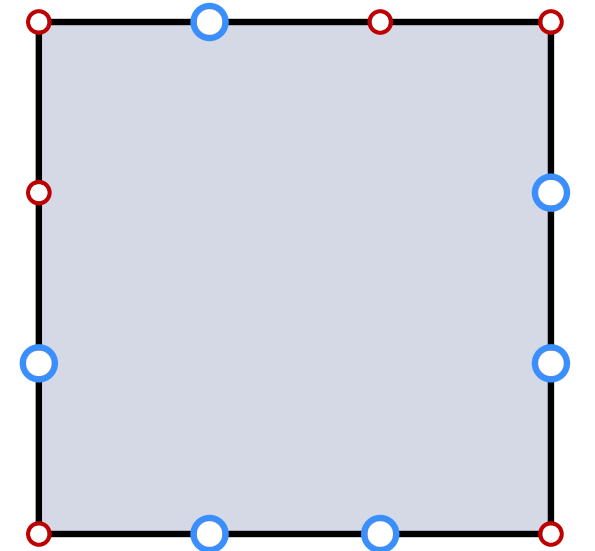


Running Time - Number of Subproblems per Square

Consider a square S and its portals

It has $4m + 4$ portals on its boundary, each of which is used at most twice

At most k portals are used on each side of S



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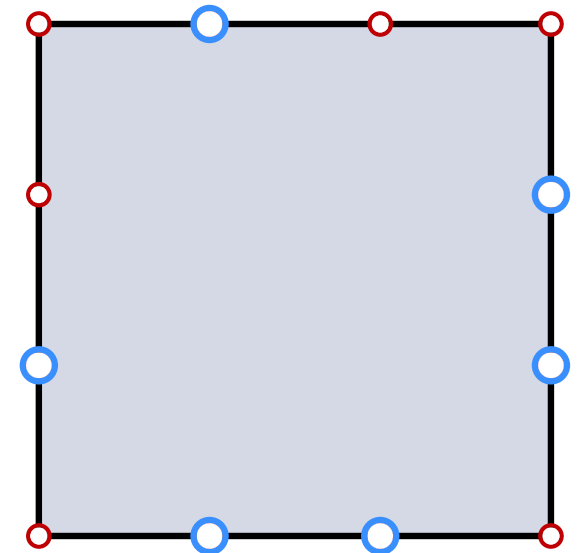
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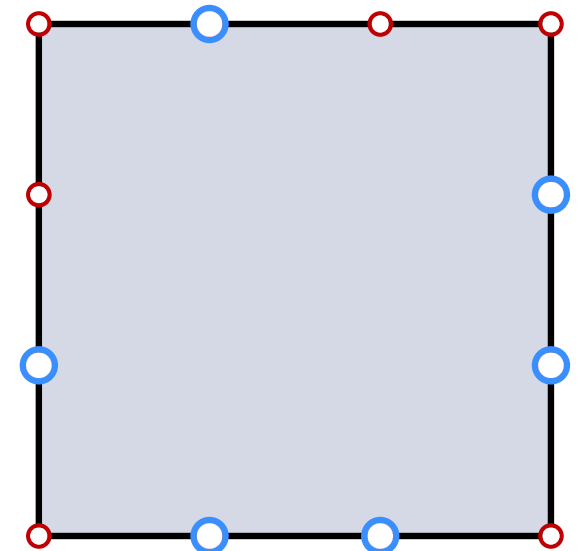
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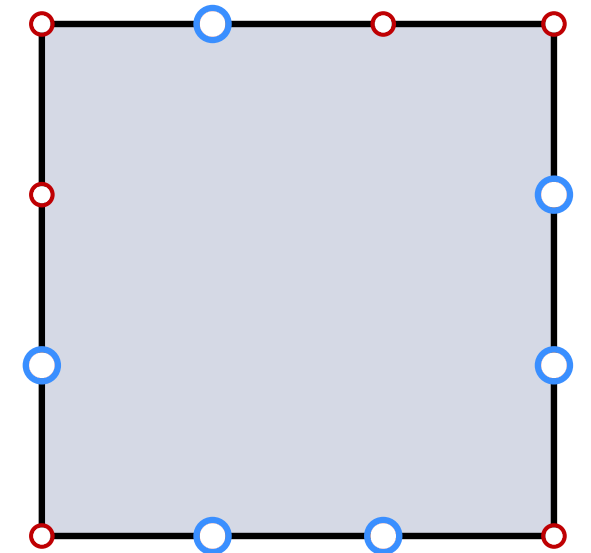
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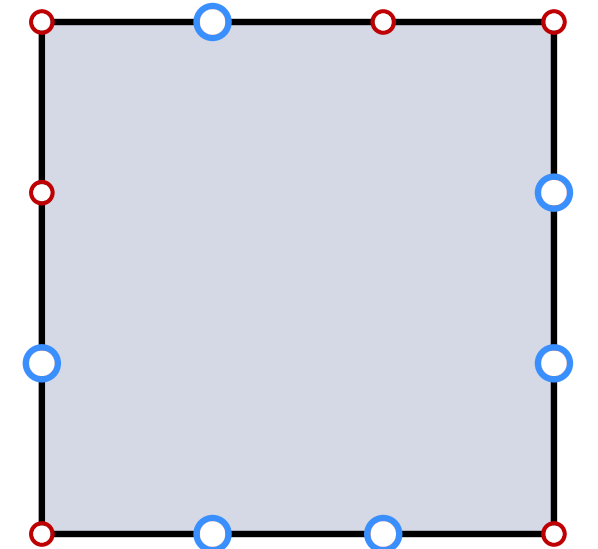
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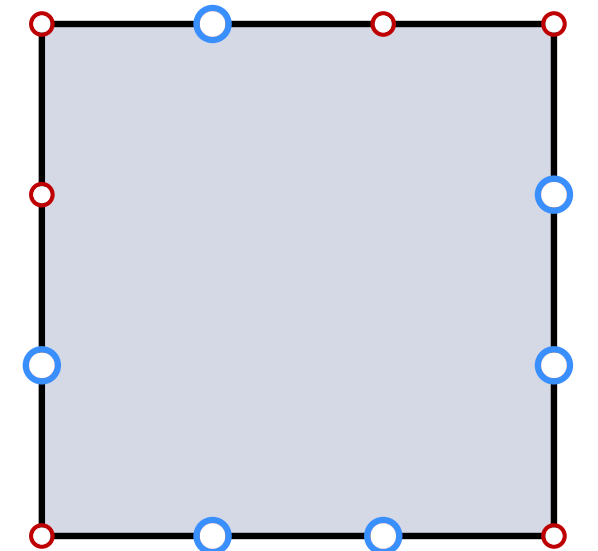
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Recall

$$k = \mathcal{O}\left(\frac{1}{\varepsilon}\right)$$

$$m = \mathcal{O}\left(\frac{\log n}{\varepsilon}\right)$$

Running Time

Recall: quadtree had $\mathcal{O}(n \log n)$ nodes and one square per node

Claim: brute force on a square with $\mathcal{O}\left(\frac{1}{\varepsilon}\right)$ points (base case) can

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Algorithm considers all combinations of subproblems for the squares of the children for each node

The number of subproblems per child is at most T

The number of combinations for four children is T^4

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Total running time:

$$\mathcal{O}(n \log n + (n \log n)T^5) = \mathcal{O}((n \log n)T^5) = n(\varepsilon^{-1} \log n)^{\mathcal{O}(1/\varepsilon)}$$

Overview

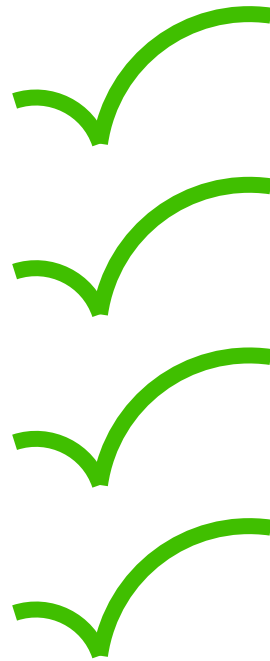
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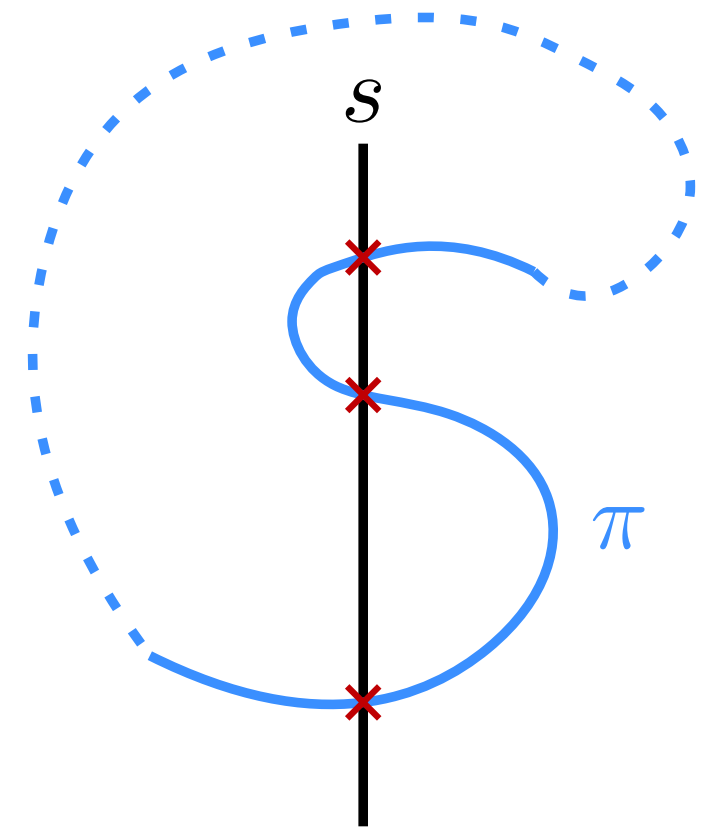
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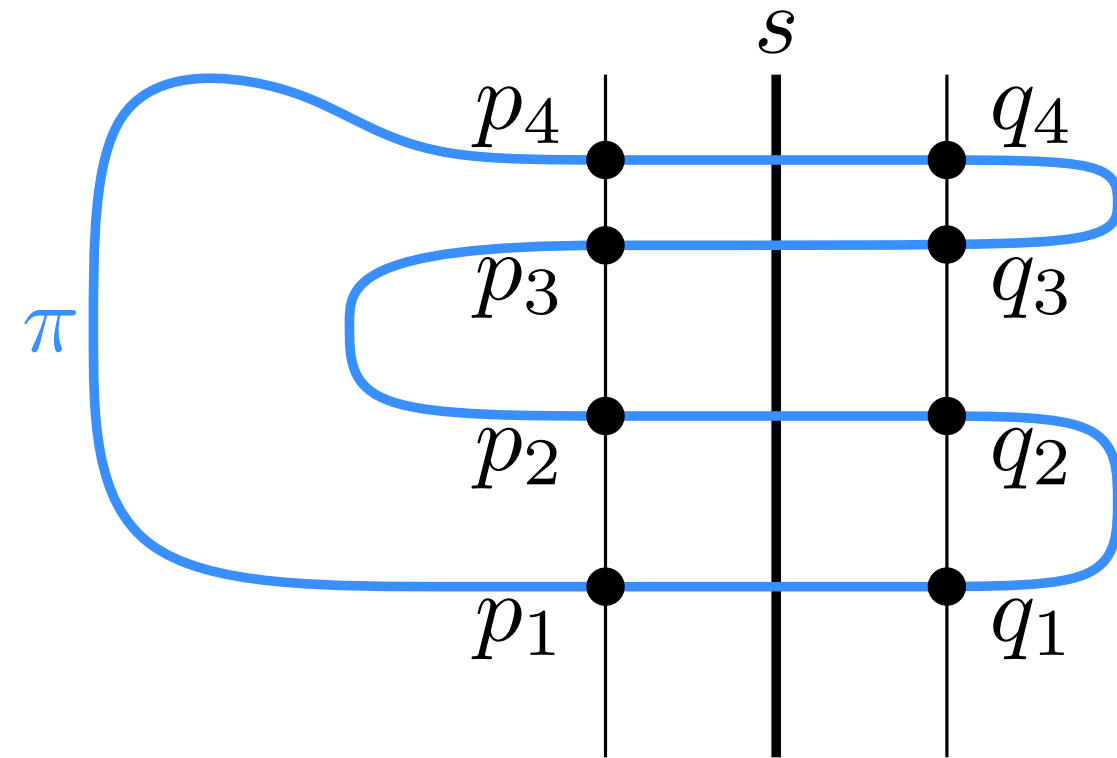
Patching Lemma

Patching lemma: closed curve π crossing segment s at least $k \geq 3$ times can be replaced by closed curve π' crossing s at most twice such that $||\pi'|| \leq ||\pi|| + 4||s||$



Patching Lemma

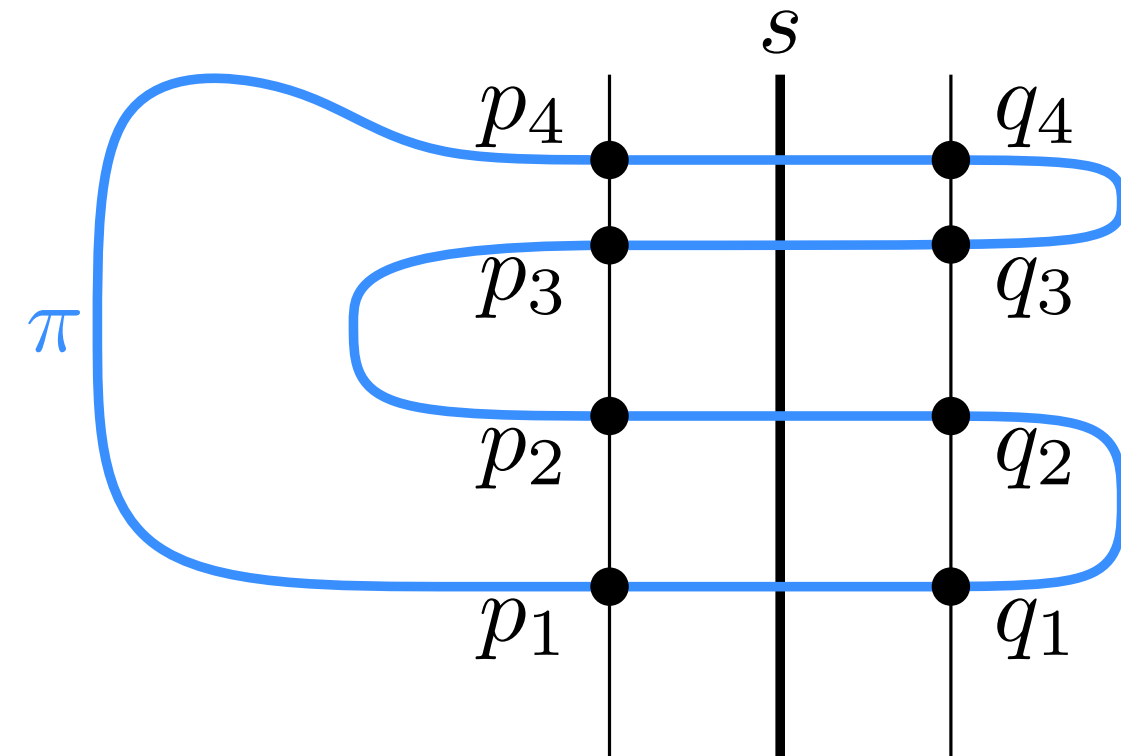
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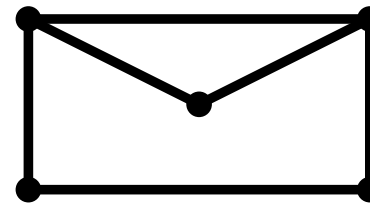
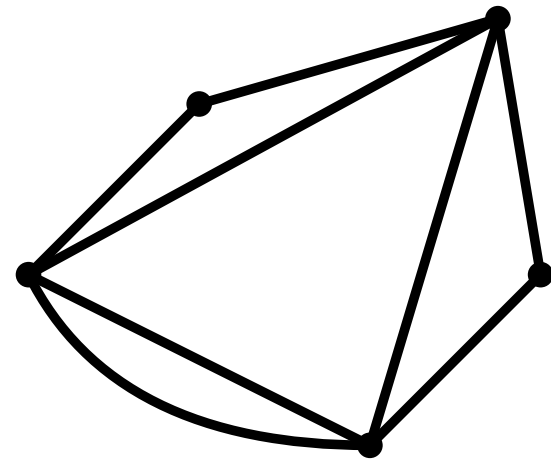
Idea: construct an Eulerian tour including π that crosses s at most twice



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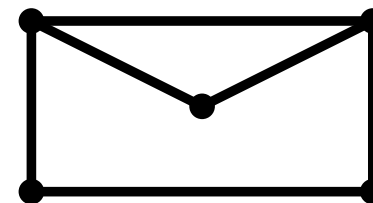
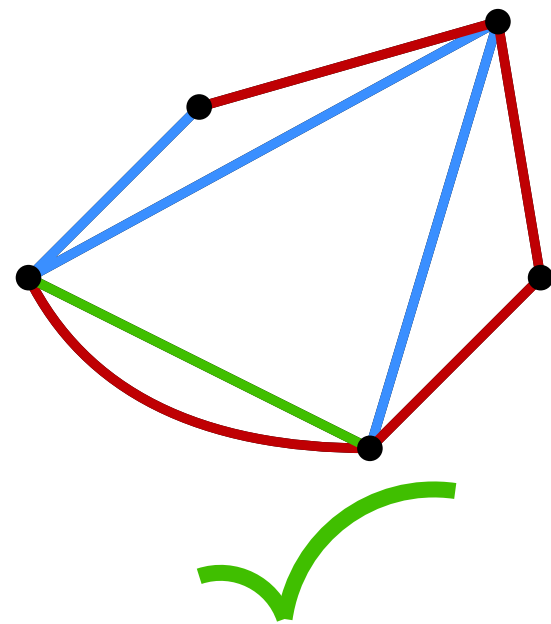
Theorem: a connected graph admits an Eulerian tour if and only if its vertices have even degree



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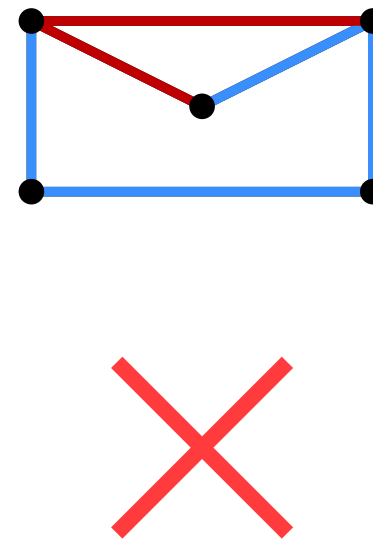
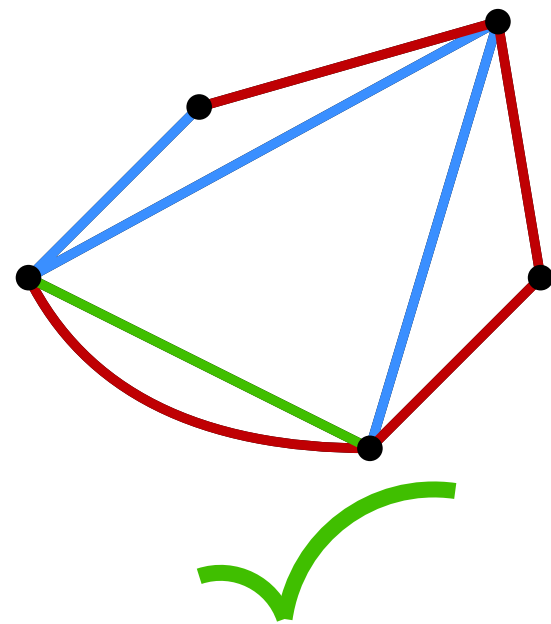
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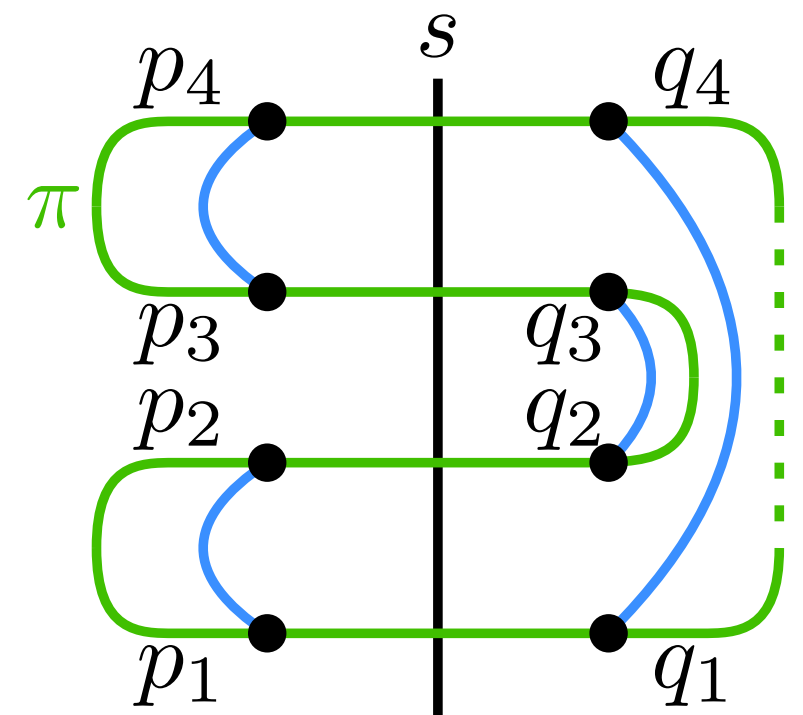


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Let E_π be the set of edges each representing a connected component of $\pi \setminus s$



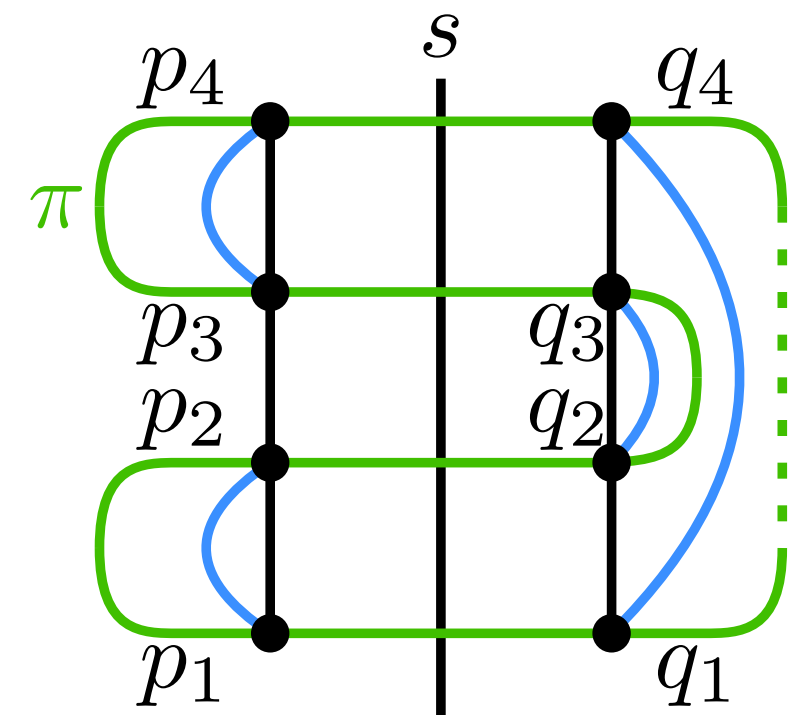
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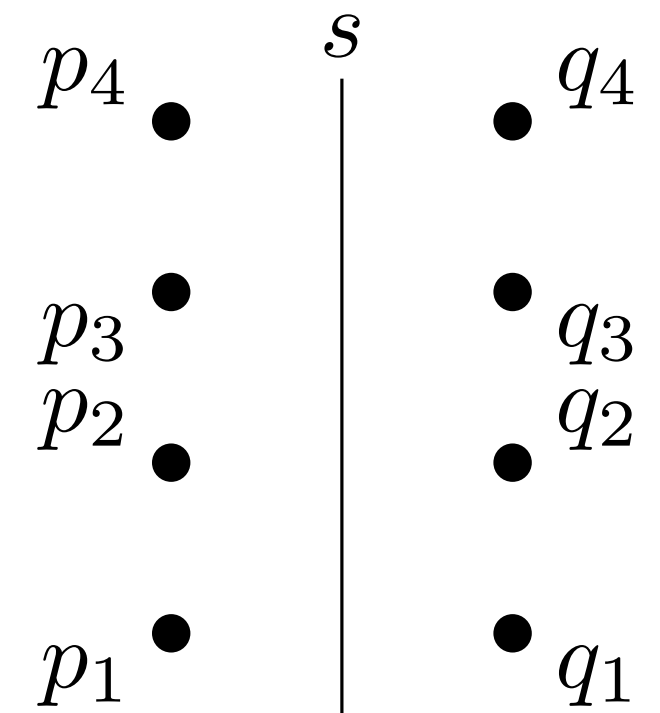
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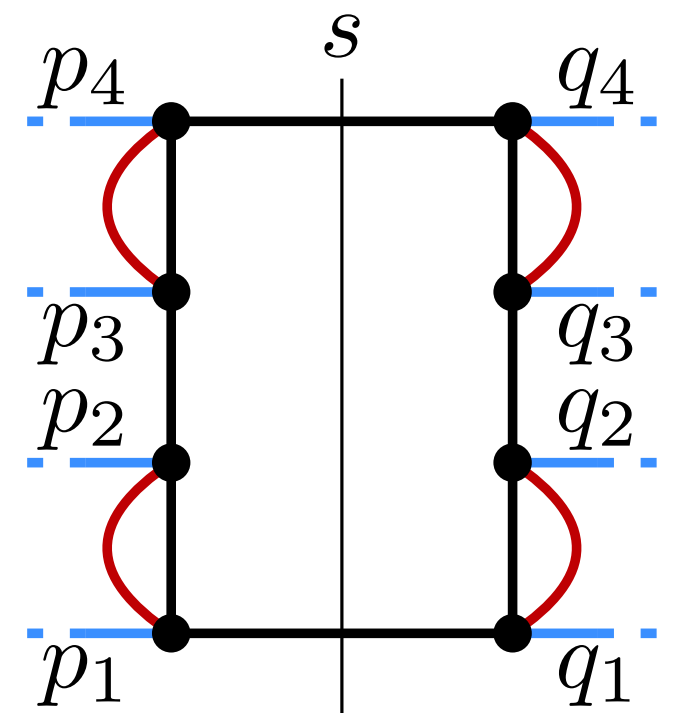
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$E = \bigcup_{i=1}^{k-1} \{s_i, s'_i\} \cup E_\pi \cup \bigcup_{i=1}^{k-1} (\text{odd}) \{s_i, s'_i\} \cup \{(p_1, q_1)\}$

and also add (p_k, q_k) if k is even



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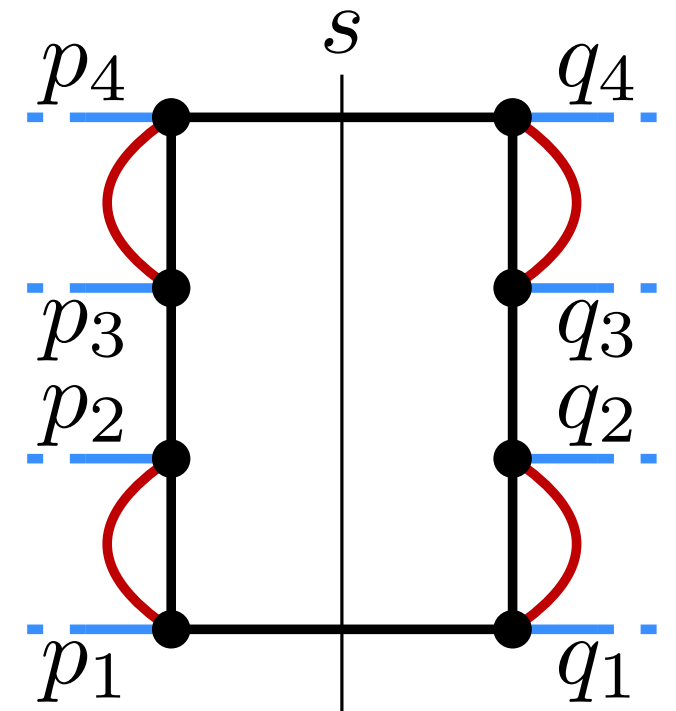
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G is connected and its vertices have even degree

Hence it admits an Eulerian tour π'

π' visits all of π outside of s as $E_\pi \subseteq E$

π' crosses s at most twice: at (p_1, q_1) and (p_k, q_k)



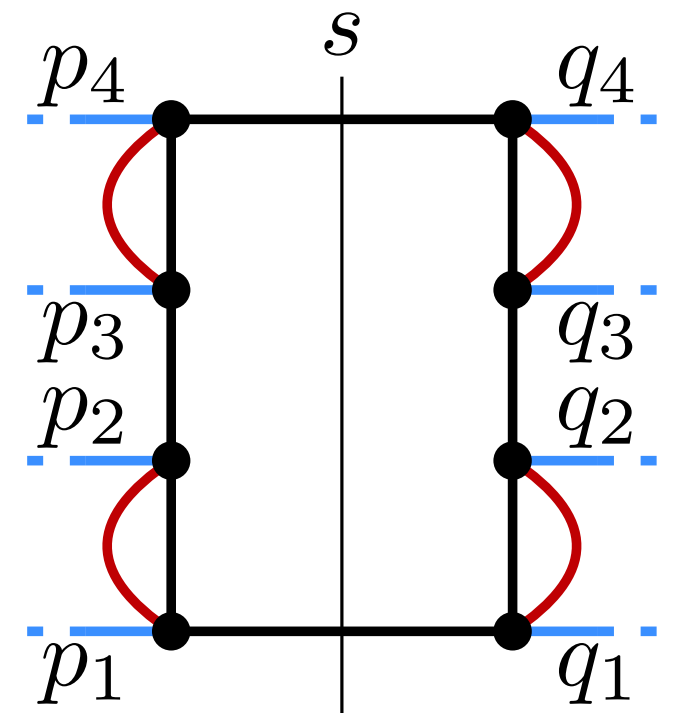
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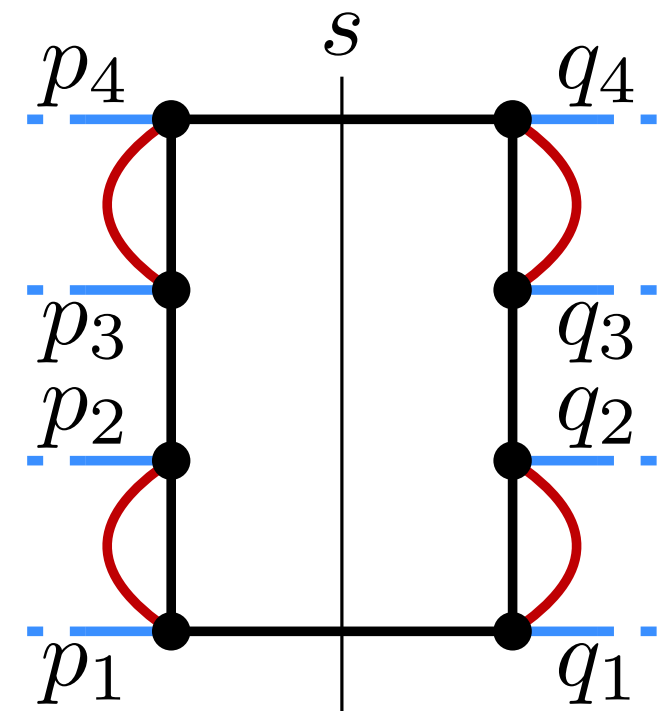
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$||\pi'||$ is the length of all edges in E

$$||\pi'|| \leq ||\pi|| + 2||s|| + 2||s|| = ||\pi|| + 4||s||$$



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Using only k portals of a square

bottom-up (i.e. starting with small cells): When $> k$ intersections, patch!

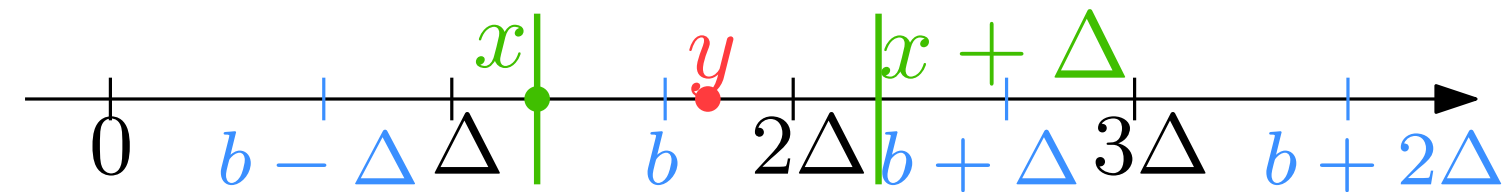
intuition: patching on low levels: relatively cheap, and also helps higher levels

+ fewer (exponentially decreasing) intersections at higher levels: shifting

Shifted Grids

recall: shifted partition of real line

Let $\Delta > 0$ and $b \in [0, \Delta]$ uniformly distributed. We shift the grid G_Δ by b



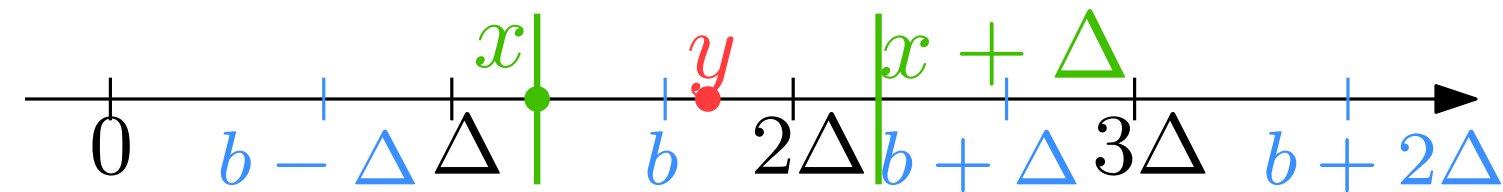
$$h_{b,\Delta}(x) = \lfloor \frac{x-b}{\Delta} \rfloor$$

Lemma: For $x, y \in \mathbb{R}$ holds $\mathbb{P}[h_{b,\Delta}(x) \neq h_{b,\Delta}(y)] = \min\left(\frac{|x-y|}{\Delta}, 1\right)$

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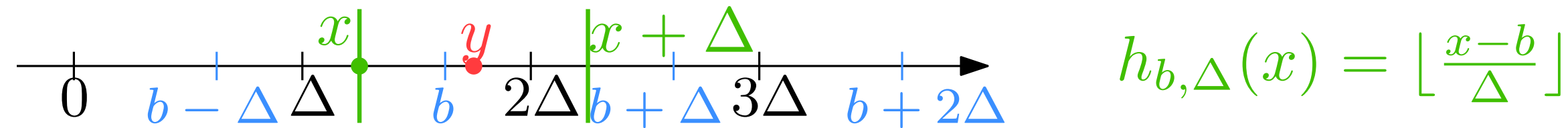
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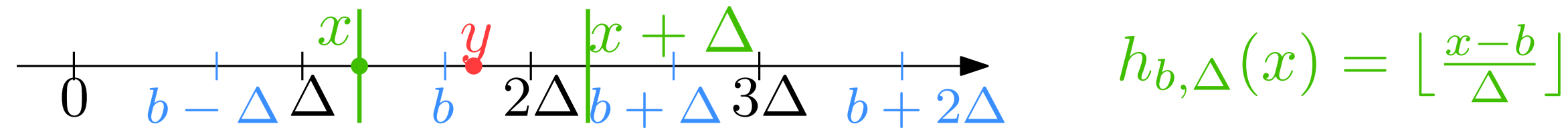
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Lemma: Let s be a segment in the plane, The probability that s intersects the shifted grid of side length Δ is at most $\sqrt{2} \|s\| / \Delta$.

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... generalizes to grids and quadtrees ...

Lemma: Let s be a segment in the plane, The probability that s intersects the shifted grid of side length Δ is at most $\sqrt{2}\|s\|/\Delta$.

Furthermore the expected number of intersection of s with vertical and horizontal lines of G_Δ is in the range $[\|s\|/\Delta, \sqrt{2}\|s\|/\Delta]$

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patching lemma + shifted grids $\rightarrow k$ portals per cell suffice

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add over H levels of quadtree

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Introduced error when:

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Introduced error when:

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uses: patching lemma (+ shifting) $1 + \frac{8}{k-2}$
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Recall: $k = \frac{90}{\varepsilon}$ and $m \geq \frac{20H}{\varepsilon}$

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uses: shifting

Recall: $k = \frac{90}{\varepsilon}$ and $m \geq \frac{20H}{\varepsilon}$

$$\begin{aligned} \left(1 + \frac{\varepsilon}{2}\right) \left(1 + \frac{8}{k-2}\right) \left(1 + \frac{2H}{m+1}\right) \|\pi_{\text{OPT}}\| &\leq \left(1 + \frac{\varepsilon}{2}\right) \left(1 + \frac{\varepsilon}{10}\right)^2 \|\pi_{\text{OPT}}\| \\ &\leq (1 + \varepsilon) \|\pi_{\text{OPT}}\| \end{aligned}$$

Summary

shifted **quadtree** with points snapped to grid

dynamic programming on quadtrees

running time: not too many subproblems, since subsquares only connect at few portals

correctness: patching lemma + shifting + snap to grid

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For a set P of n points in \mathbb{R}^2 and $\varepsilon > 0$, we can compute a tour π over P with expected length $(1 + \varepsilon) \|\pi_{\text{OPT}}\|$ in time $(\varepsilon^{-1} \log n)^{\mathcal{O}(1/\varepsilon)}$