

ε -sampling

range space

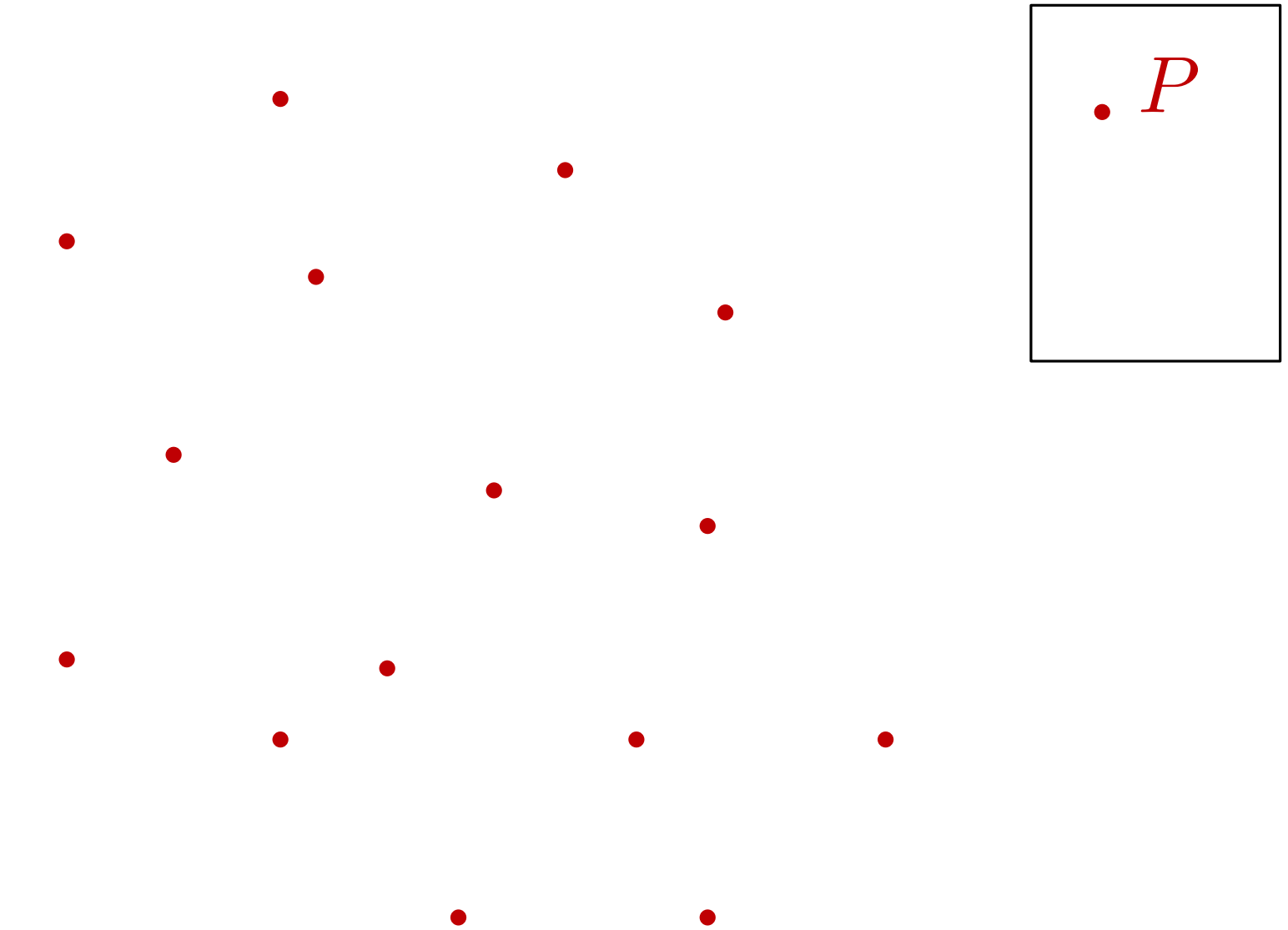
VC-dimension

ε -nets

ε -samples

Motivation: sampling for approximation

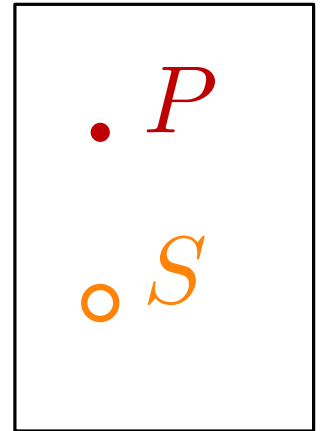
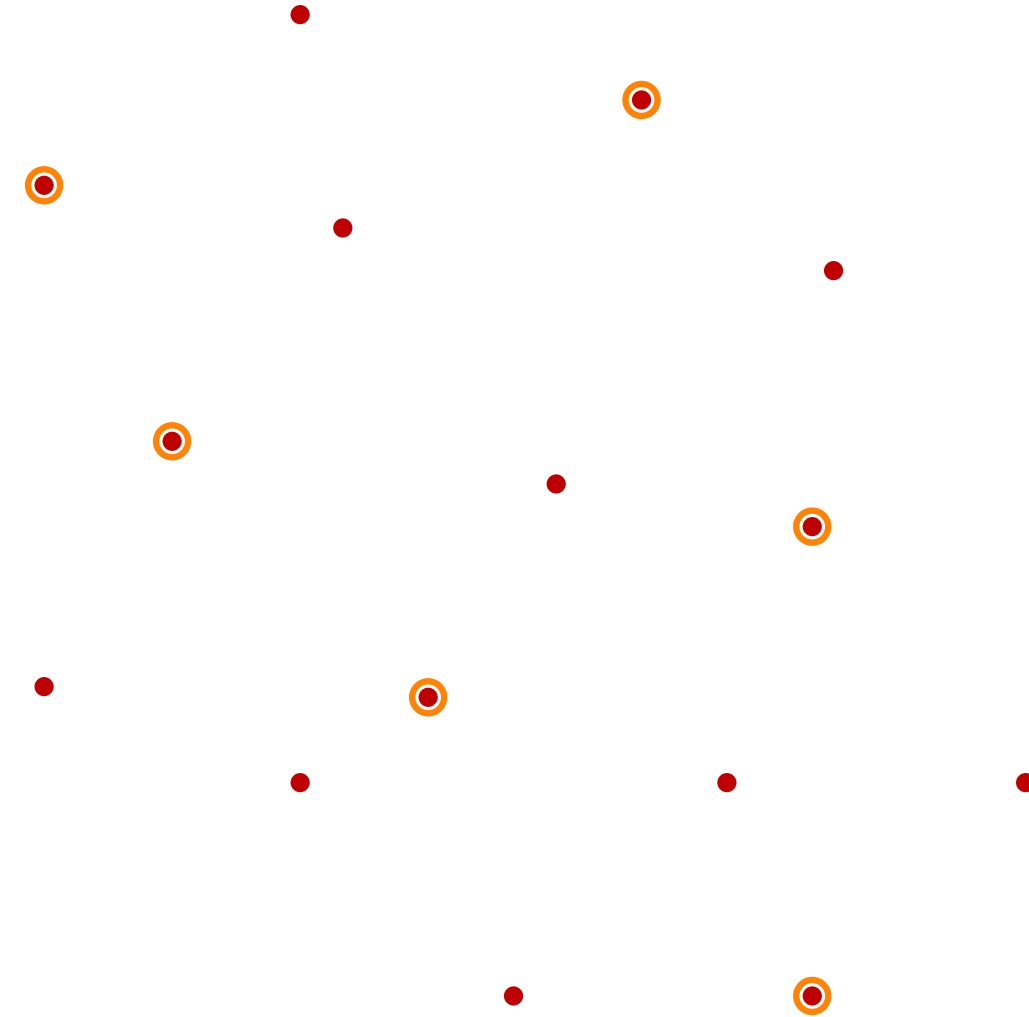
Given P ,



Motivation: sampling for approximation

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how many points do we need to sample
($S \subset P$), such that

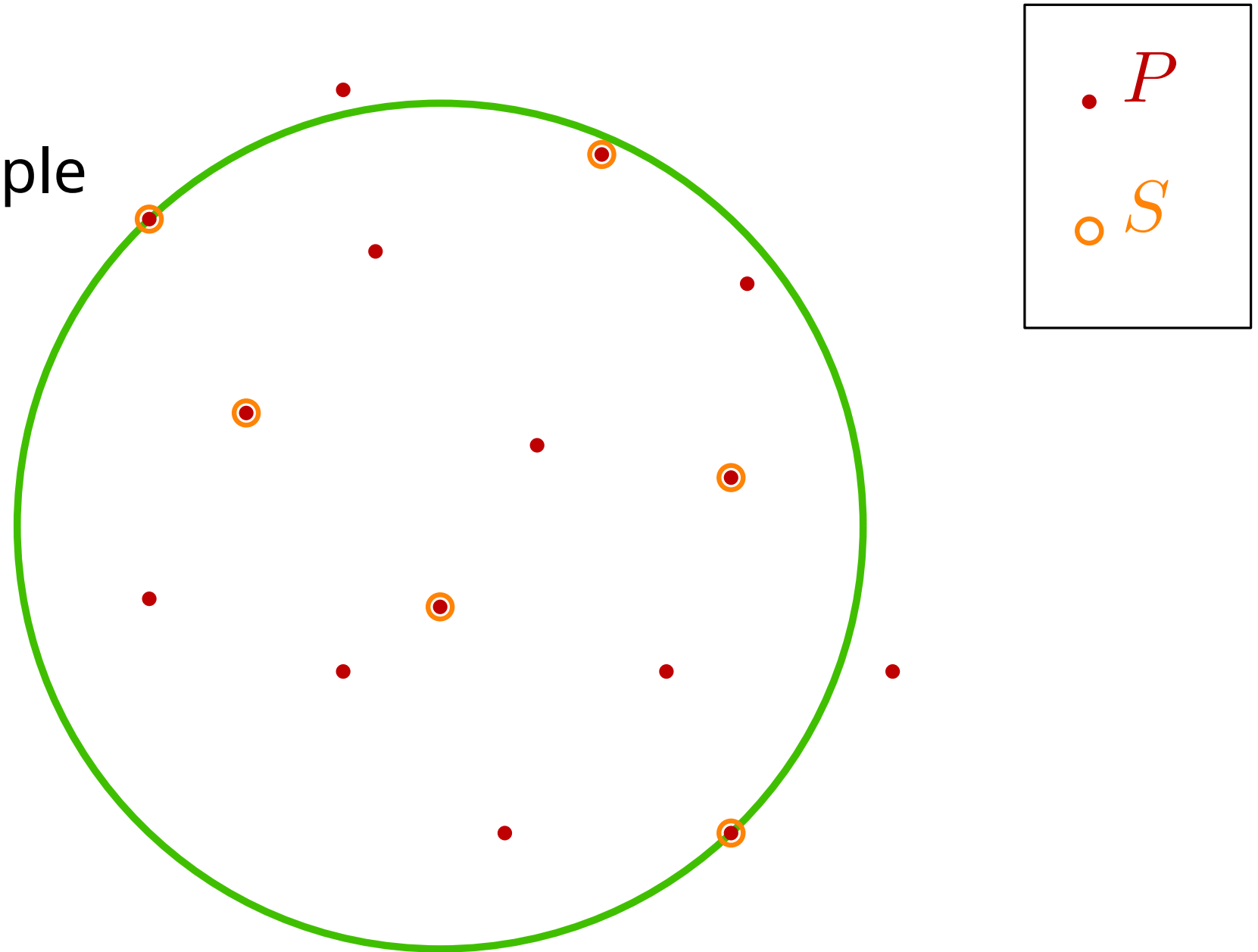


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1. the **smallest enclosing disk**
contains 90% of the points in P ?



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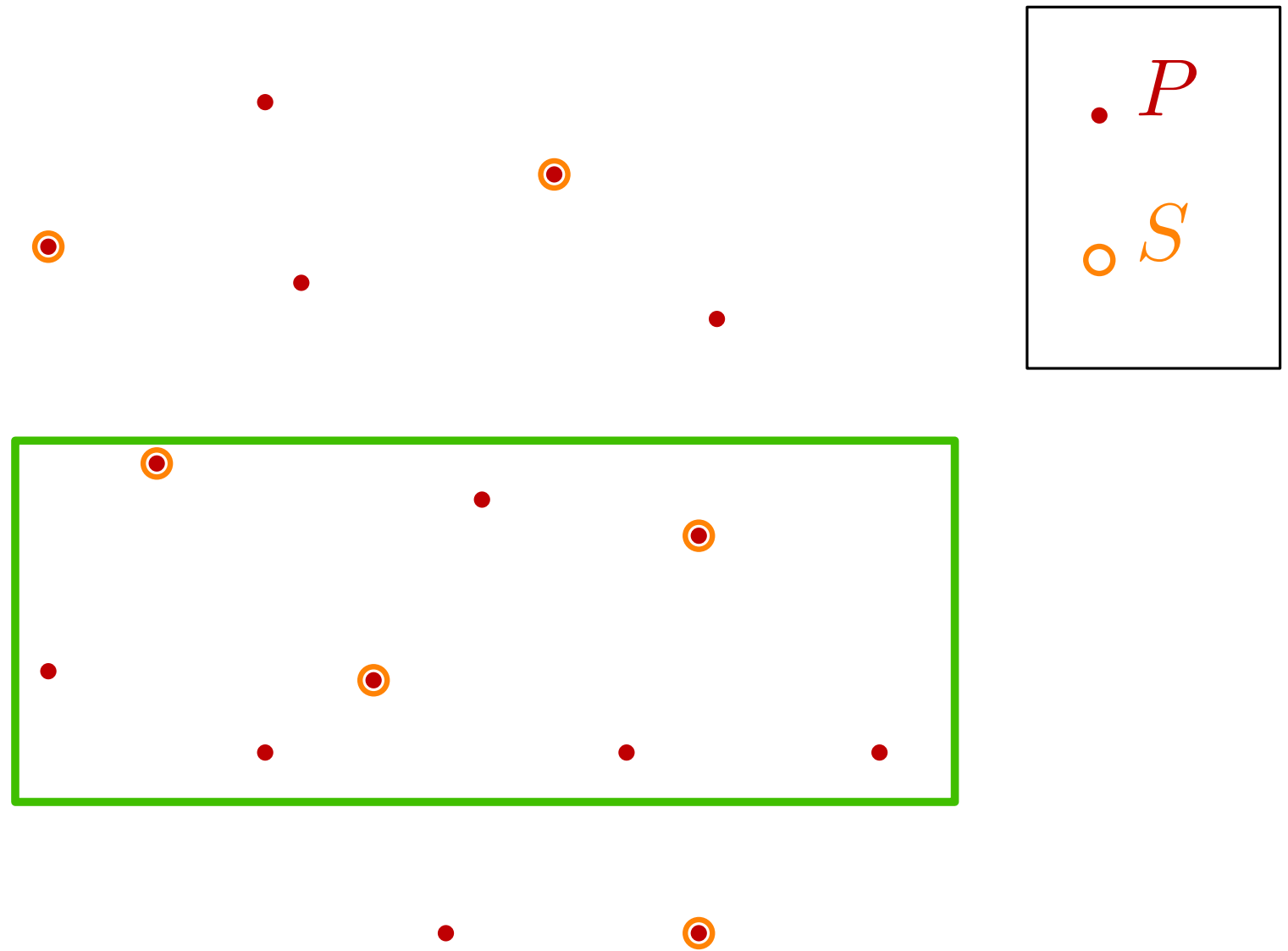
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2. for any **query rectangle** r

we can estimate the number of points of P in r ?



Motivation: sampling for approximation

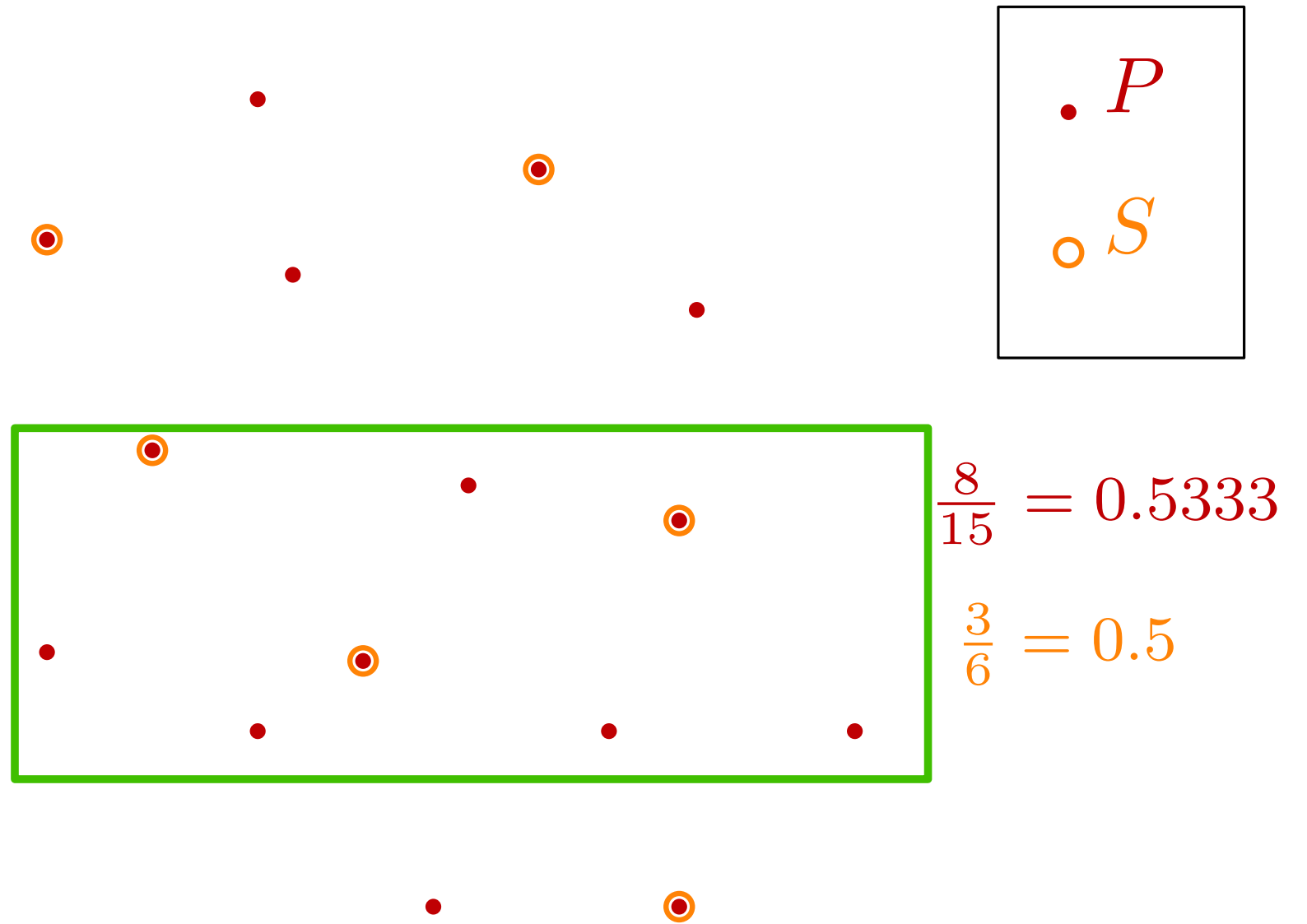
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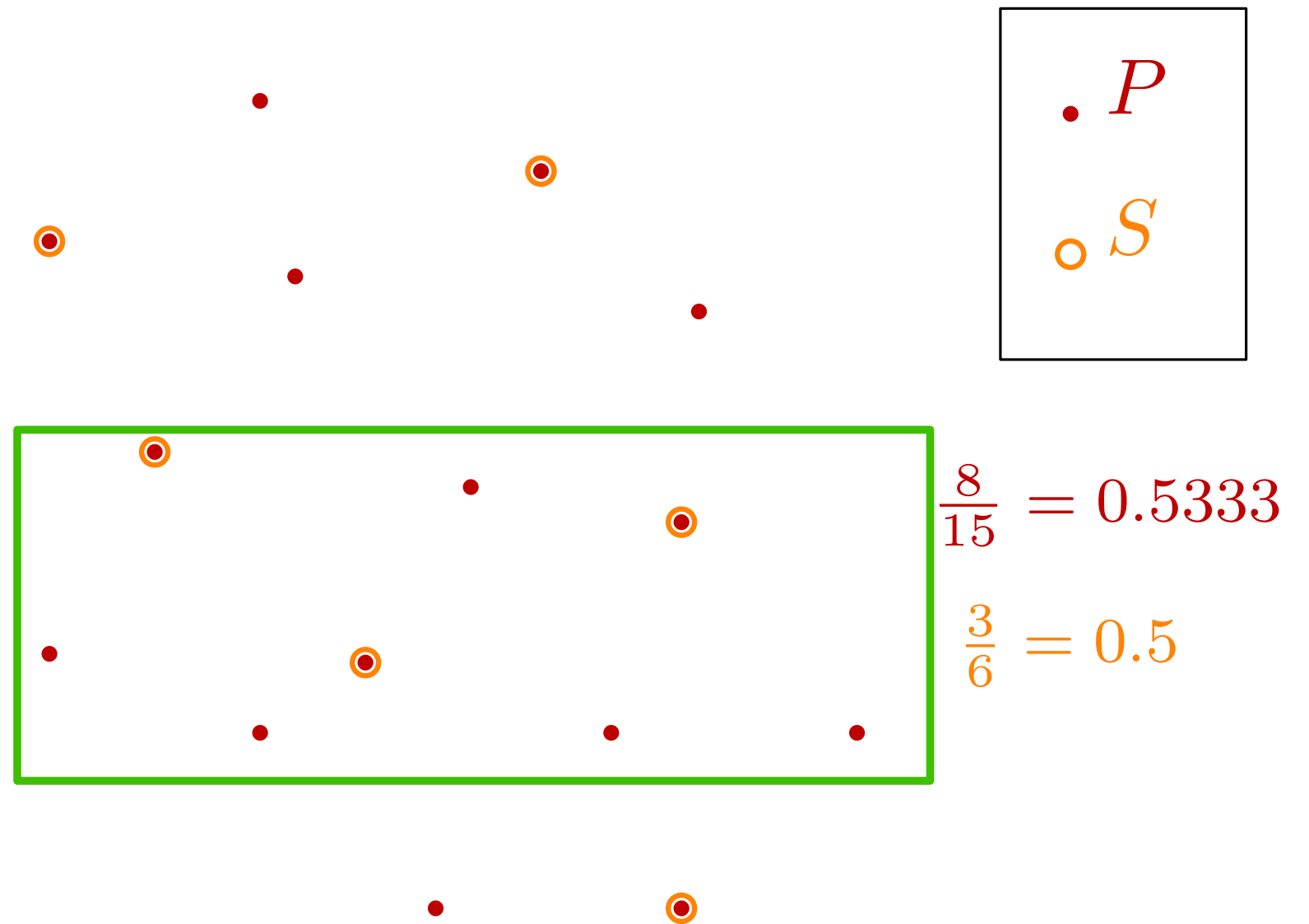
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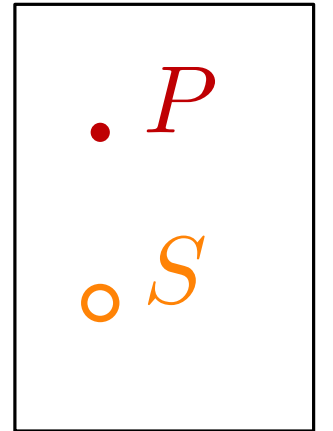
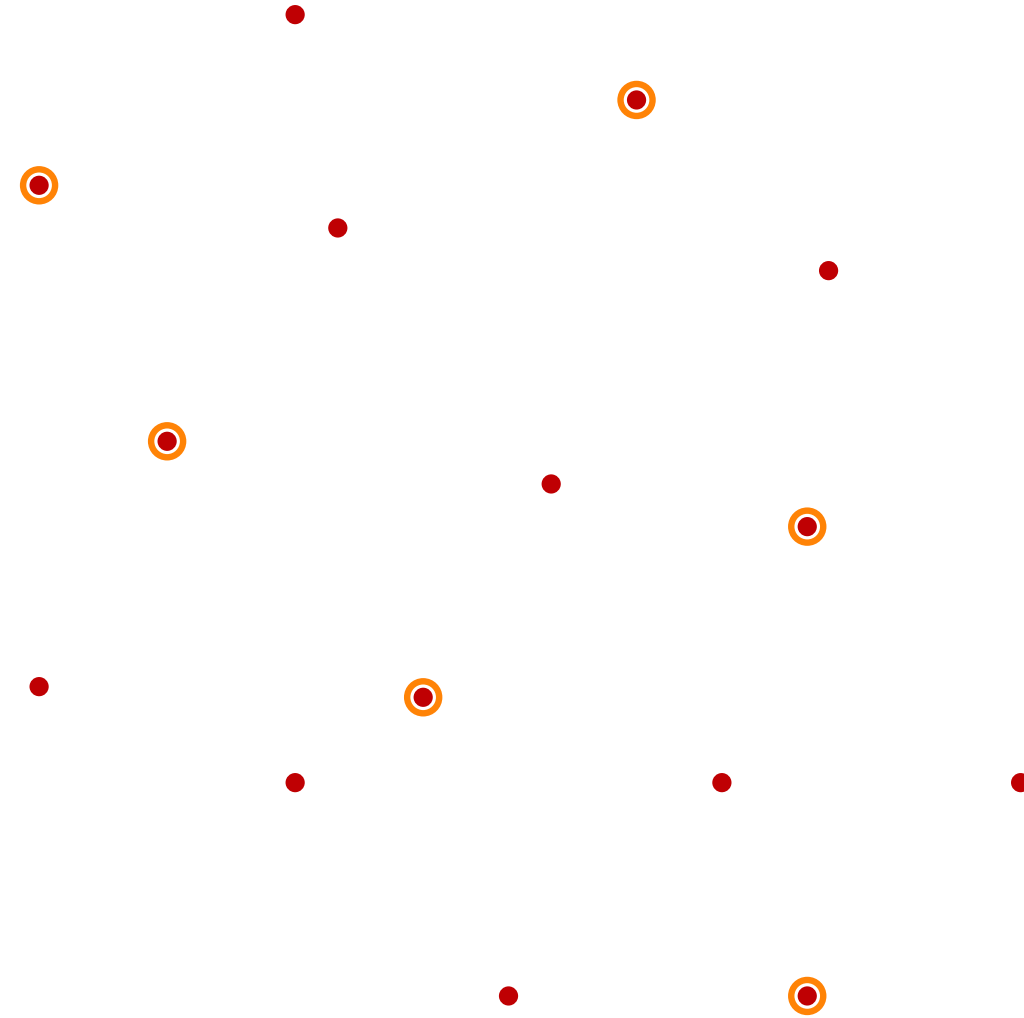
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with probability 0.999



Ranges matter

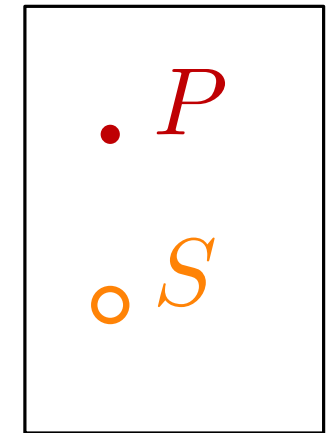
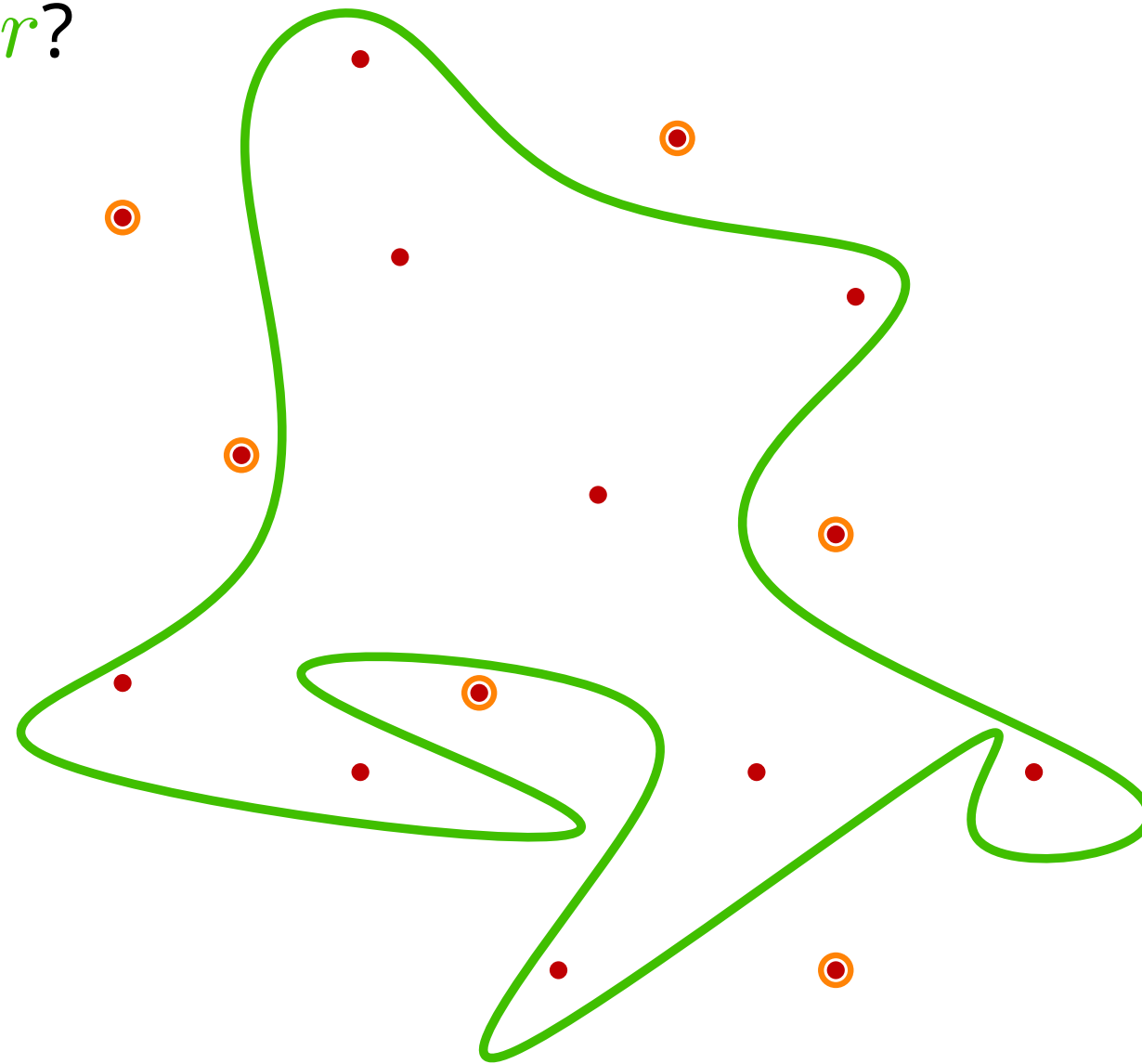
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(unless $S \approx P$)

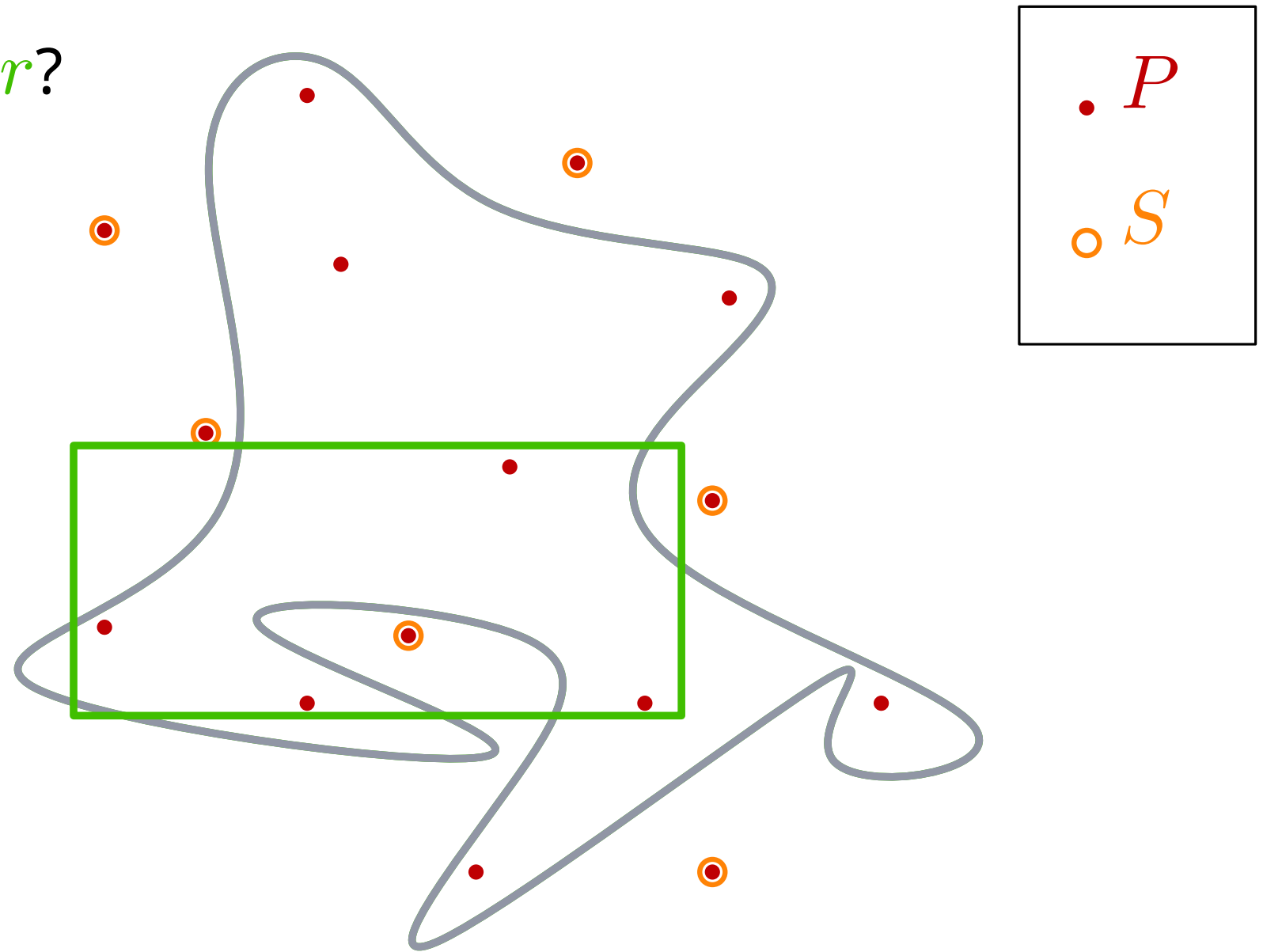


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Question: Why could this work for
(axis-aligned) rectangles?



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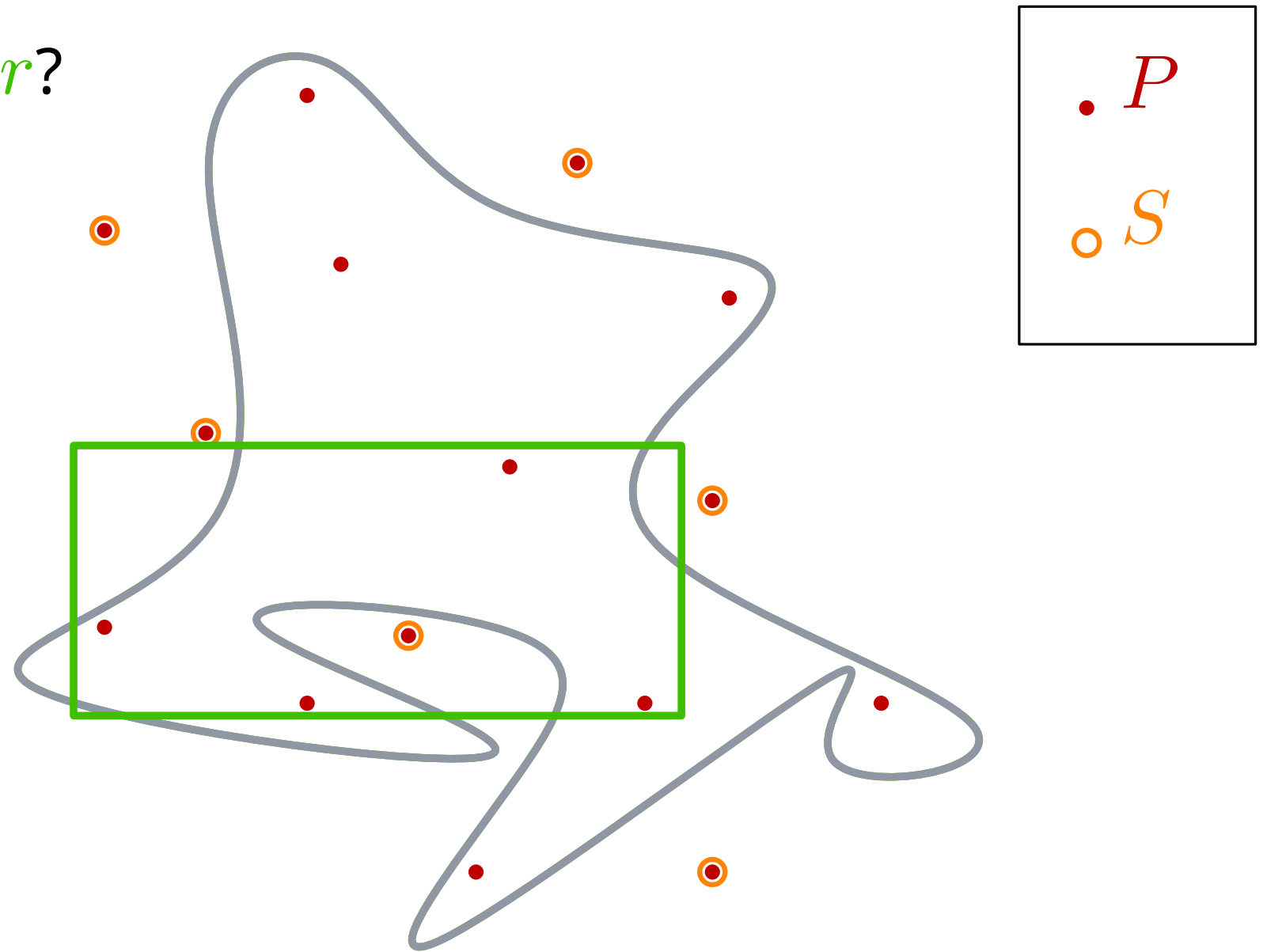
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- for 5 points: range with 4 points will contain inner point



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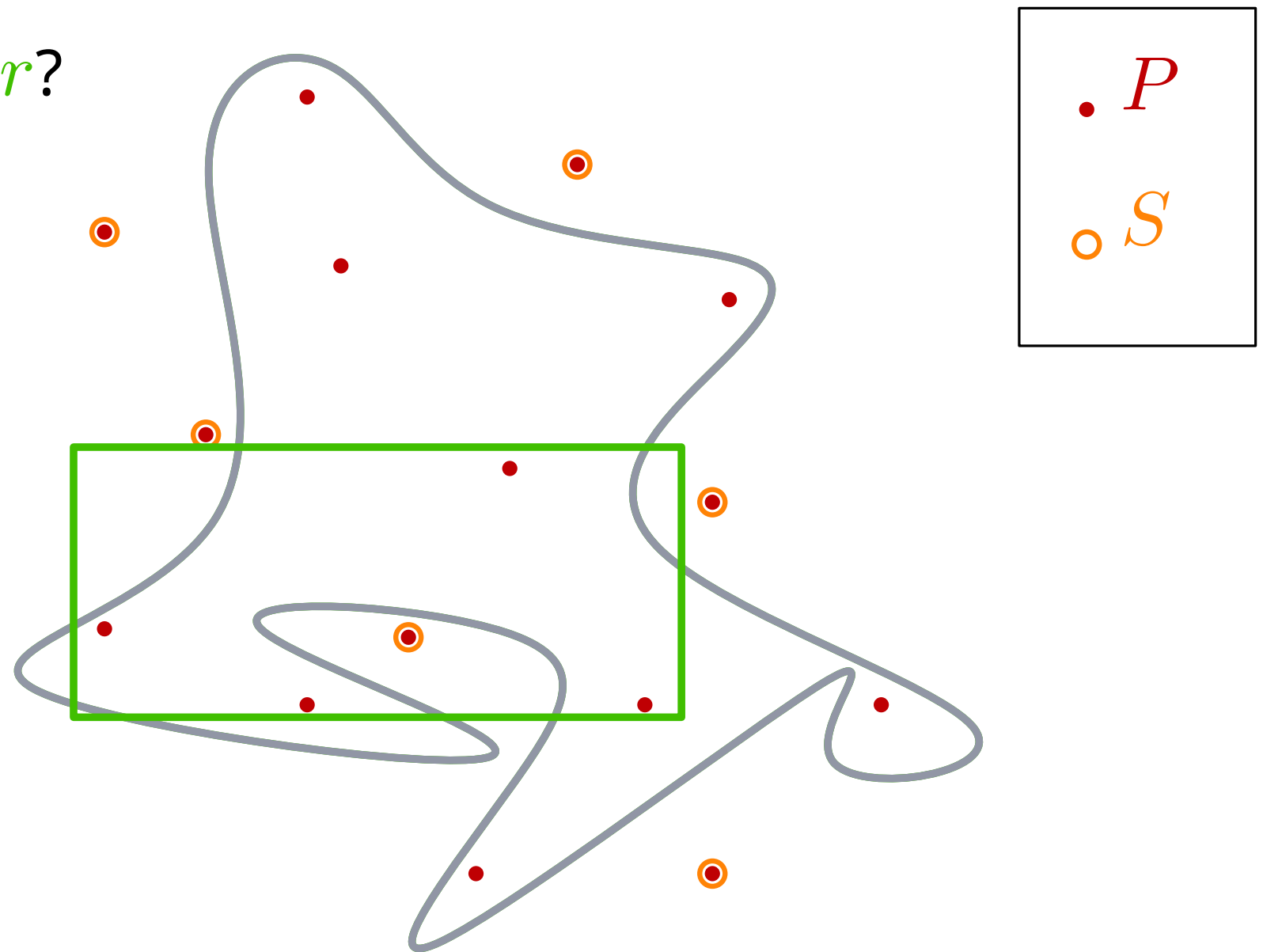
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Ideas:

- for 5 points: range with 4 points will contain inner point
- 2^n subsets of P by general ranges but much fewer by rectangles

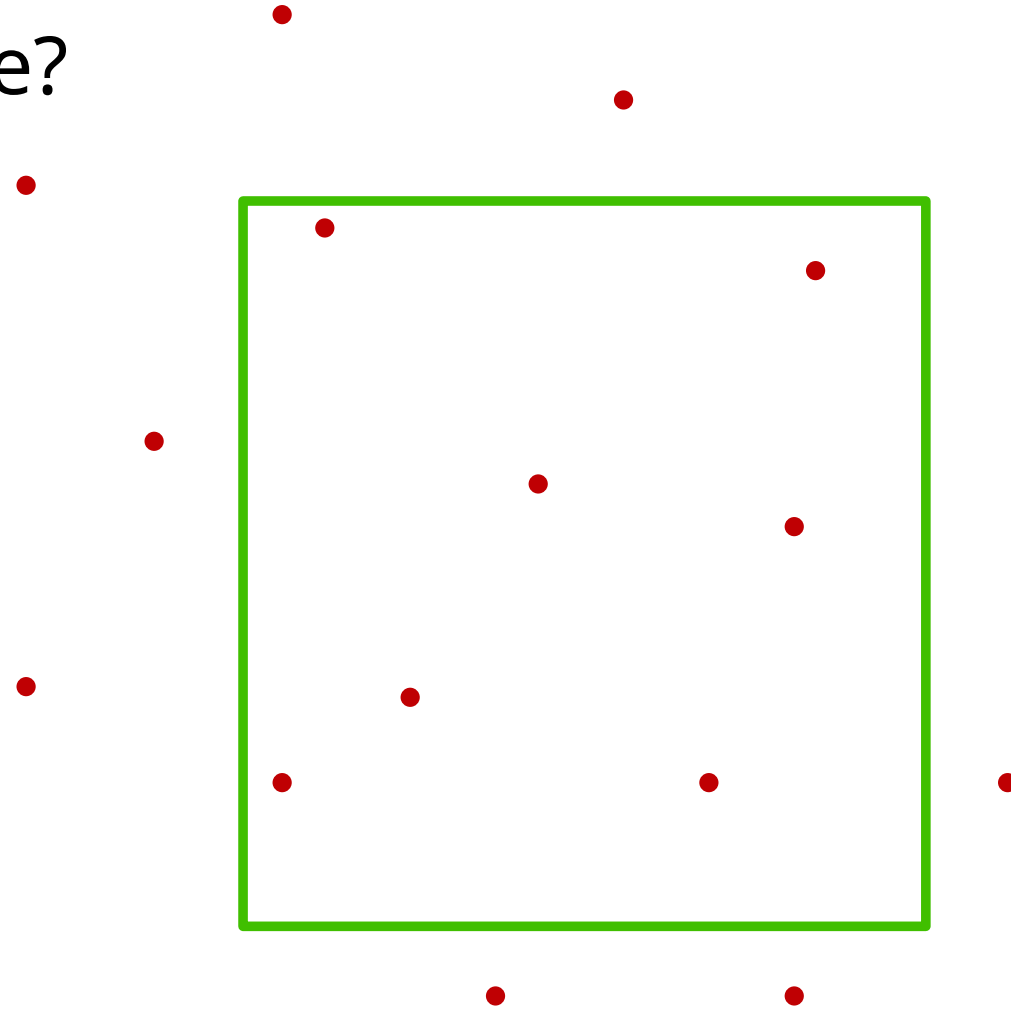


Quiz

Given point set P of size n and axis-aligned rectangles as ranges, how many sets $P \cap r$ are there?

- A $O(n^2)$
- B $O(n^3)$
- C $O(n^4)$

(we ask for a tight bound)



Quiz

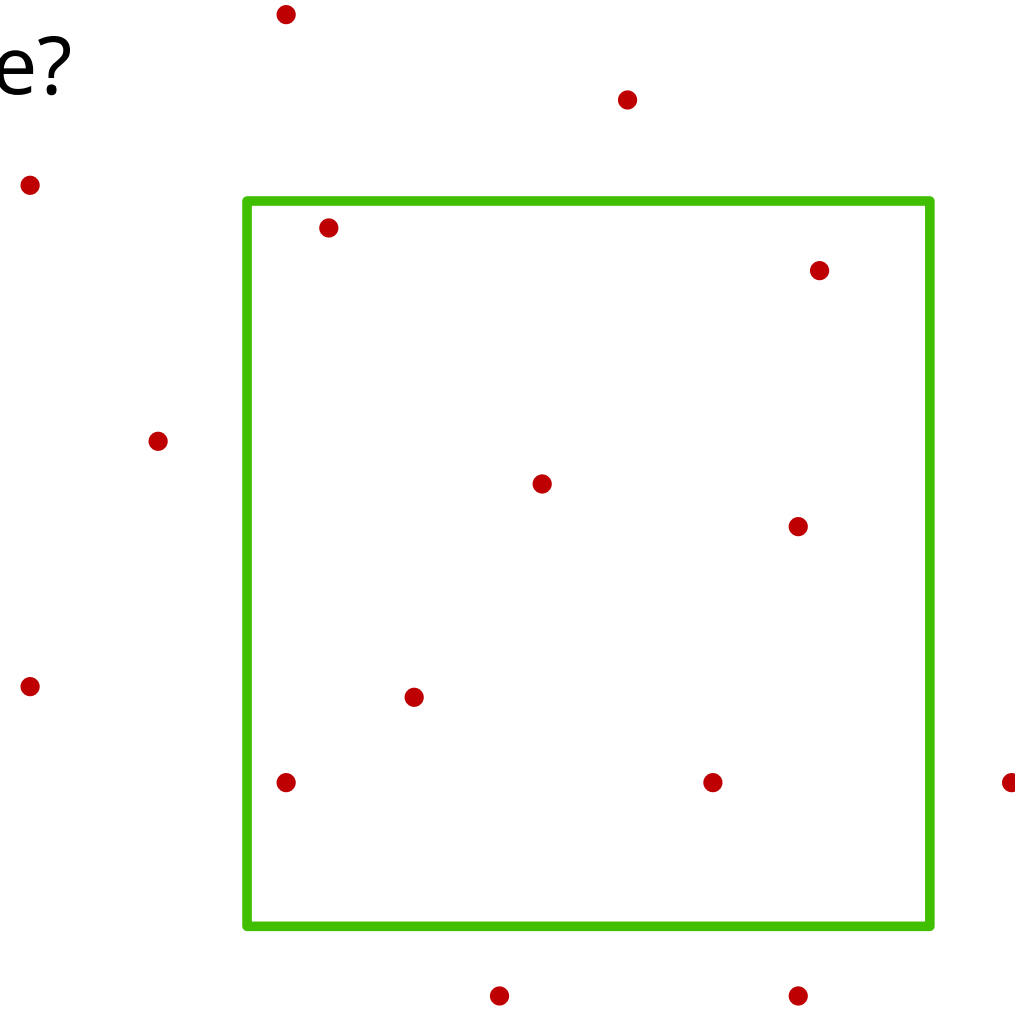
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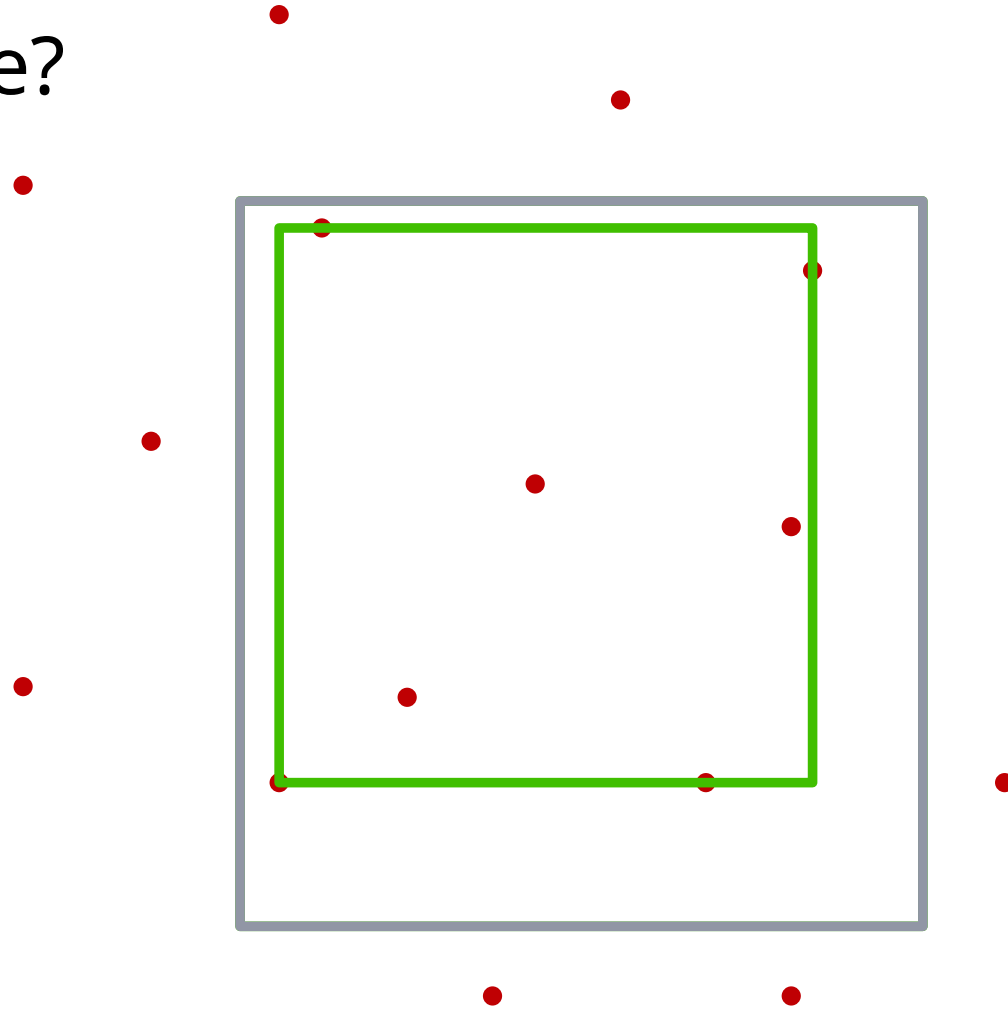
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each minimal rectangle defined by left, top, right, bottom point

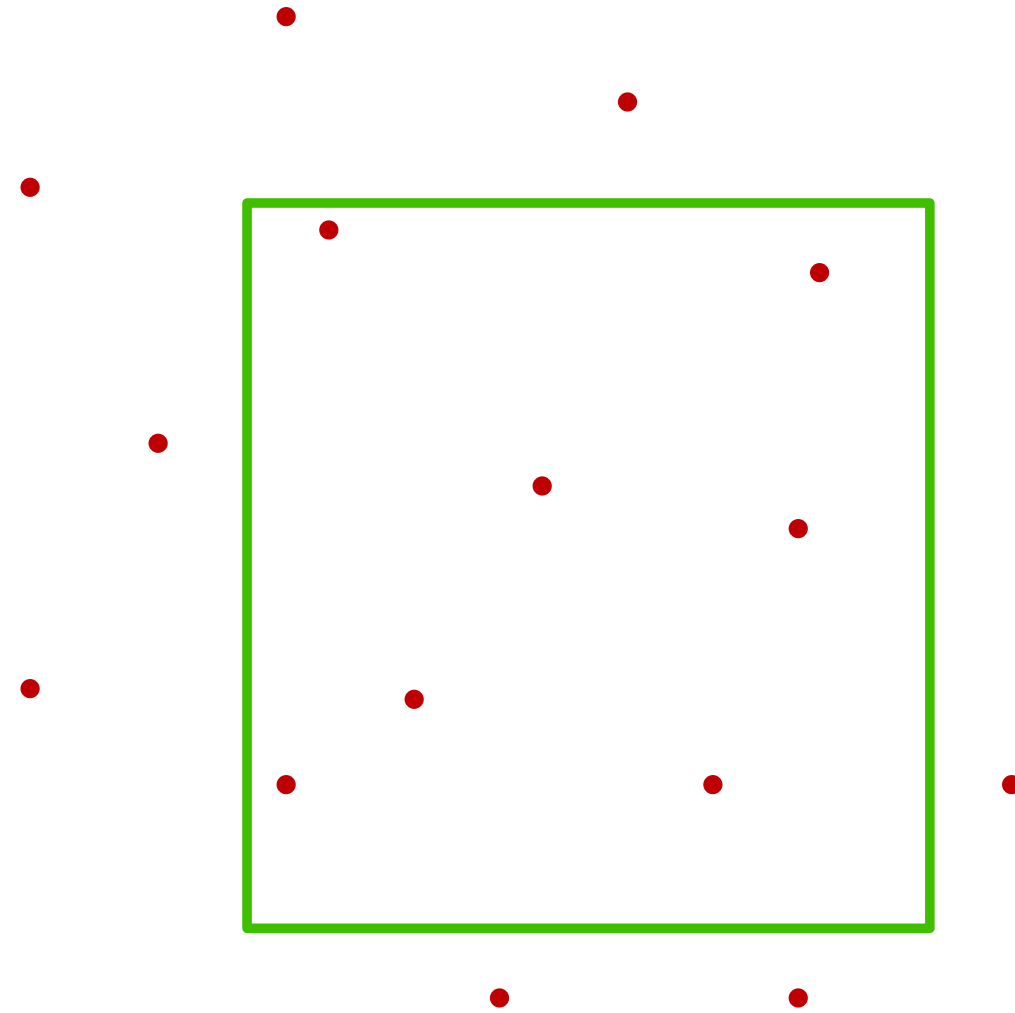


range spaces and VC-dimension

Range space

range space: pair (X, \mathcal{R})

- X is a set
- \mathcal{R} is a subset of power set of X



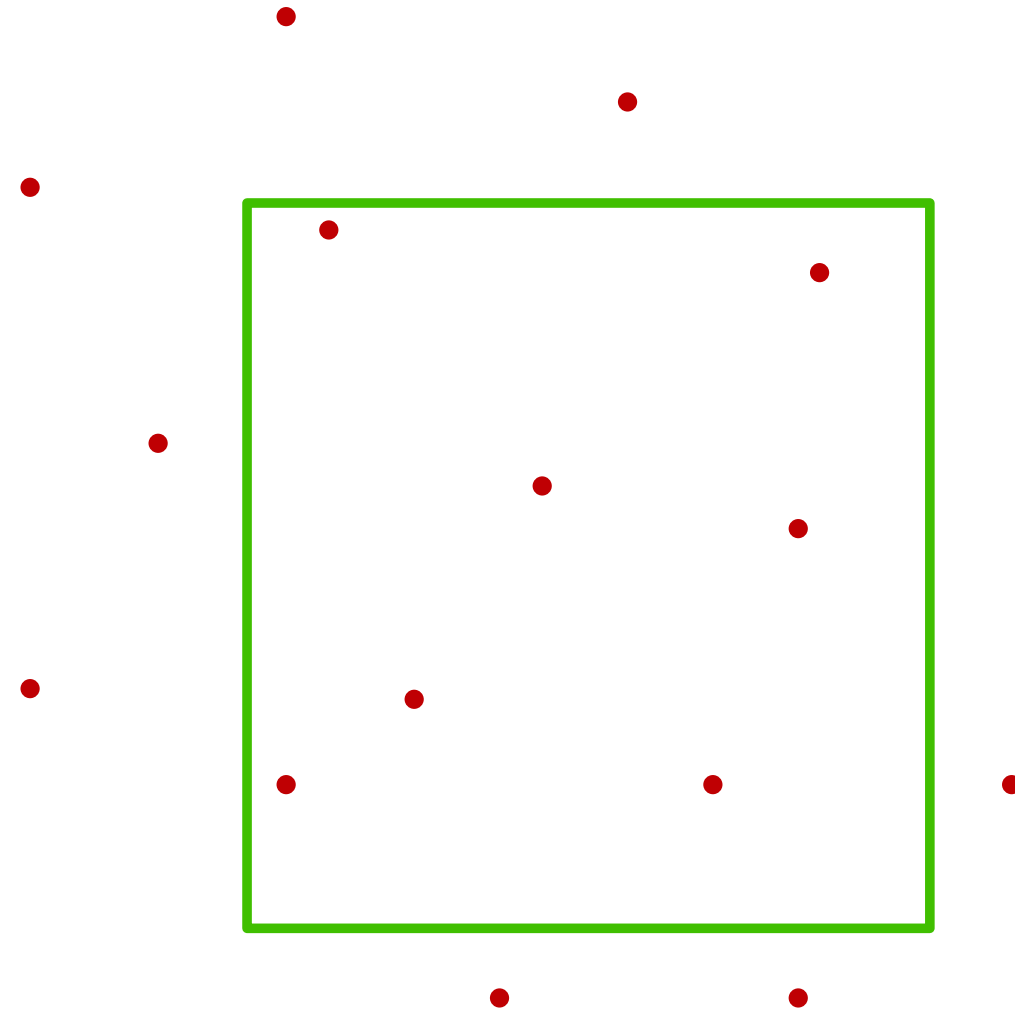
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- $X = \mathbb{R}^2$
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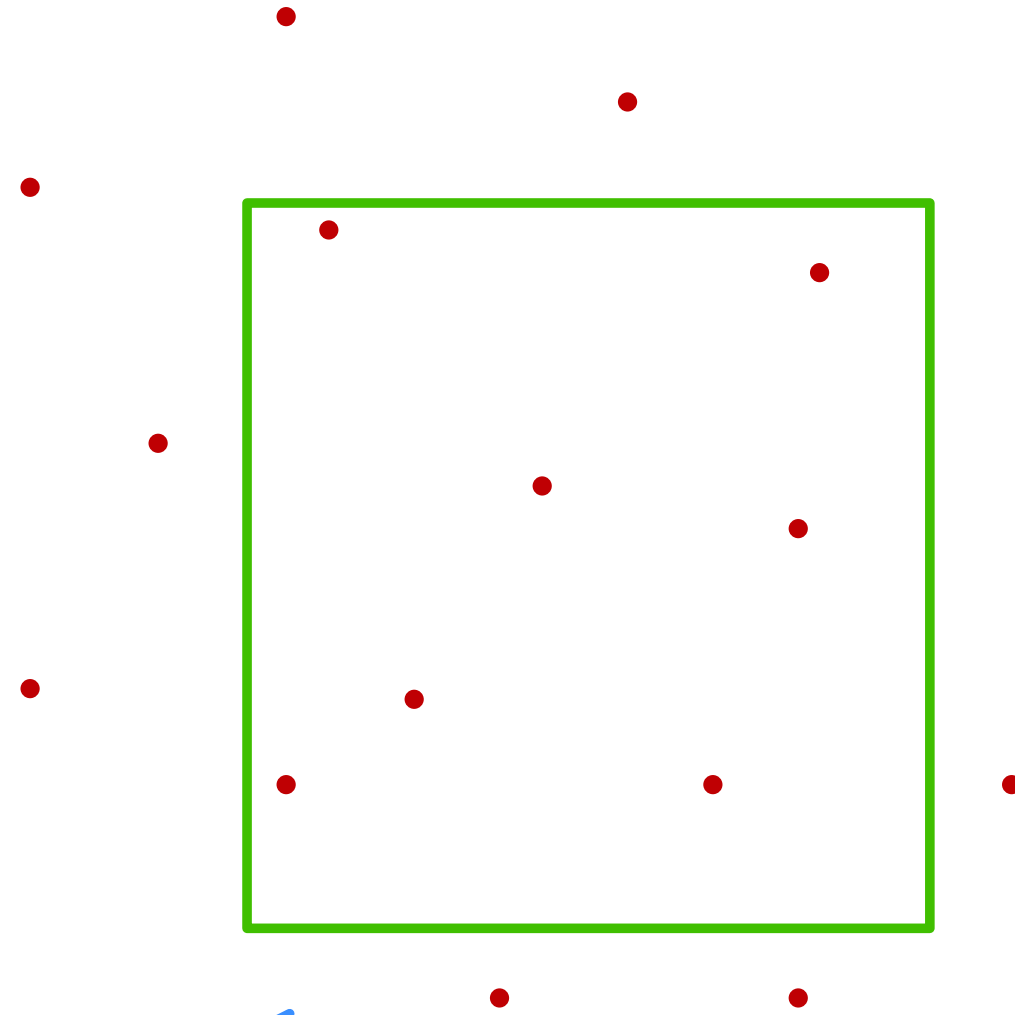
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restriction $\mathcal{R}|_P$

- $P \subseteq X$
- $\mathcal{R}|_P := \{r \cap P \mid r \in \mathcal{R}\}$
- $(P, \mathcal{R}|_P)$ is a range space, e.g.,



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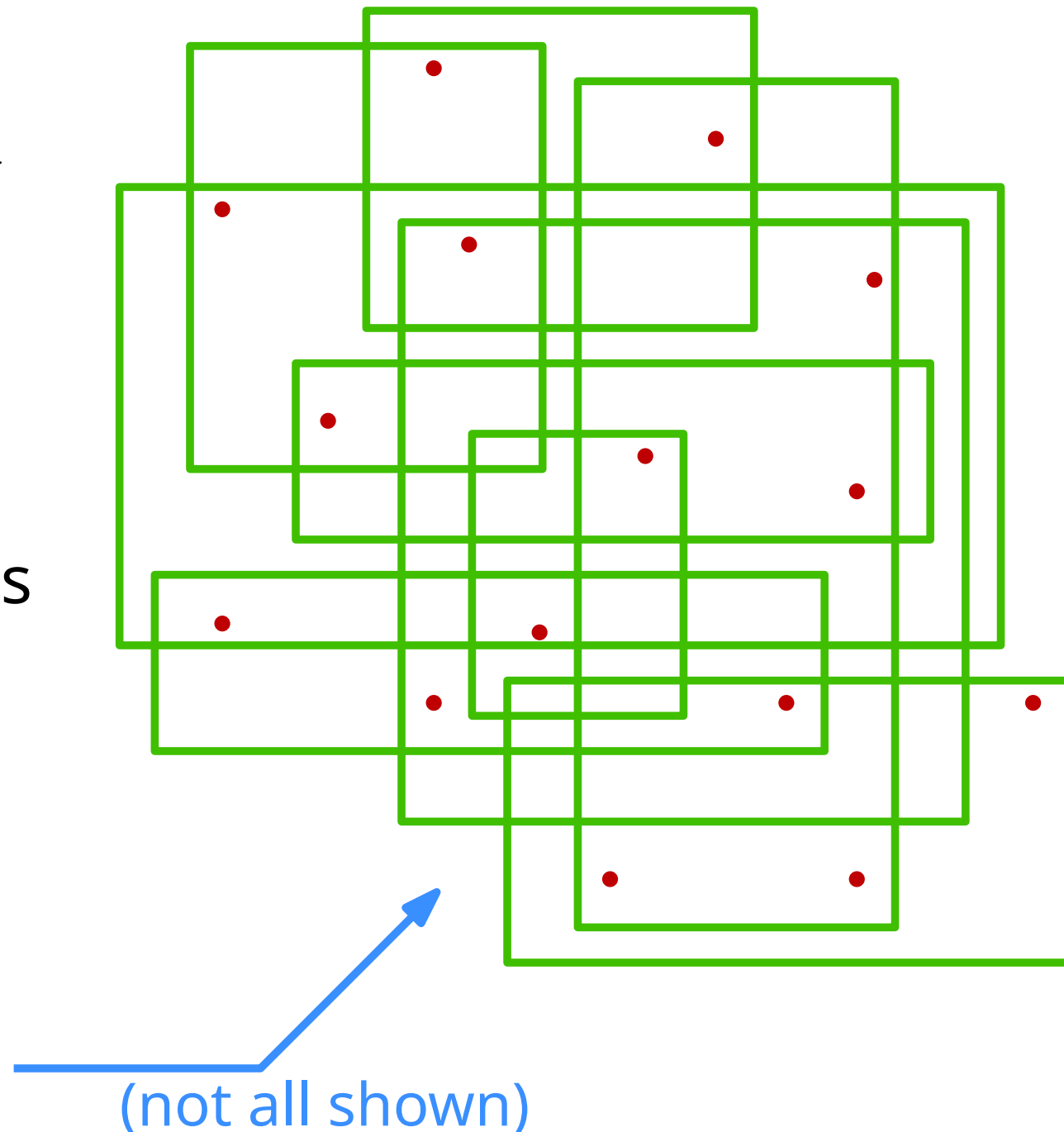
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Examples of range spaces

$(\mathbb{R}, \mathcal{I})$, with \mathcal{I} = set of closed intervals

$(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks

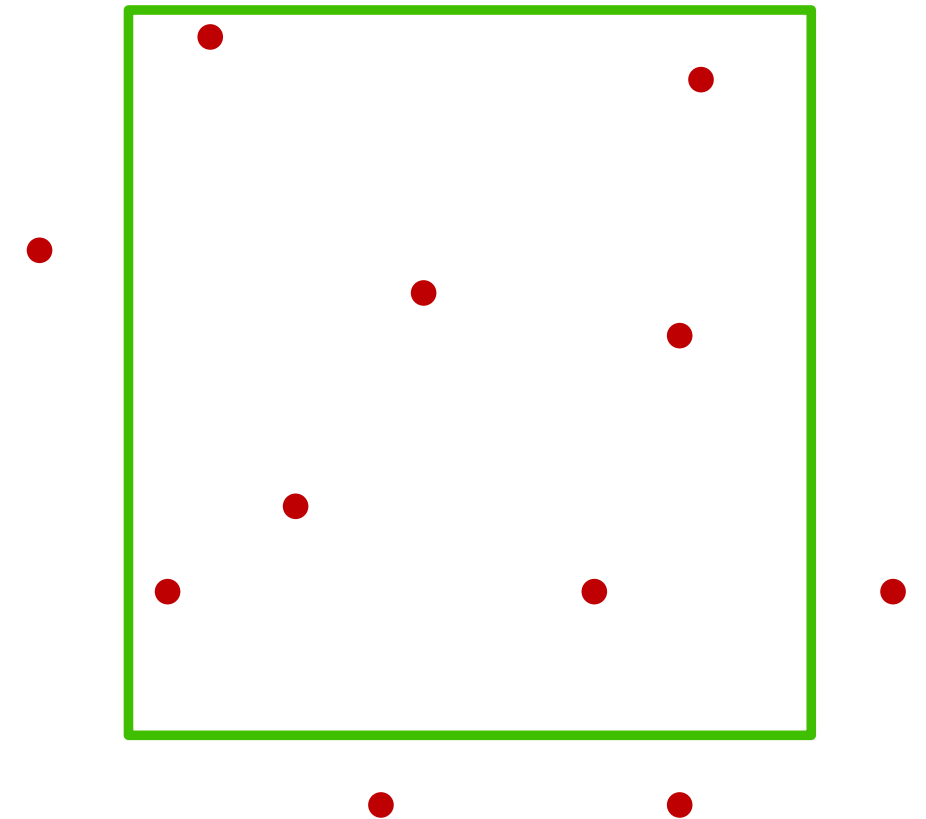
$(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

$(\mathbb{R}^2, \mathcal{GR})$, with \mathcal{GR} = set of arbitrary oriented rectangles

$(\mathbb{R}^2, \mathcal{C})$, with \mathcal{C} = set of closed convex sets

VC-dimension

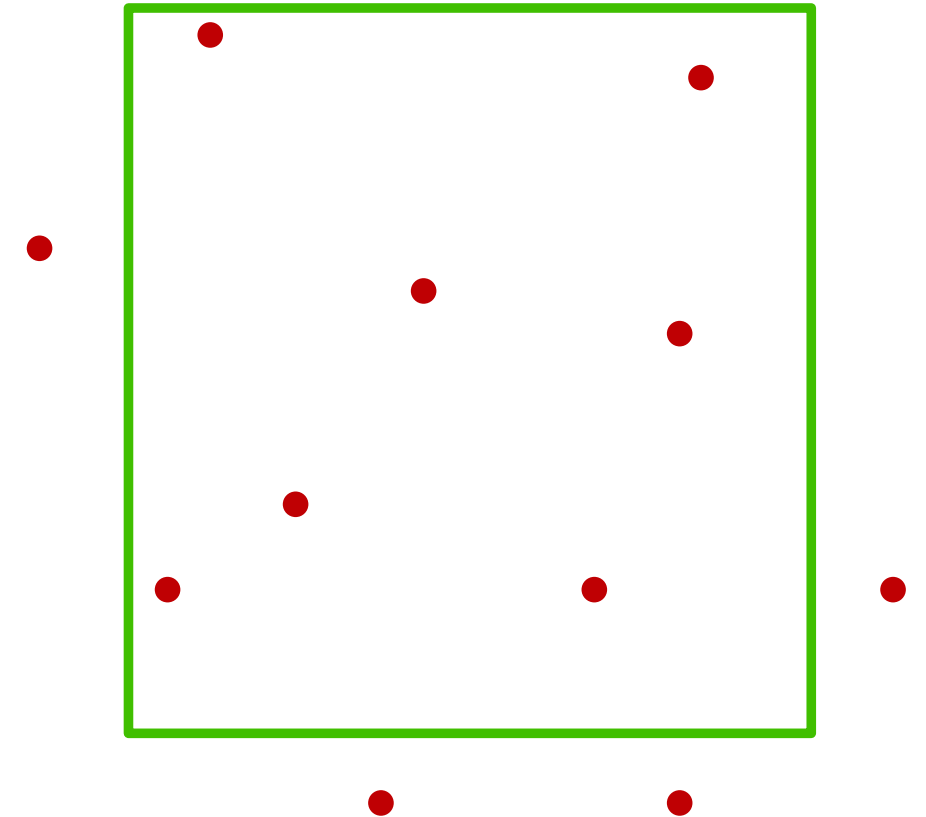
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VC-dimension

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want to quantify: range space has "low complexity"

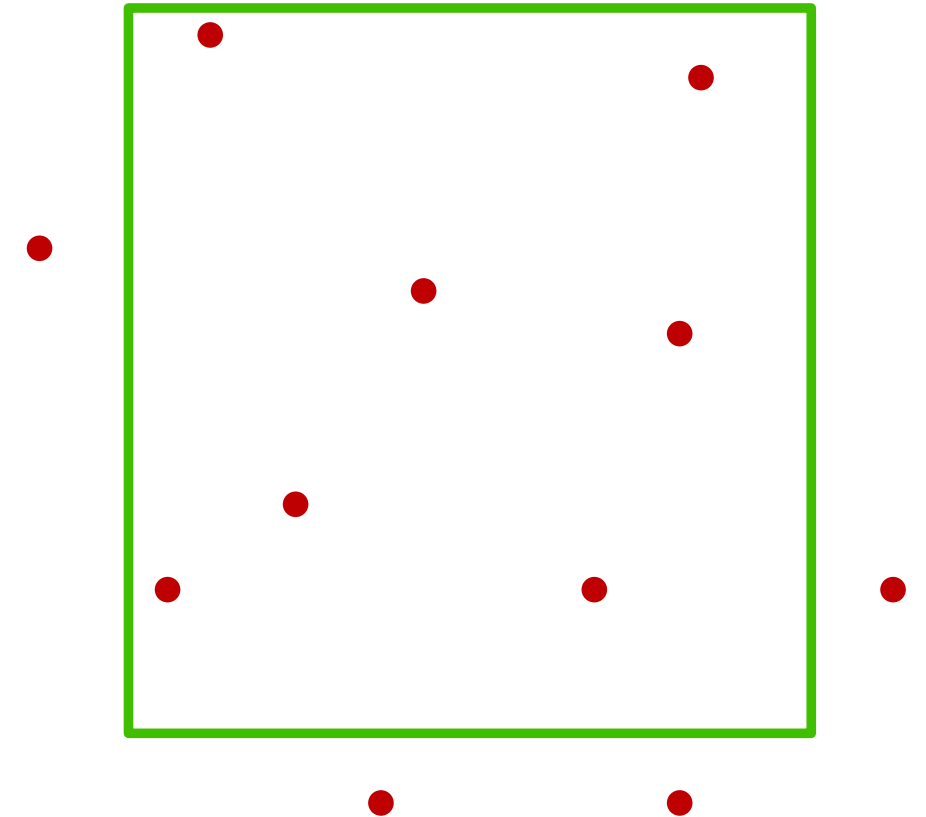


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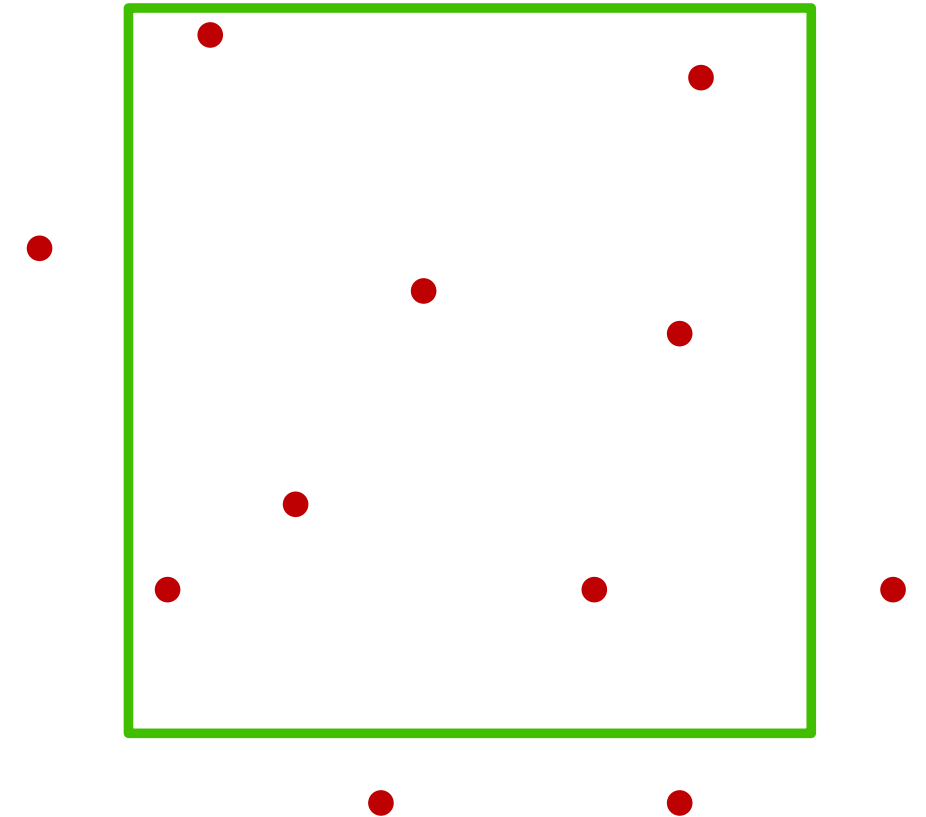
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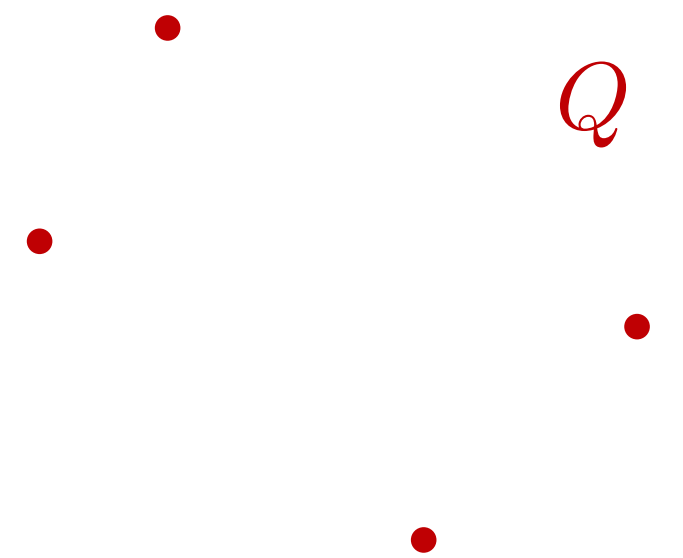
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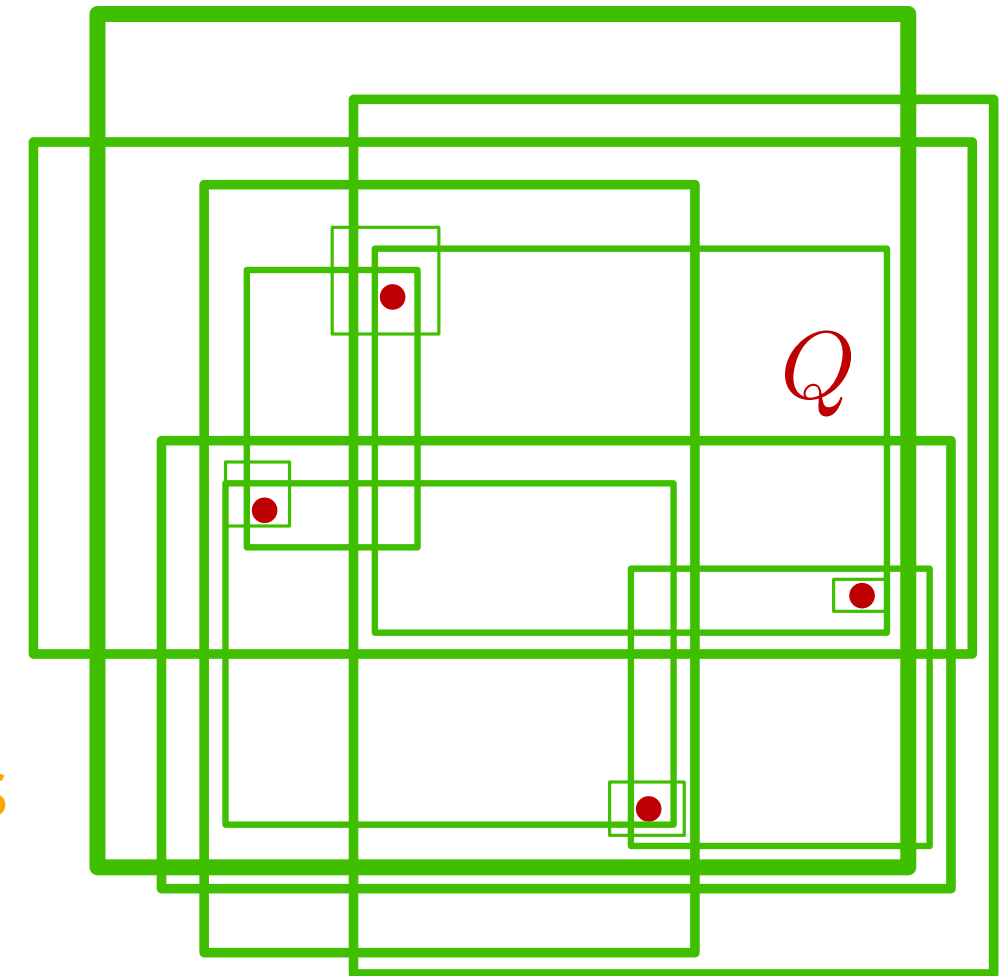
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VC-dimension

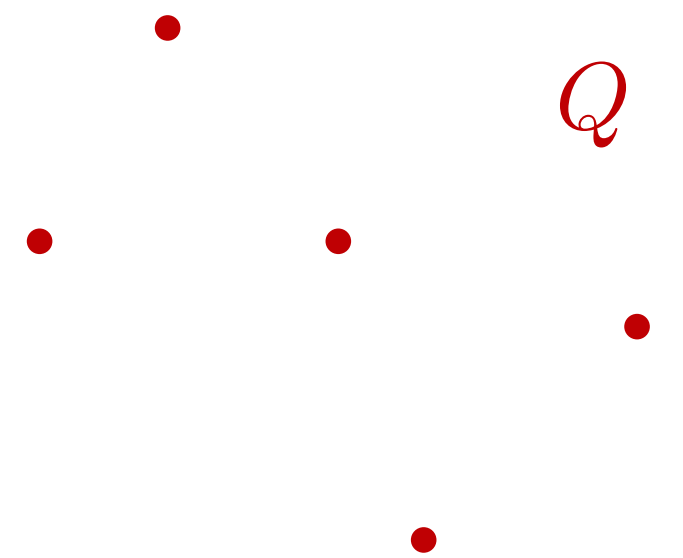
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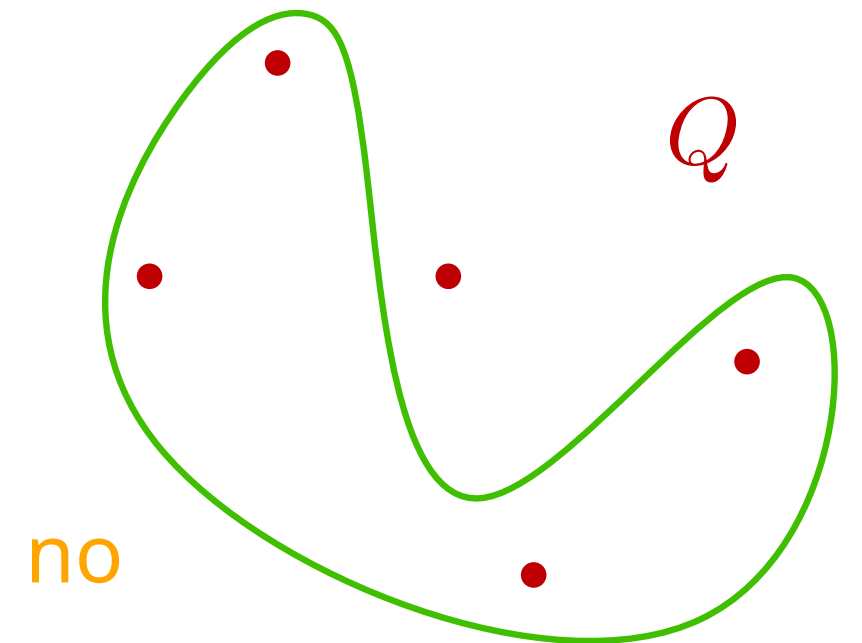
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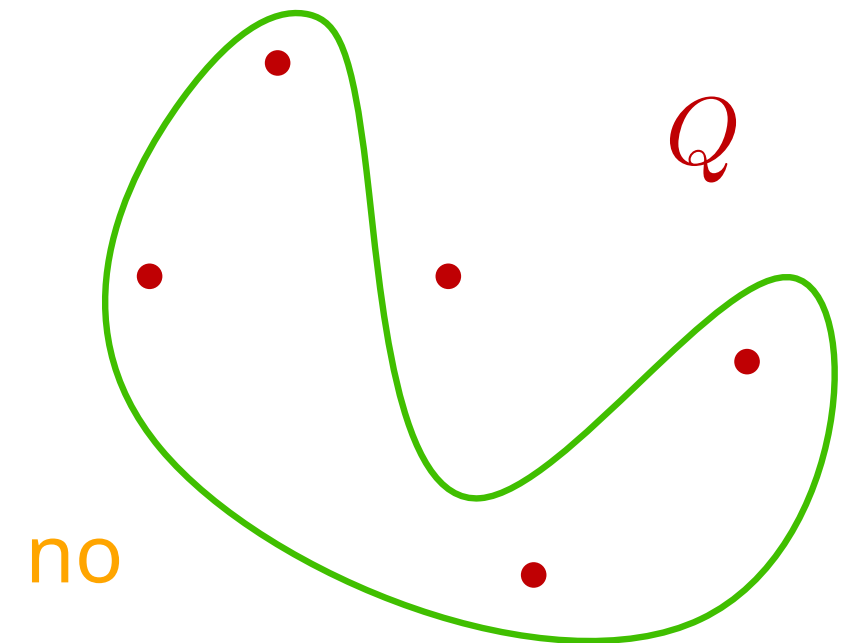
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VC-dimension of a range space:
maximum size of a shattered subset of X

Example $(\mathbb{R}, \mathcal{I})$

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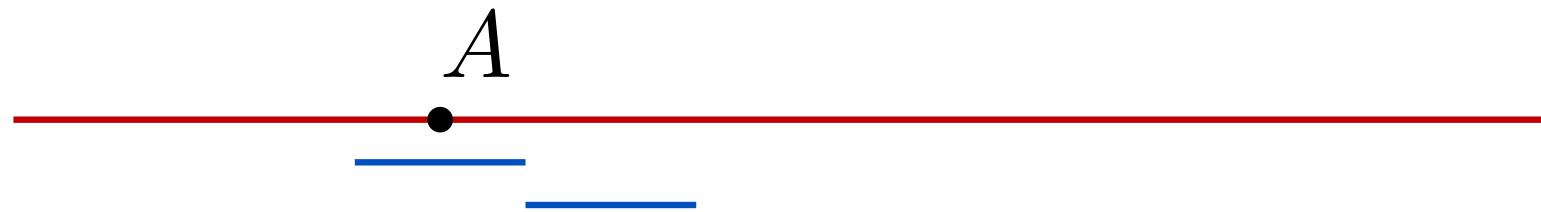


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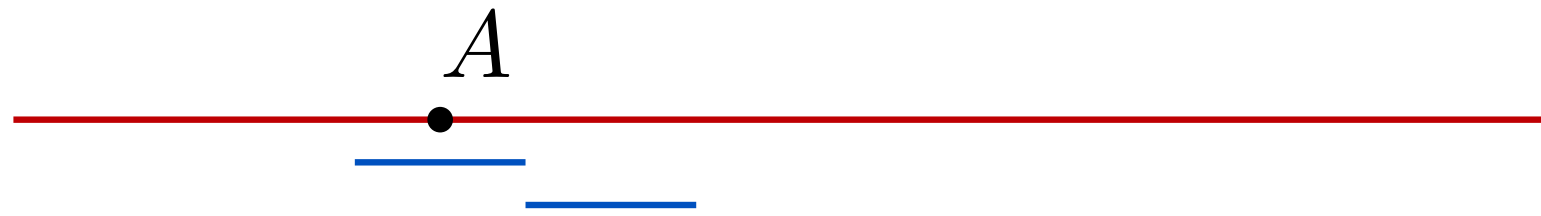
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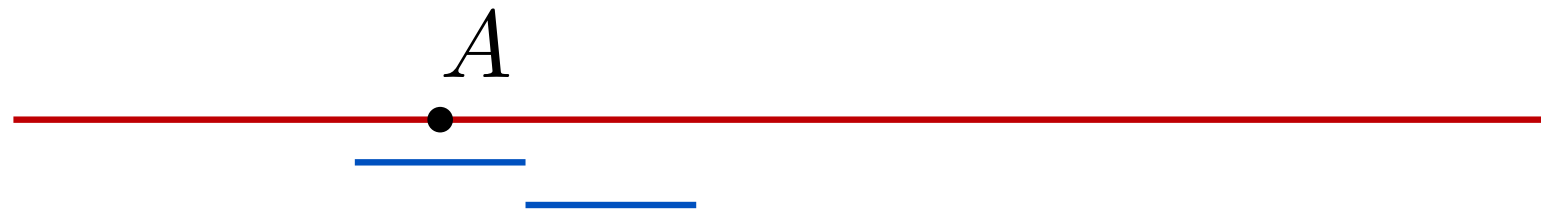


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$$|\mathcal{R}_{|P}| = 2 = 2^{|P|}$$

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Example $(\mathbb{R}, \mathcal{I})$



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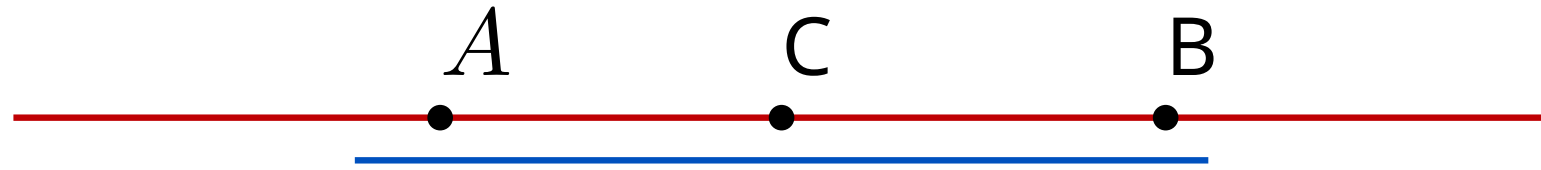


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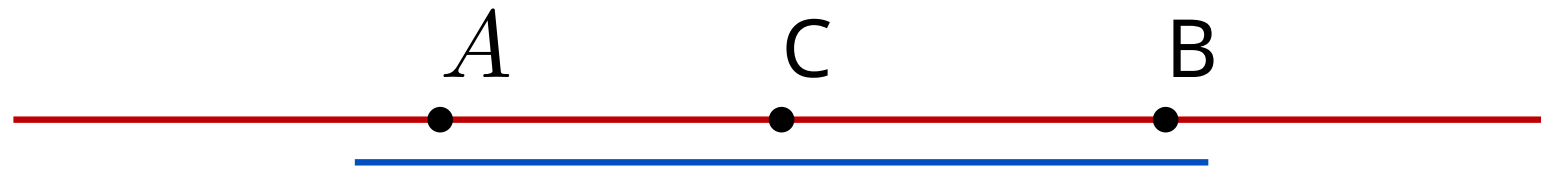
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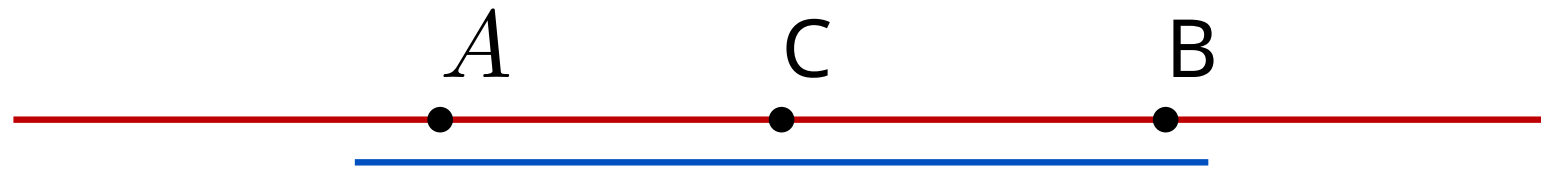
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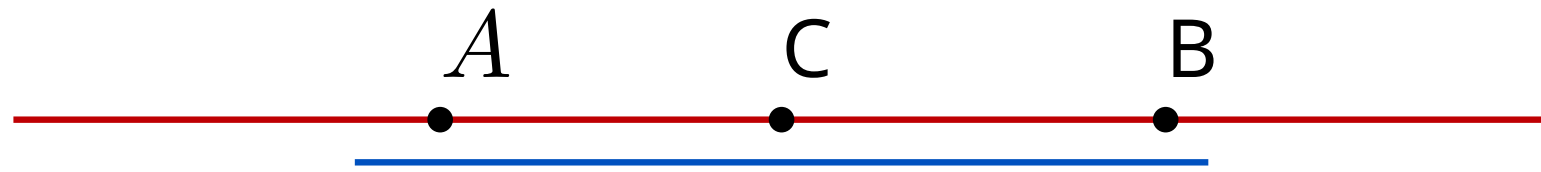


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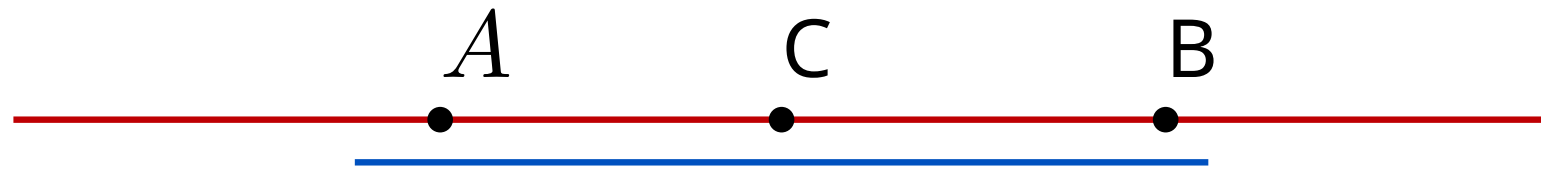
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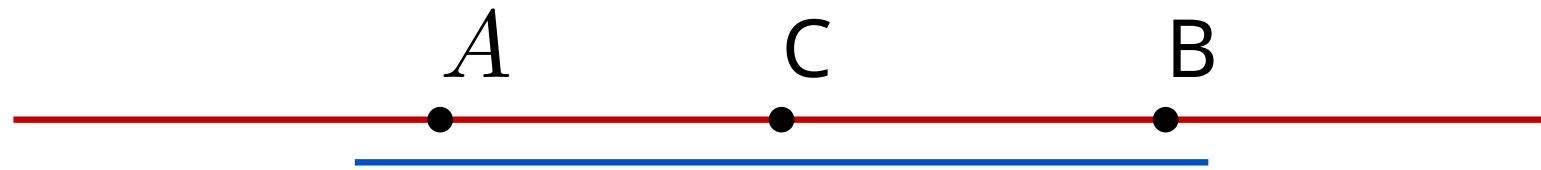
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No set of 3 or more elements can be shattered.

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VC-dimension = 2

Quiz

range space $(\mathbb{R}, \mathcal{I}_{\rightarrow})$ with $\mathcal{I}_{\rightarrow} = \{[a, \infty) \mid a \in \mathbb{R}\}$



What is the VC-dimension of this space?

- A 1
- B 2
- C 3

Quiz

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What is the VC-dimension of this space?

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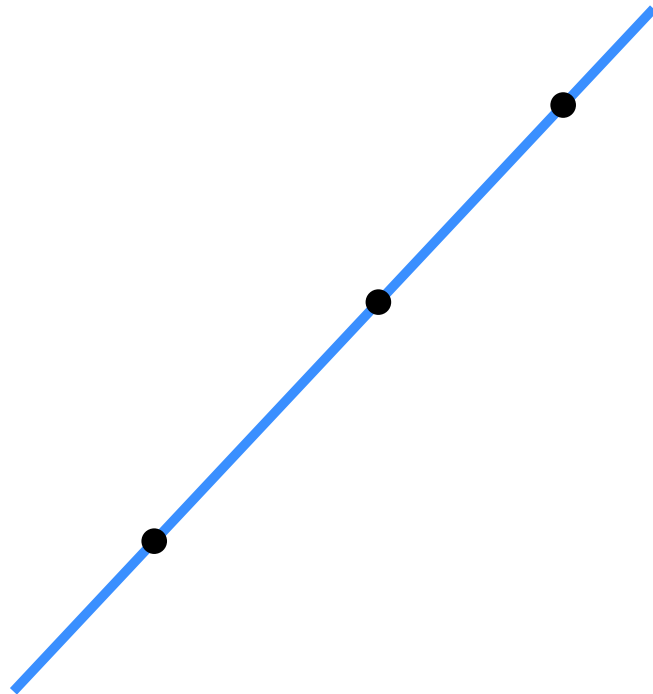
C 3

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks

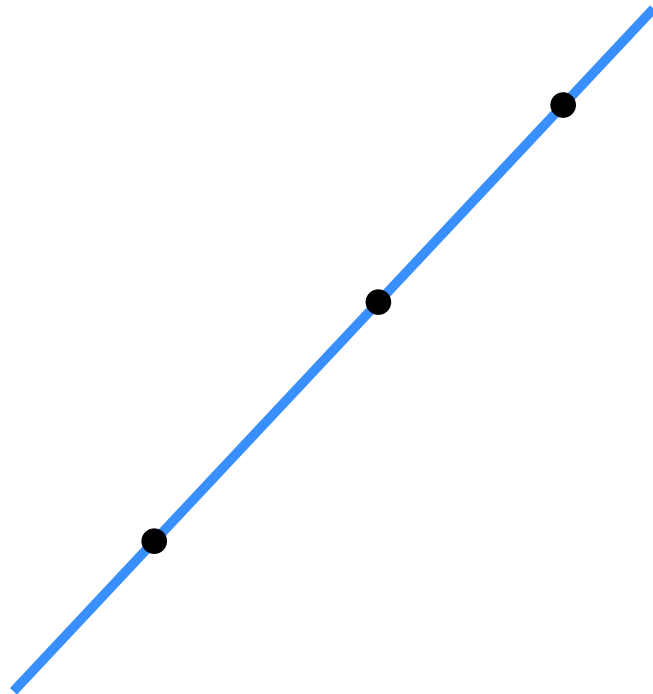
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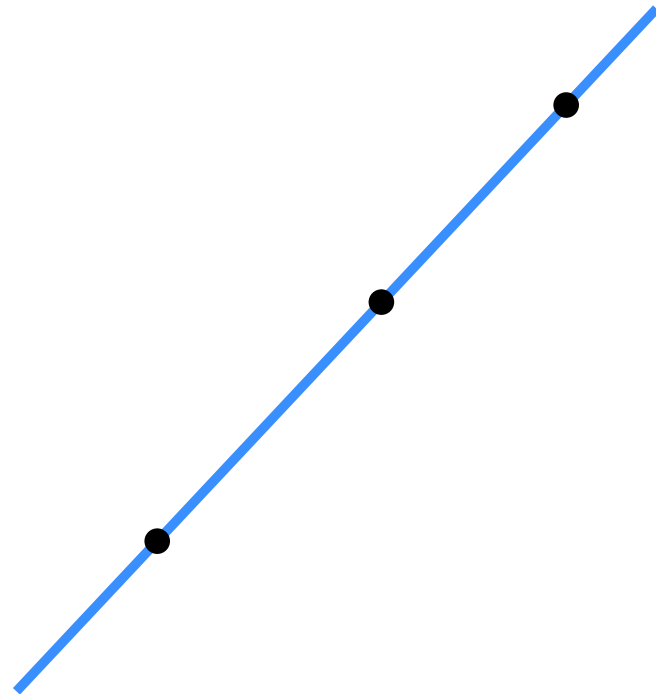
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not shatter !

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not shatter !

not relevant, since VC-dimension = **maximum** size of shattered subset

Example: disks as ranges

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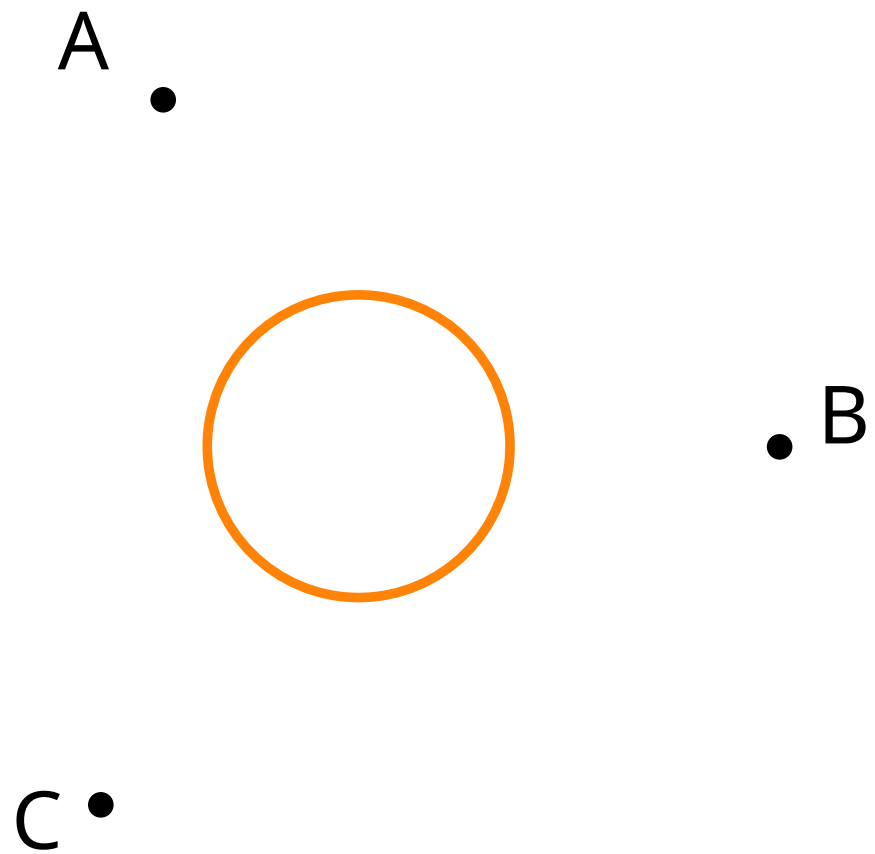
A •

• B

C •

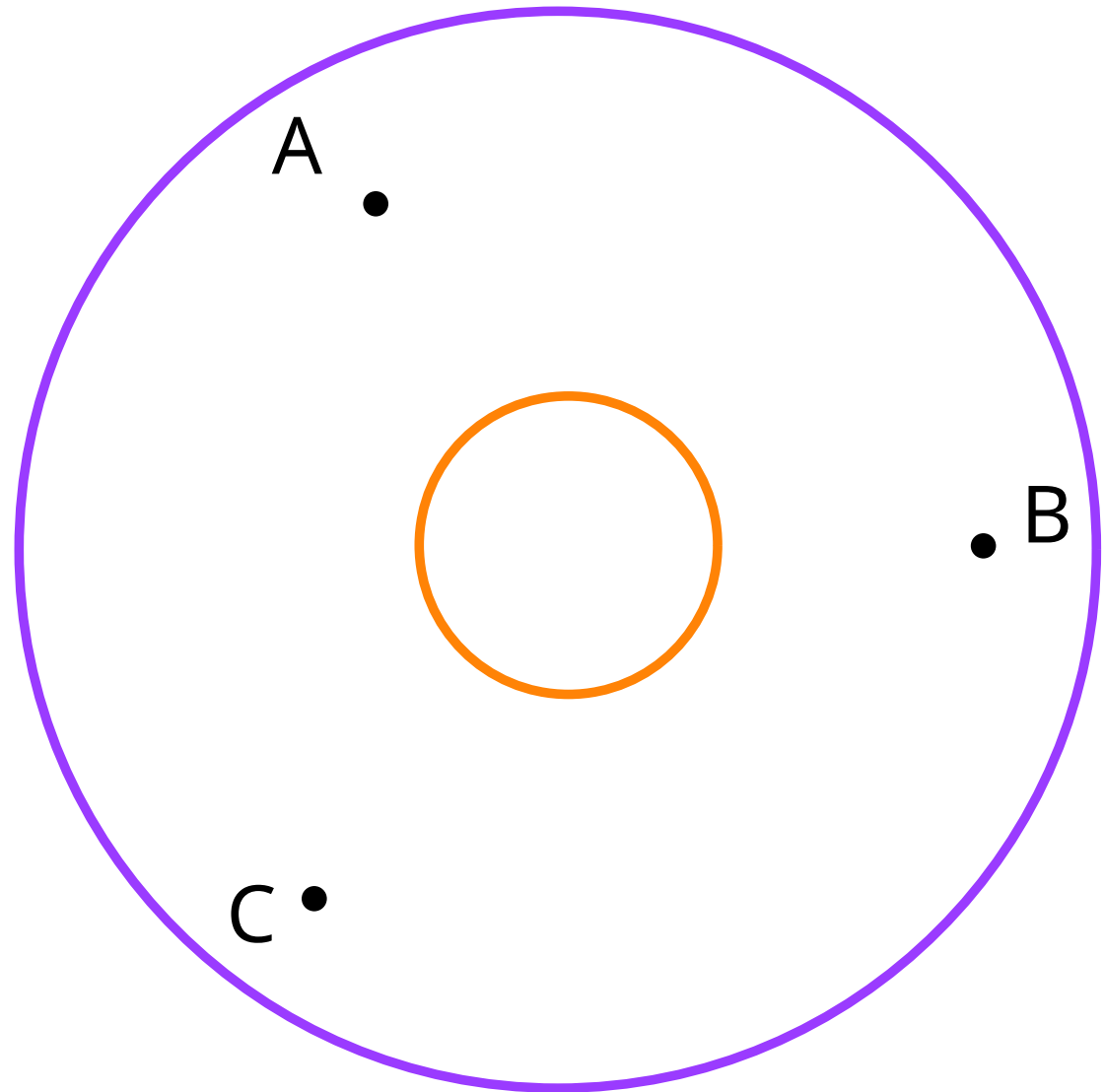
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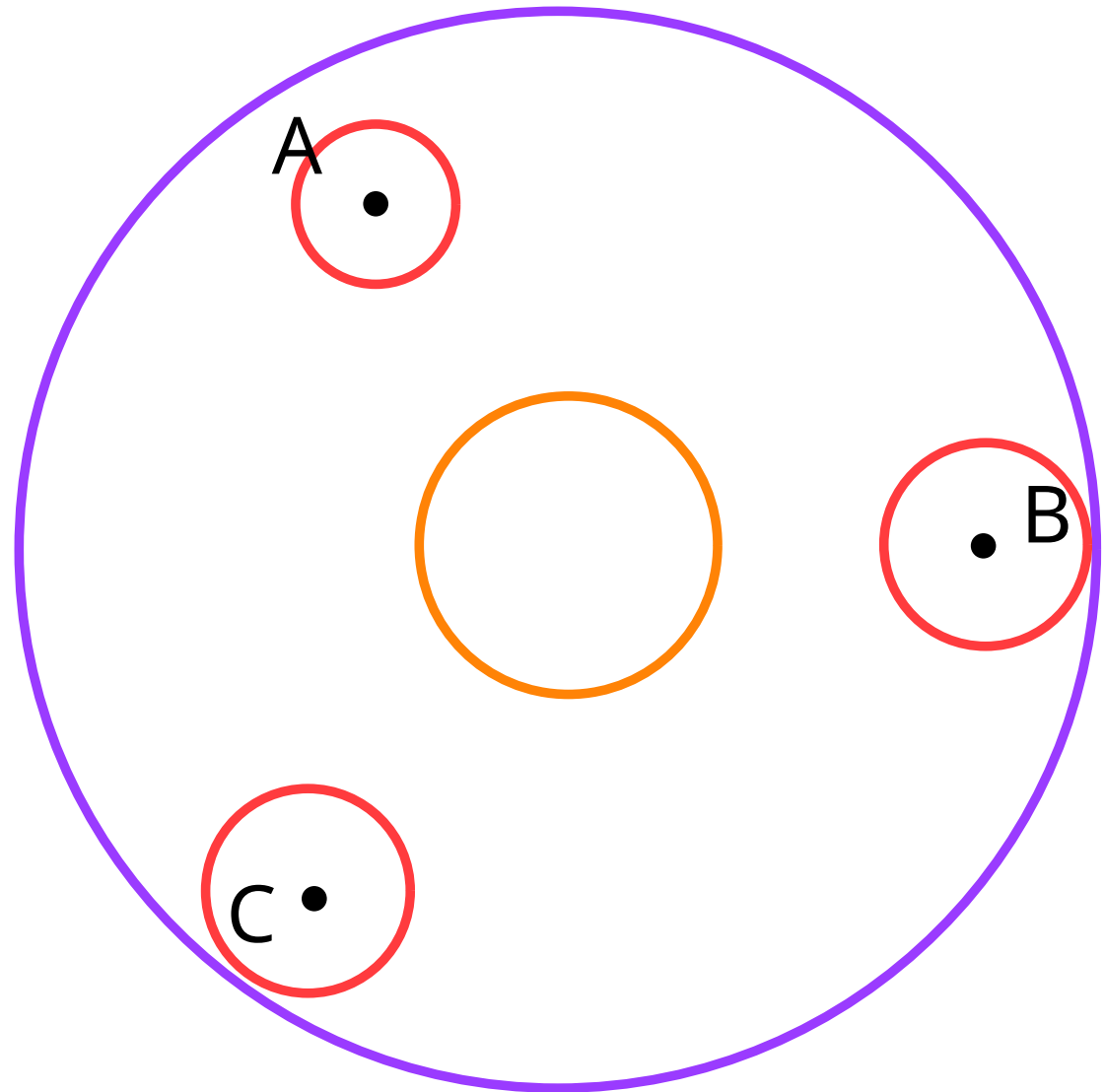
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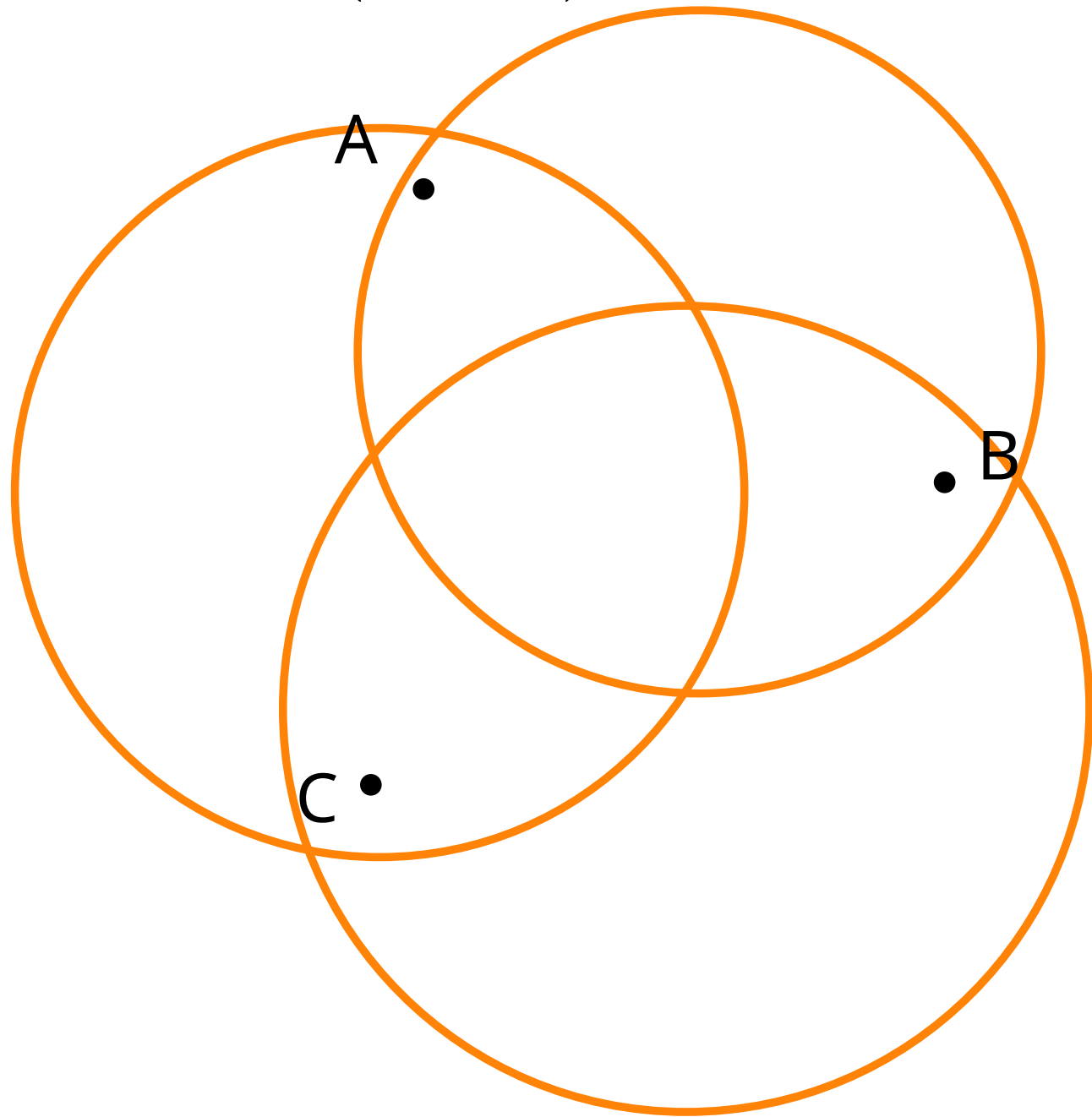
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C •

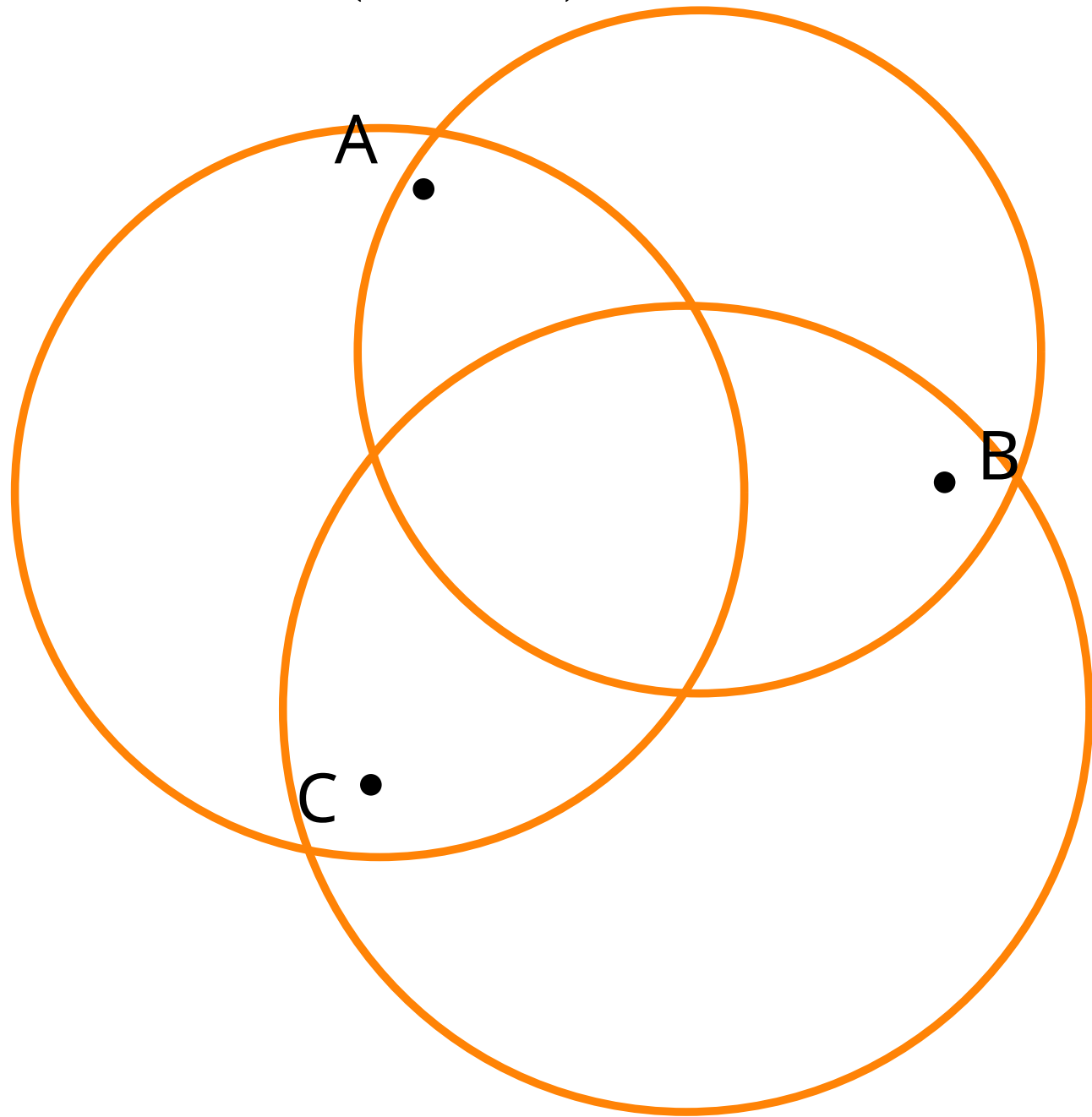
Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks



Example: disks as ranges

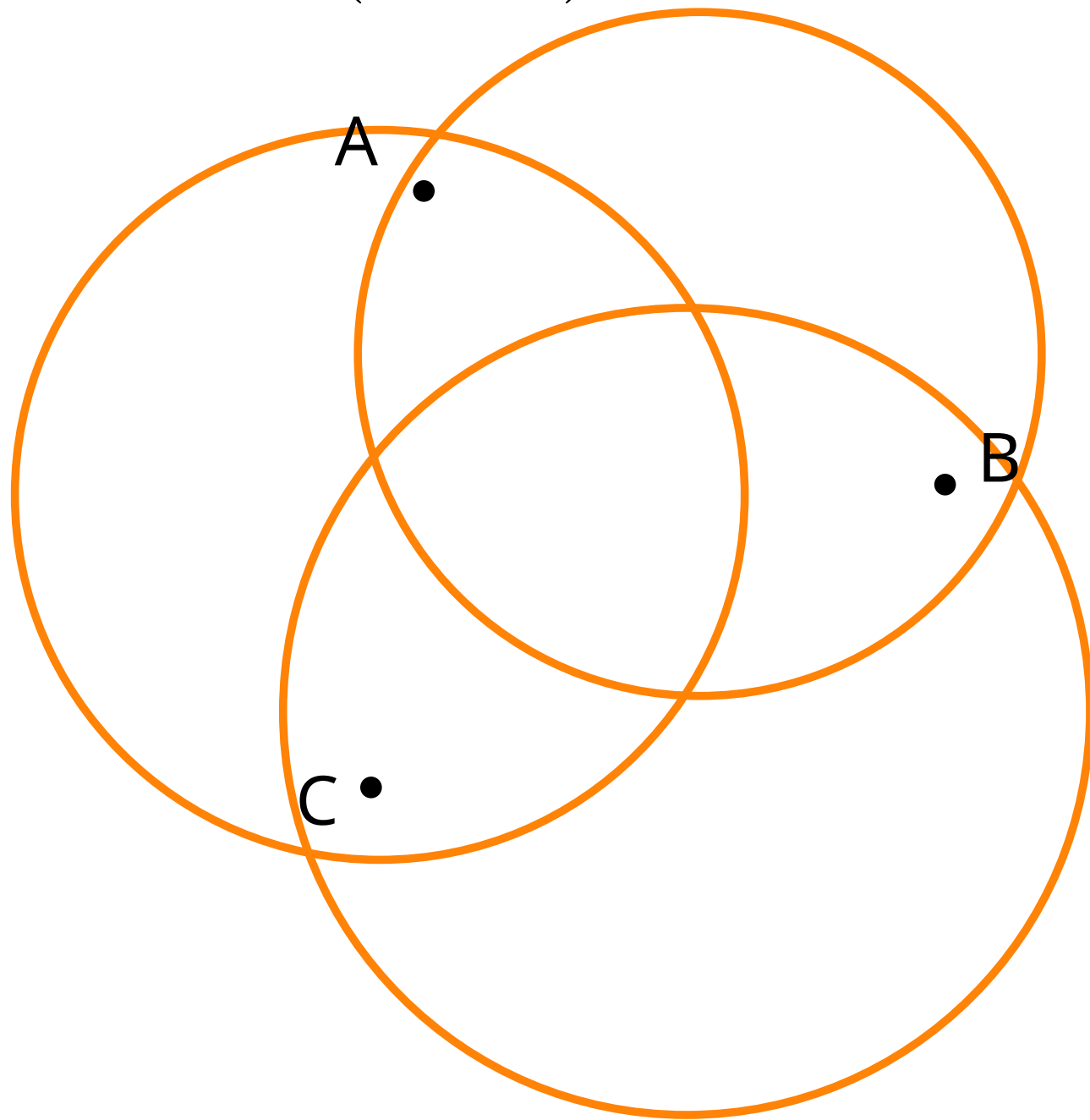
range space $(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks



shatter !

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks

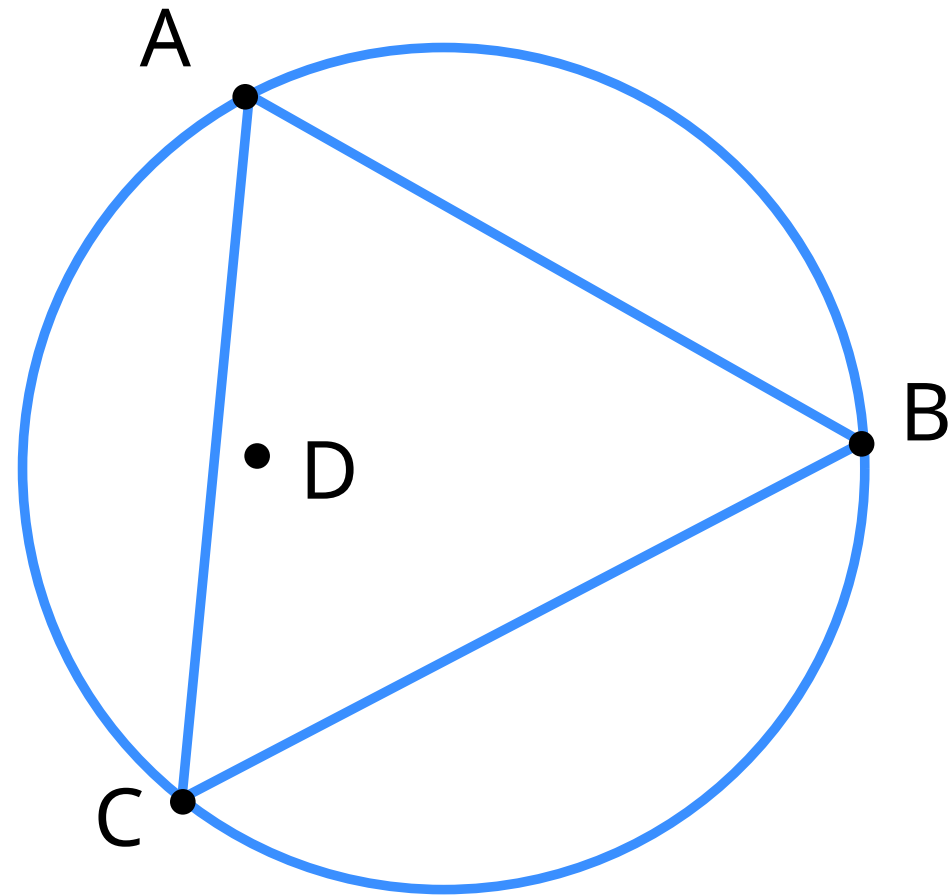


\Rightarrow VC-dimension ≥ 3

shatter !

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks

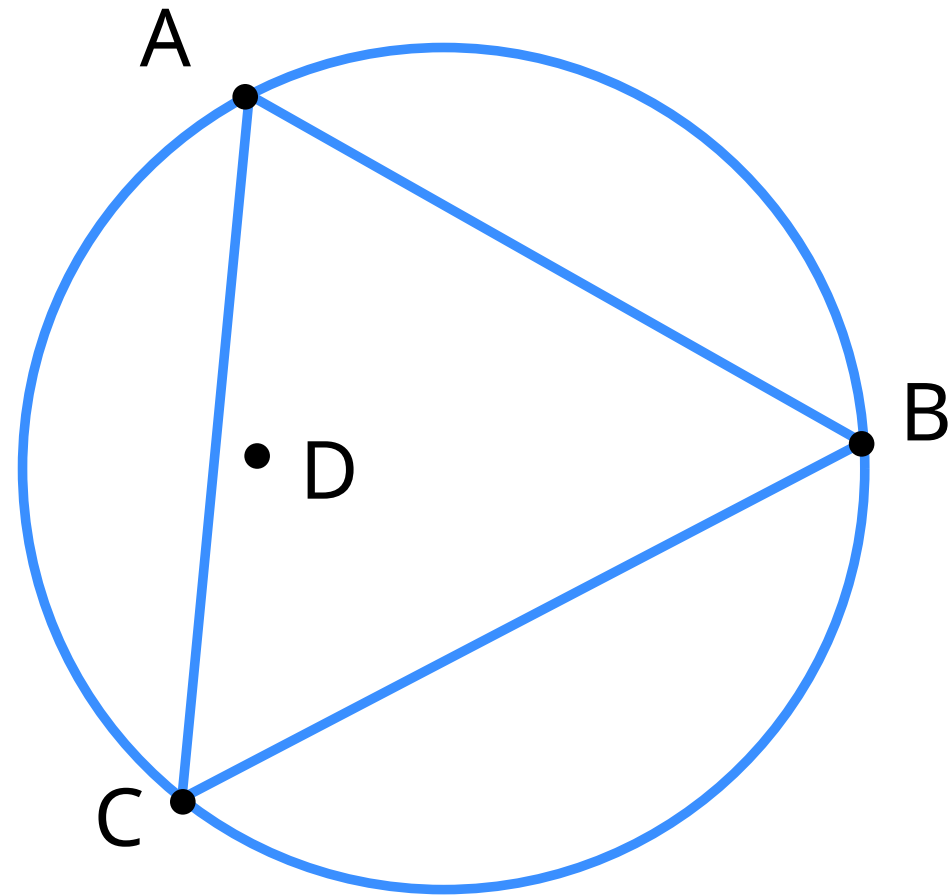


4 points

case 1: $D \in \text{triangle}(ABC)$

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks



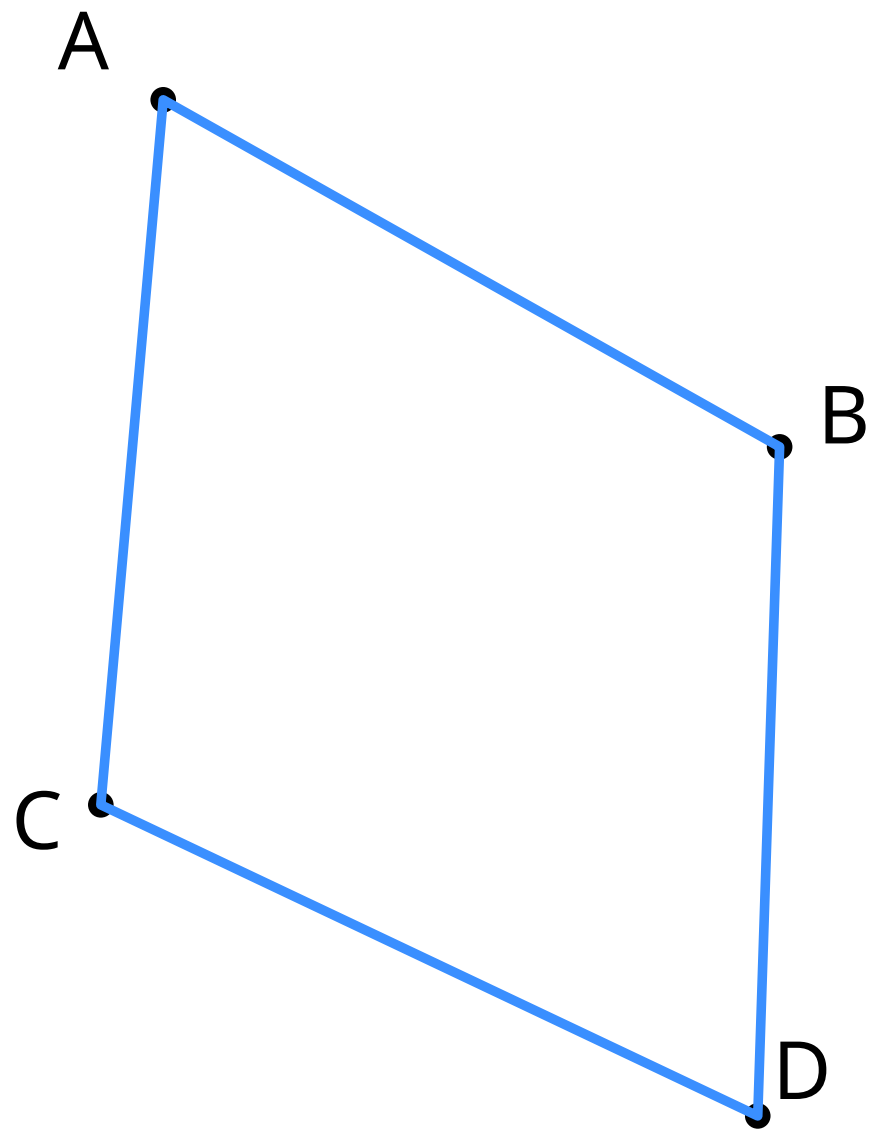
4 points

case 1: $D \in \text{triangle}(ABC)$

not shatter !

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks



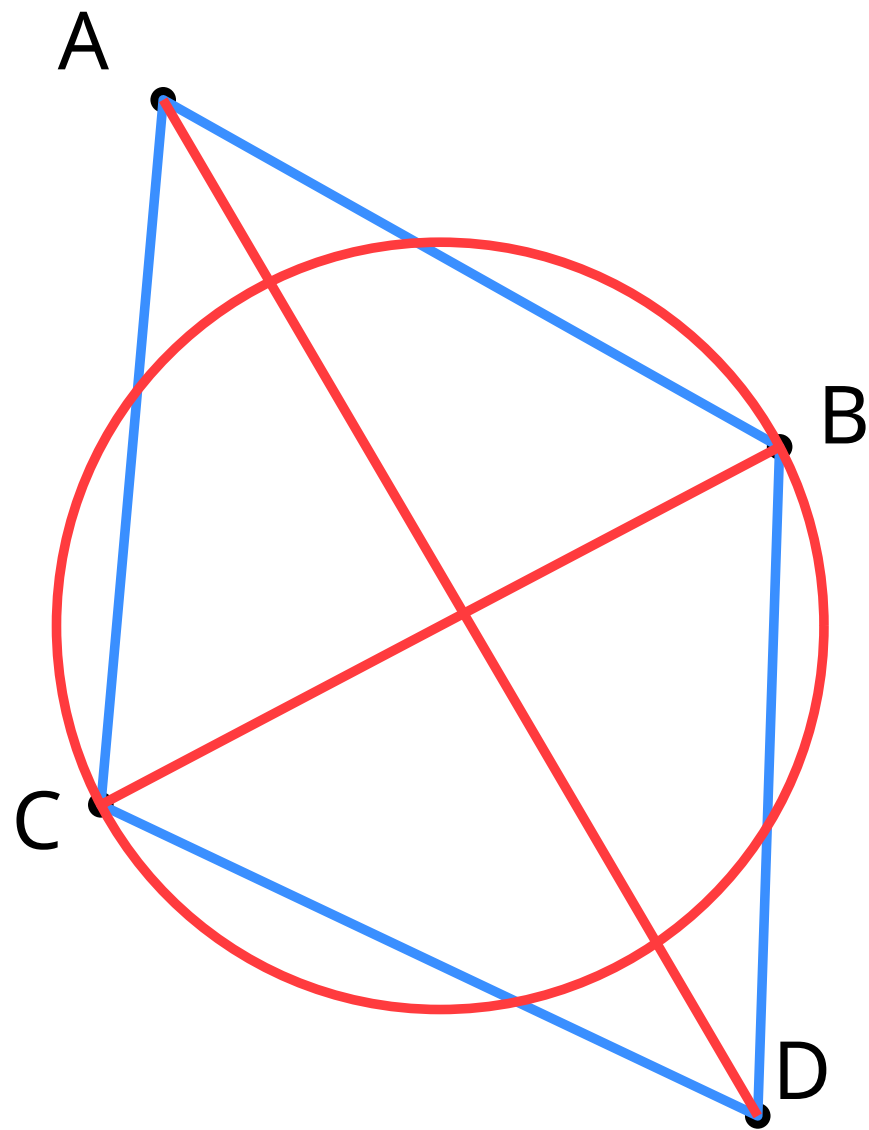
4 points

case 1: $D \in \text{triangle}(ABC)$

case 2: $ABCD$ convex quadrilateral

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks



4 points

case 1: $D \in \text{triangle}(ABC)$

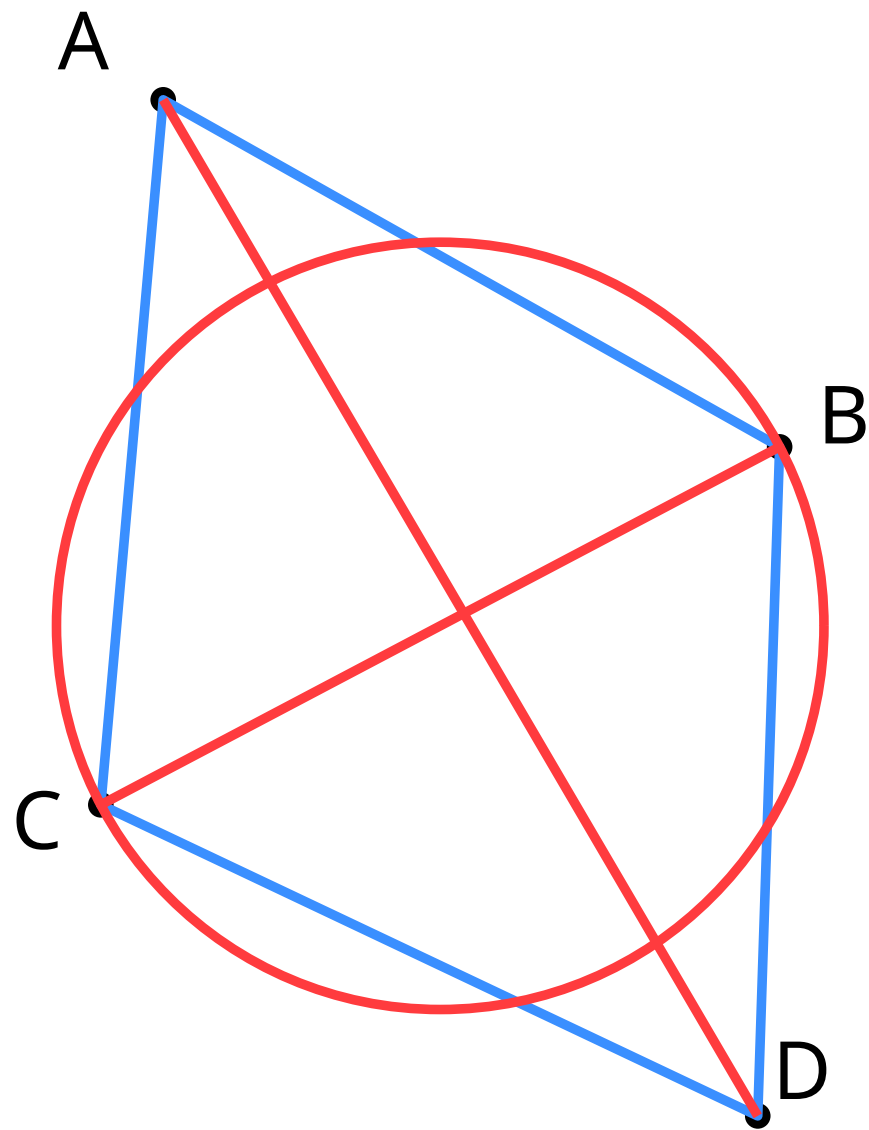
case 2: $ABCD$ convex quadrilateral

without proof:

can't get $\{A, D\}$ and $\{B, C\}$

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks



4 points

case 1: $D \in \text{triangle}(ABC)$

case 2: $ABCD$ convex quadrilateral

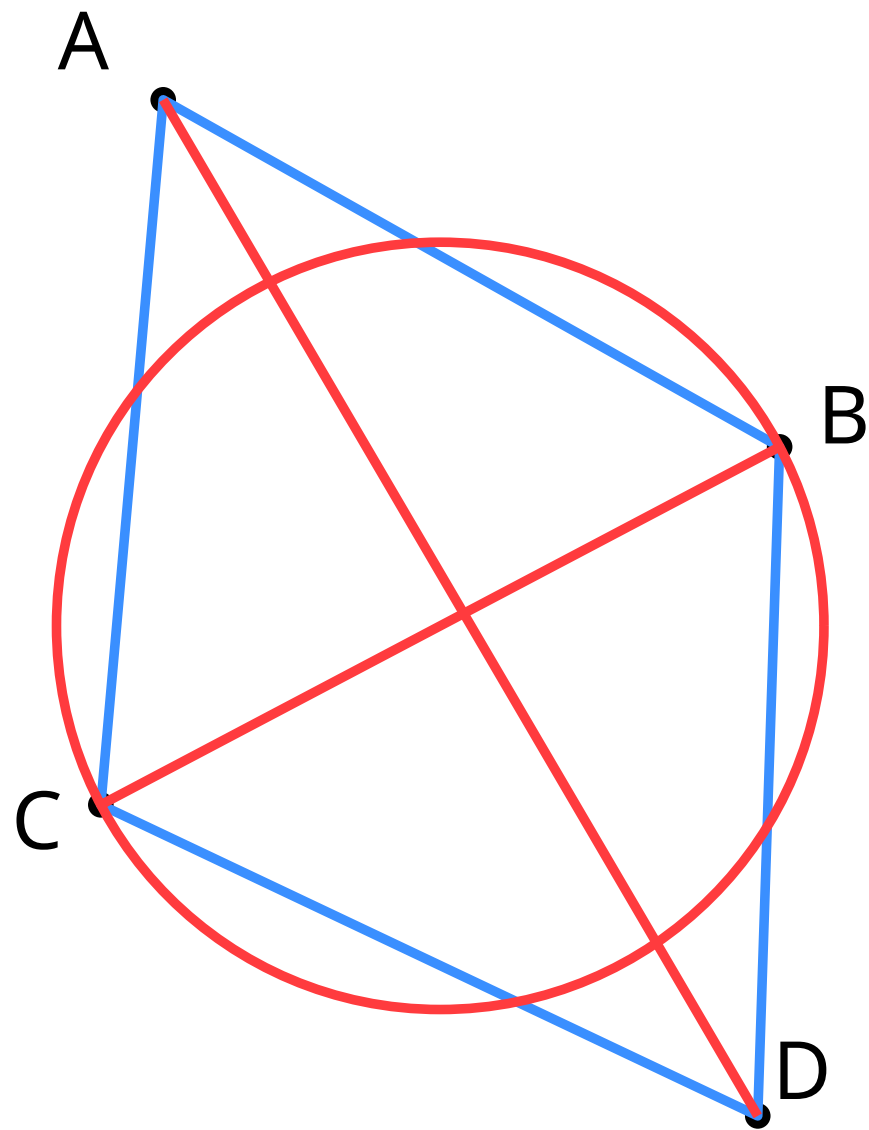
without proof:

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not shatter !

Example: disks as ranges

range space $(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks



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case 1: $D \in \text{triangle}(ABC)$

case 2: $ABCD$ convex quadrilateral

without proof:

can't get $\{A, D\}$ and $\{B, C\}$

\Rightarrow VC-dimension = 3

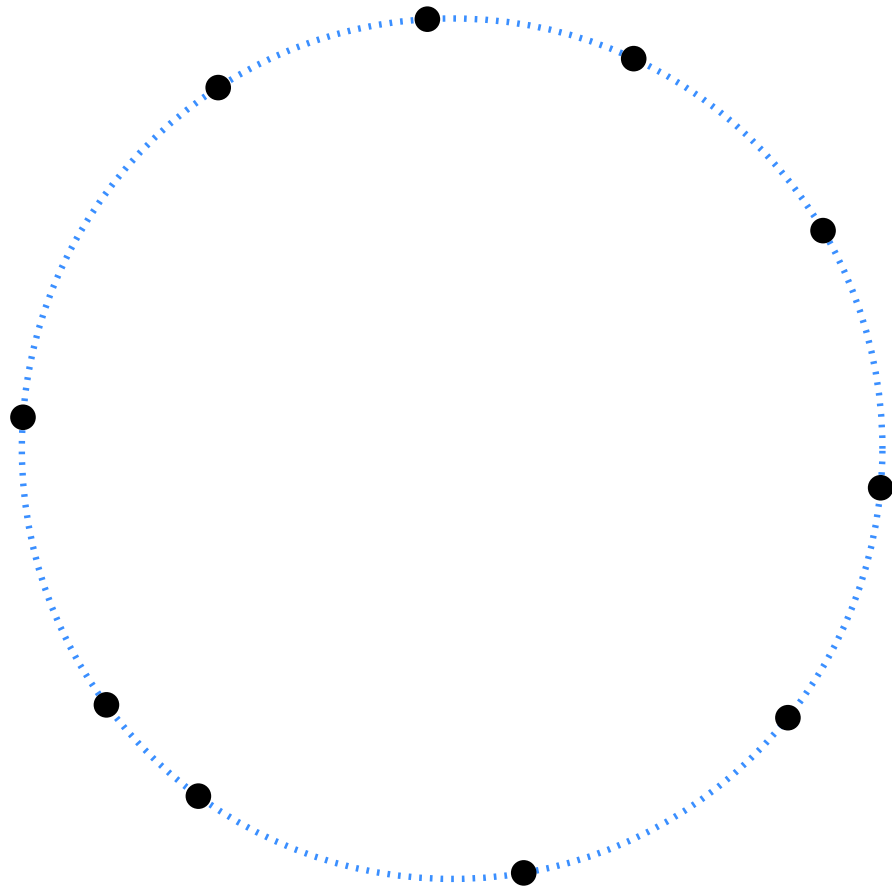
not shatter !

Example: convex sets as ranges

range space $(\mathbb{R}^2, \mathcal{C})$, with \mathcal{C} = set of closed convex sets

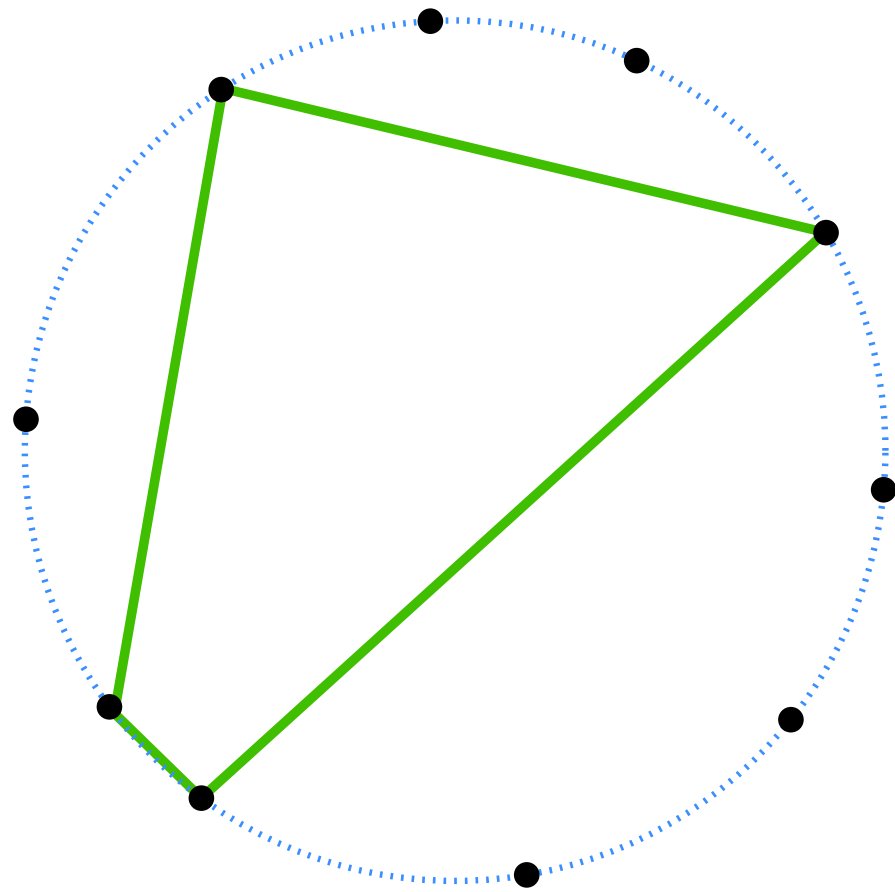
Example: convex sets as ranges

range space $(\mathbb{R}^2, \mathcal{C})$, with $\mathcal{C} =$ set of closed convex sets



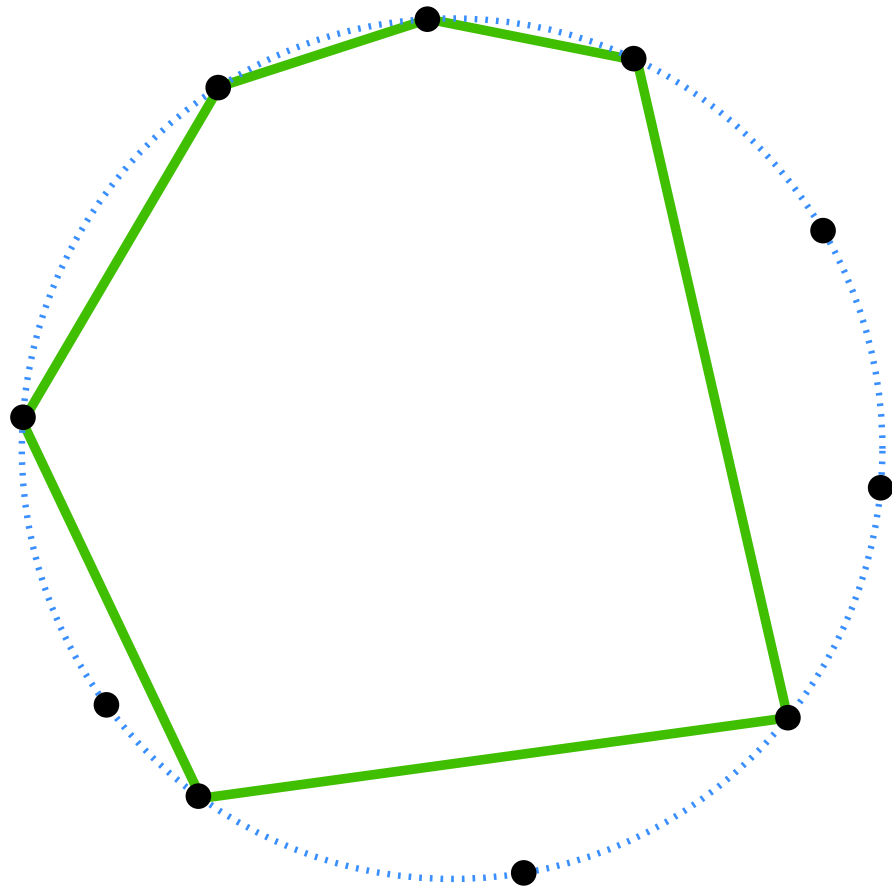
Example: convex sets as ranges

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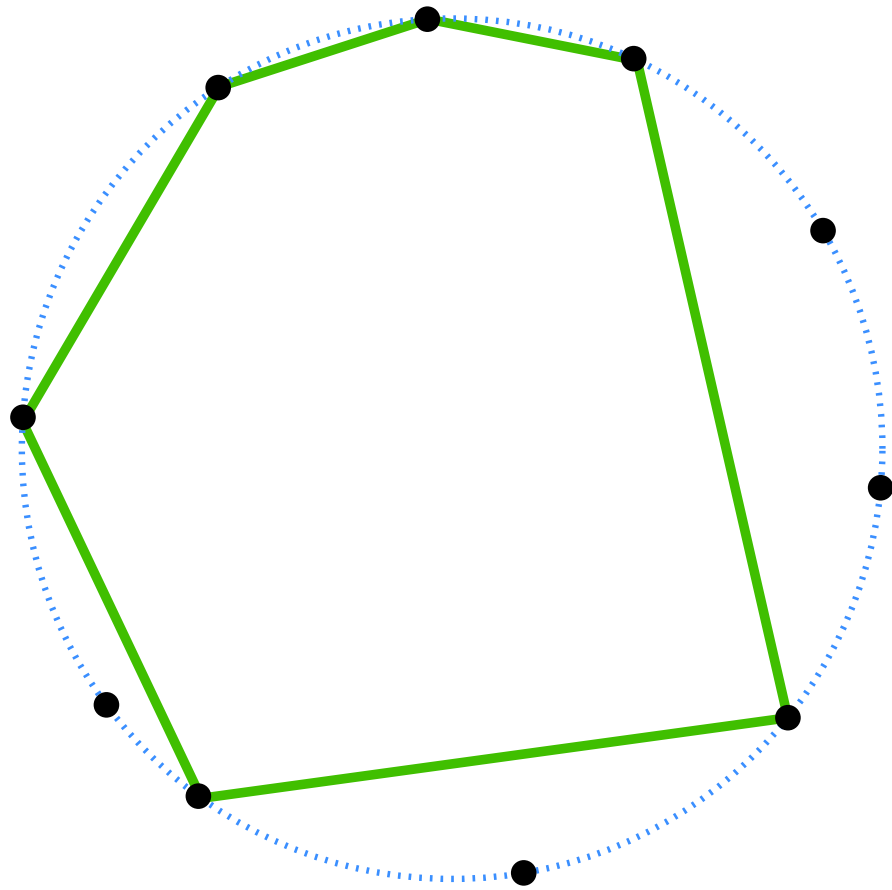
Example: convex sets as ranges

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Example: convex sets as ranges

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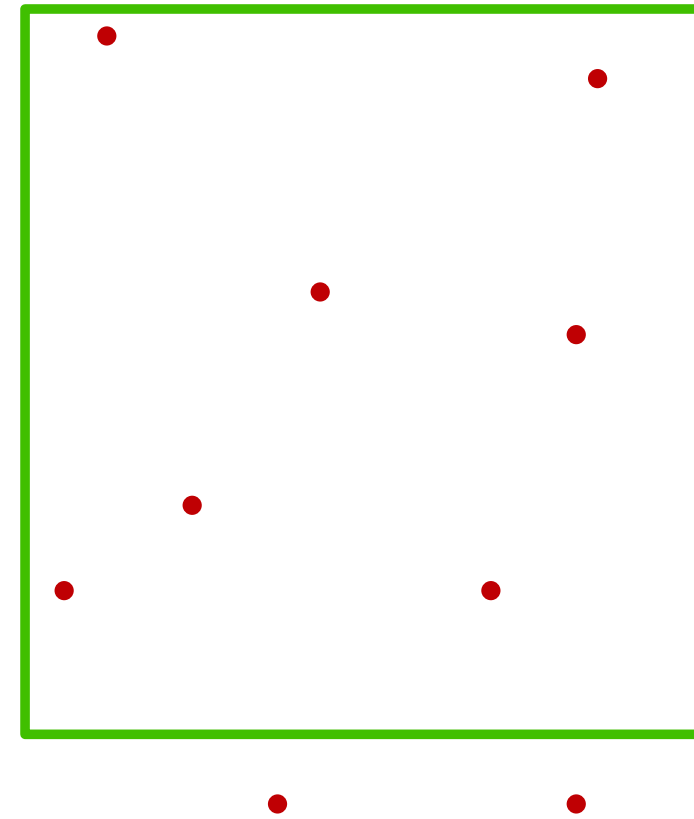
\Rightarrow VC-dimension = ∞

Quiz

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

What is its VC-dimension?

- A 4
- B 5
- C ∞



Quiz

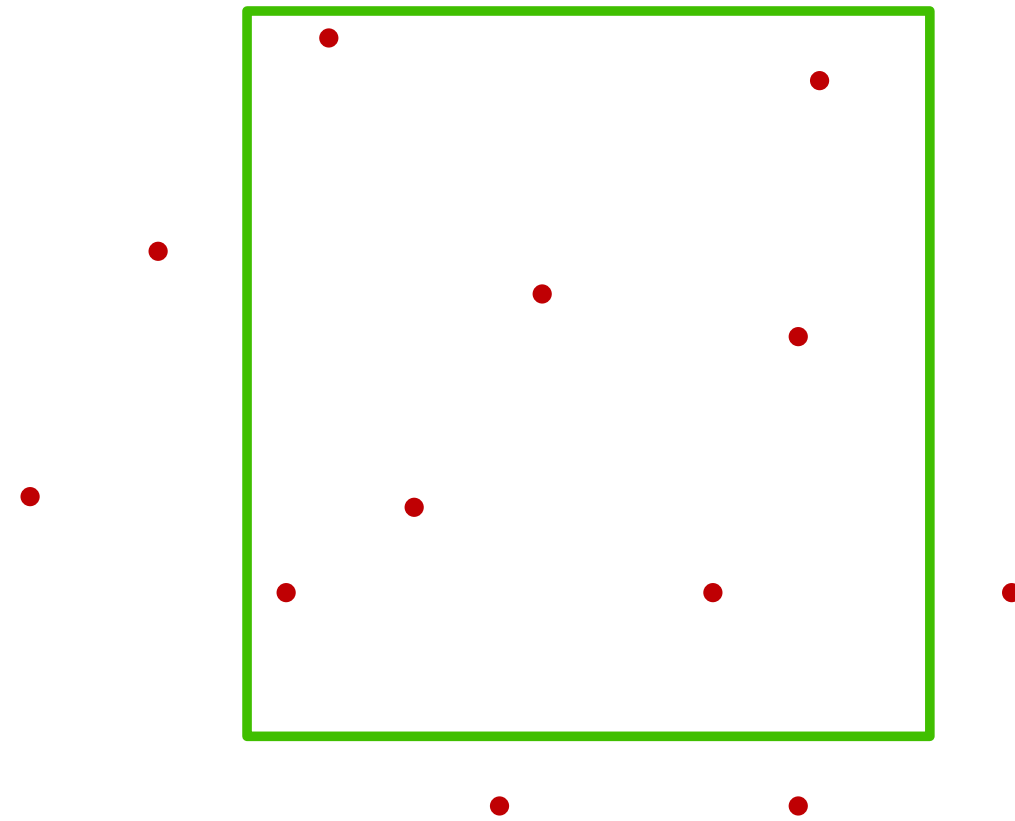
range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

What is its VC-dimension?

A 4

B 5

C ∞

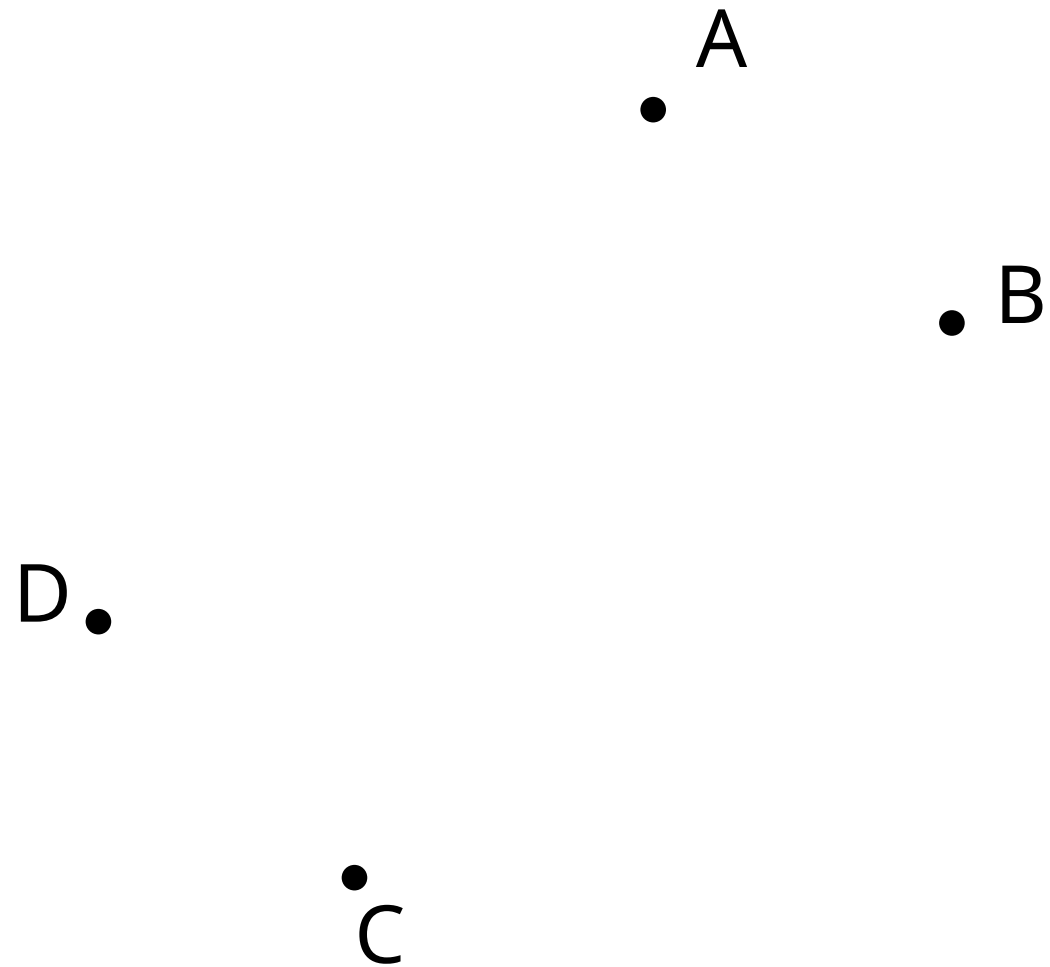


Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

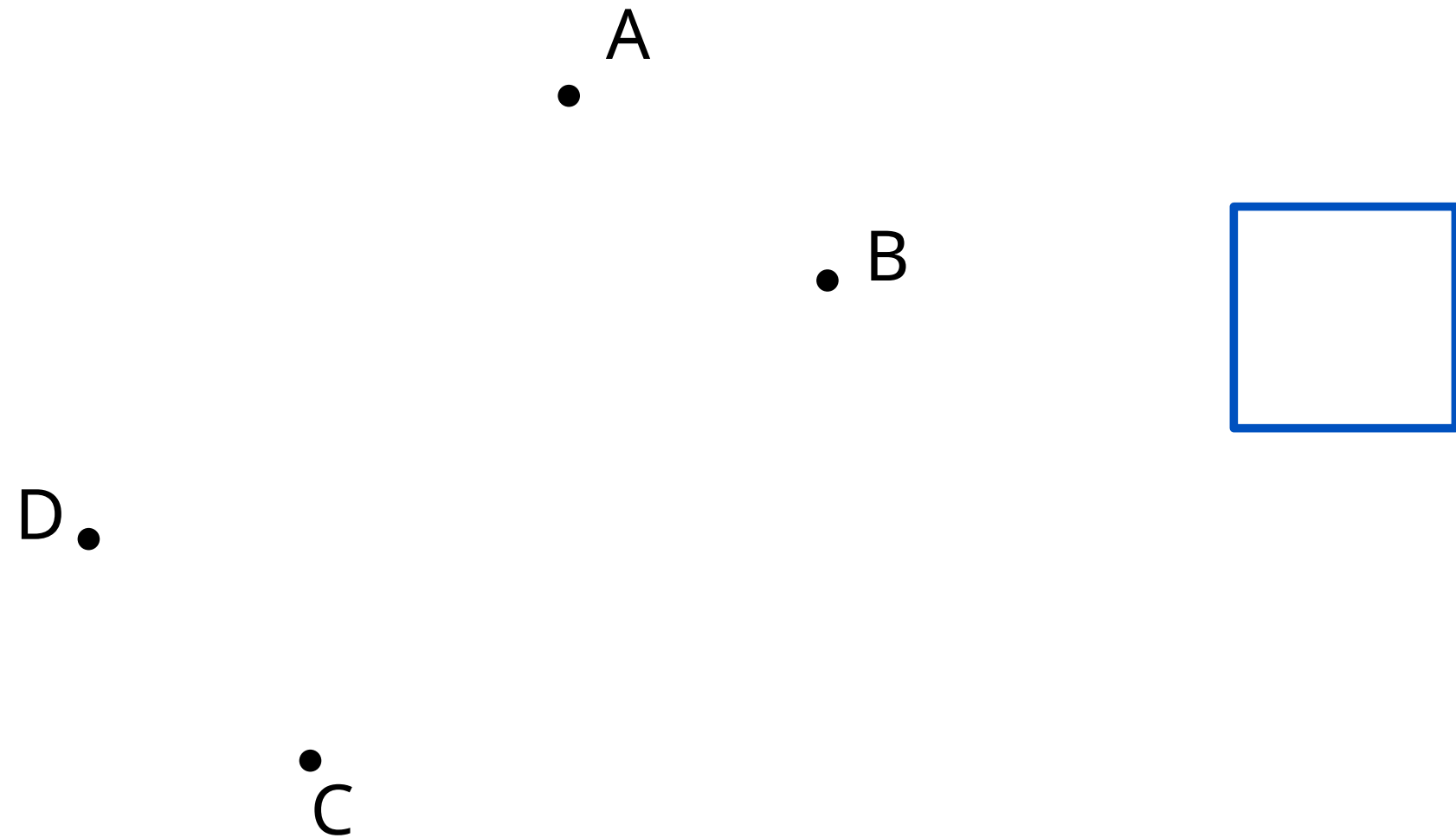
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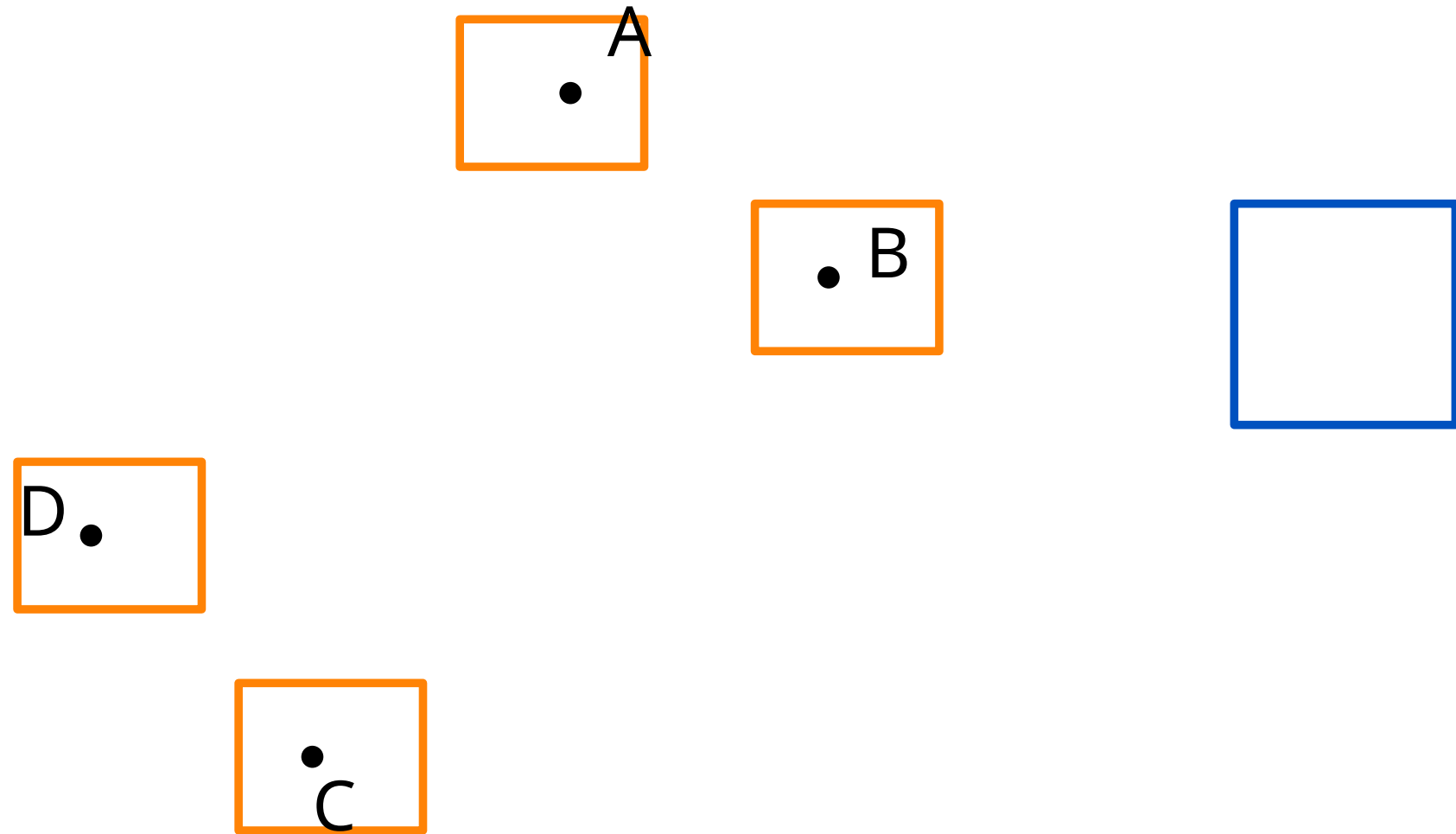
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



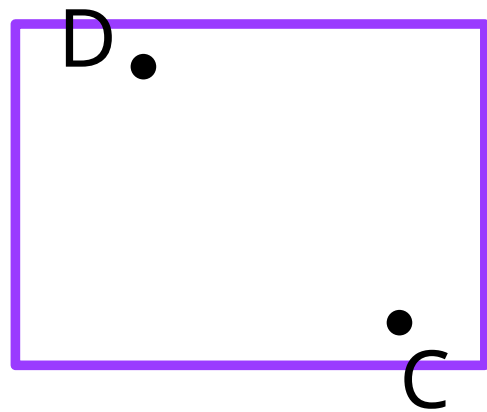
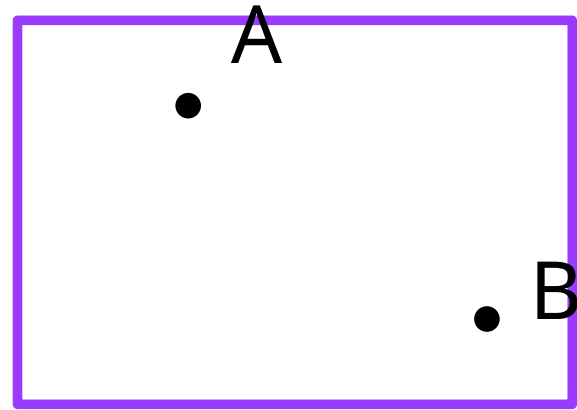
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



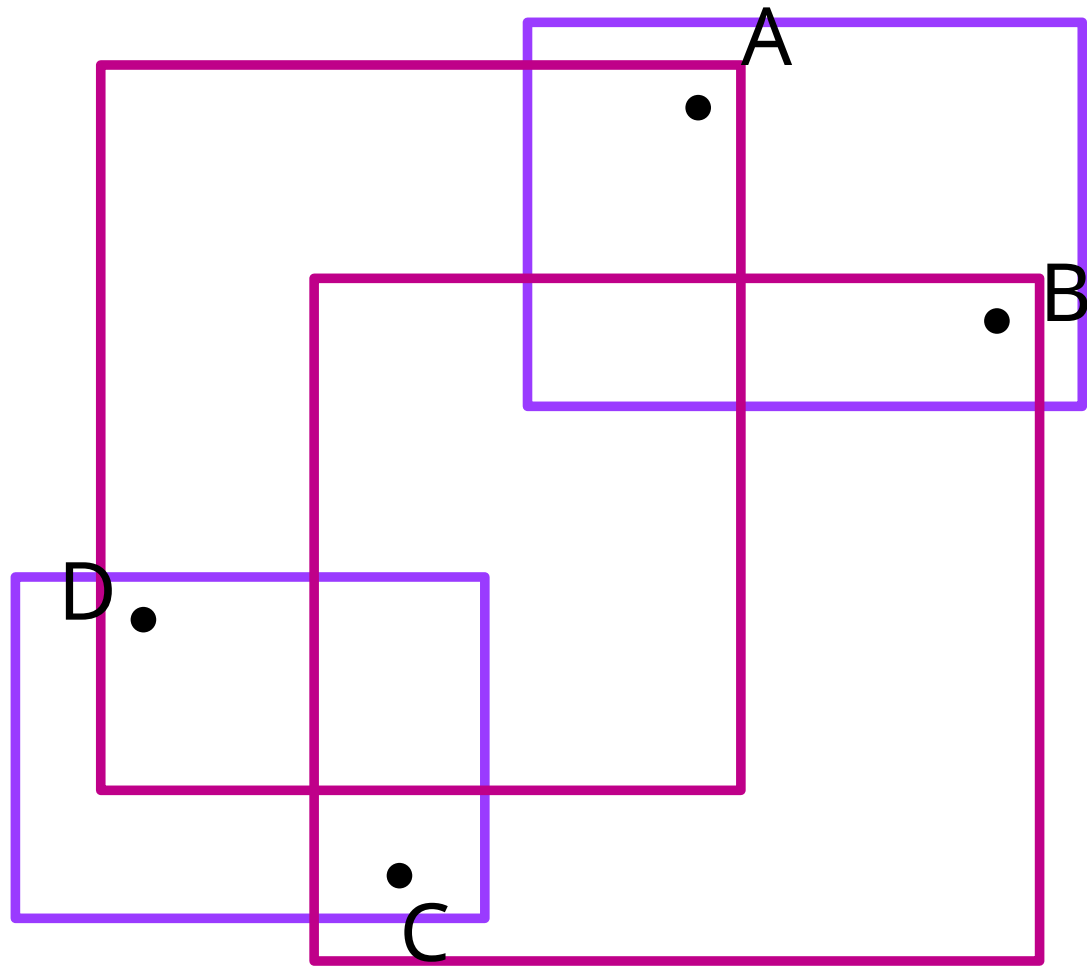
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range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



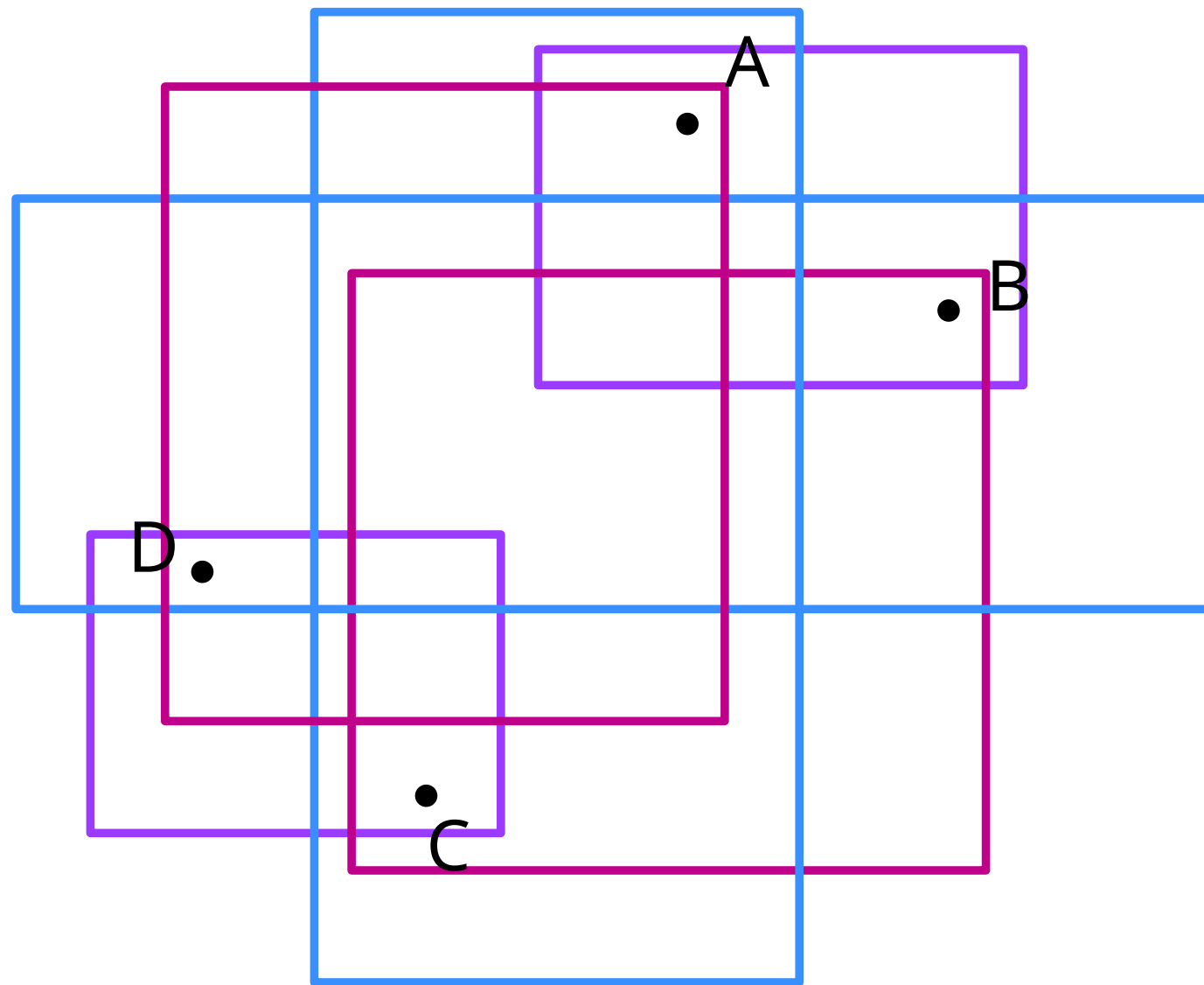
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range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



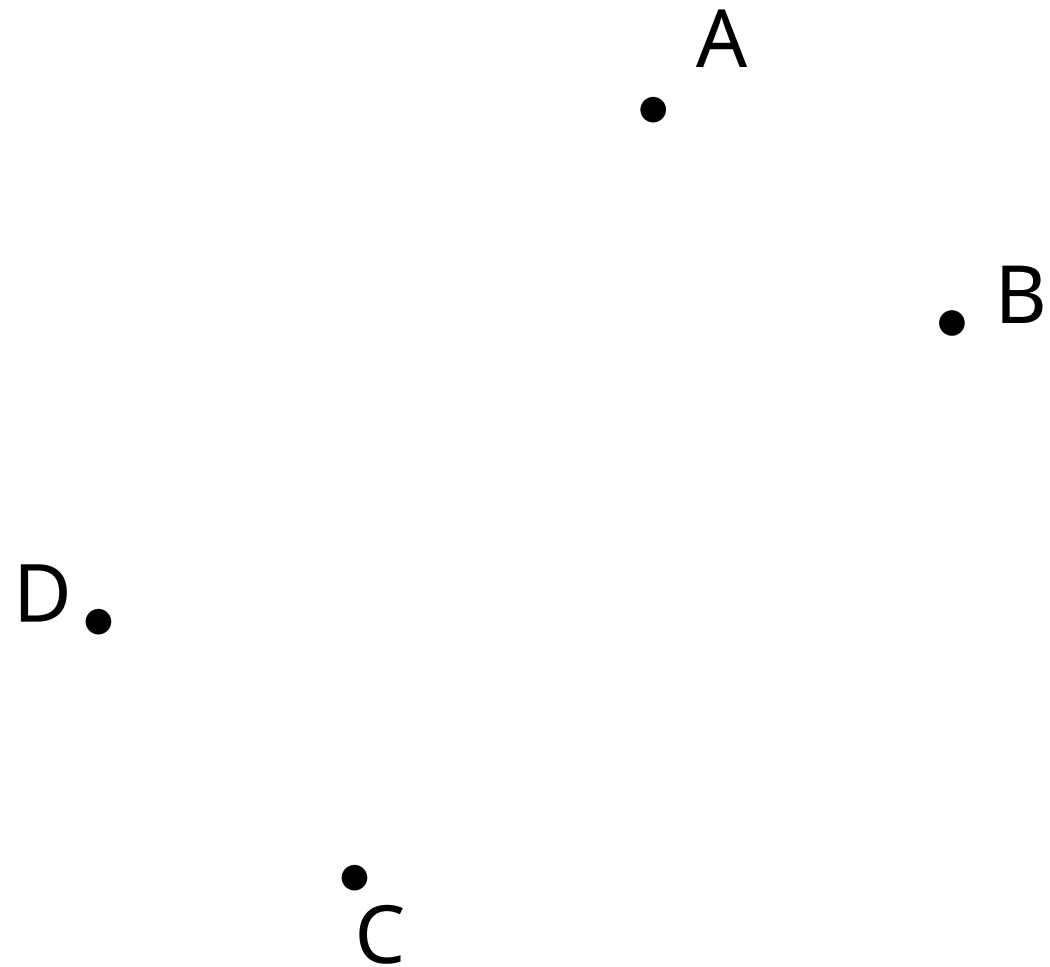
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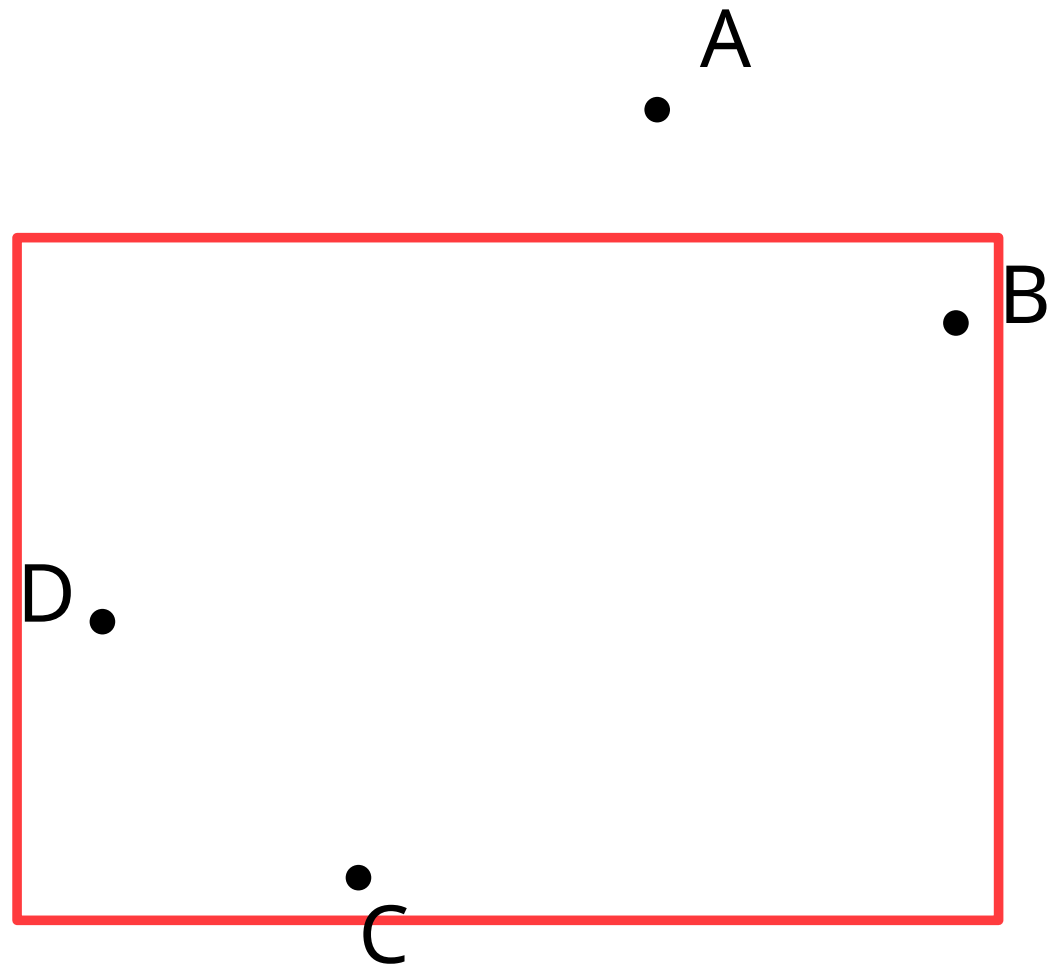
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range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



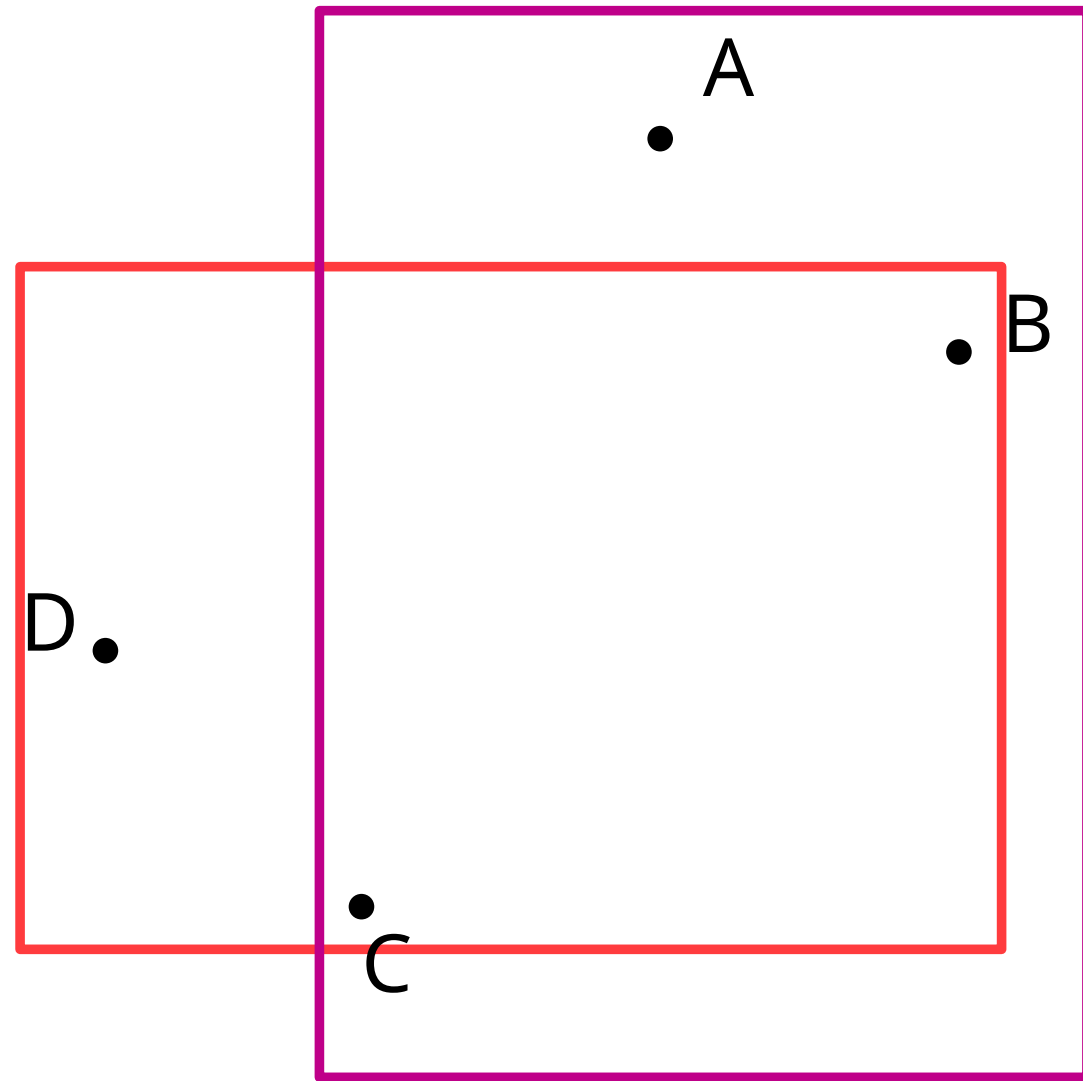
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



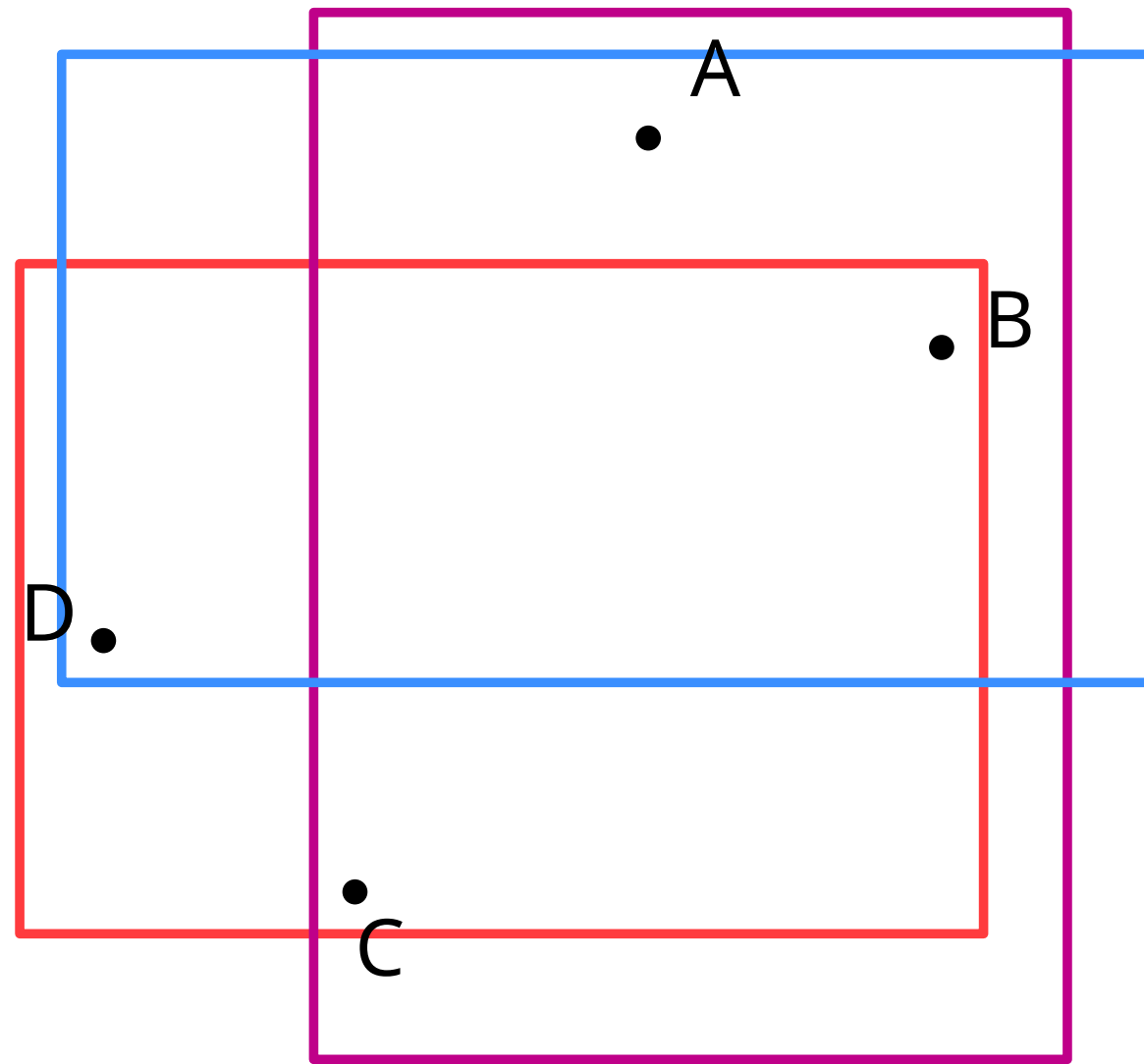
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



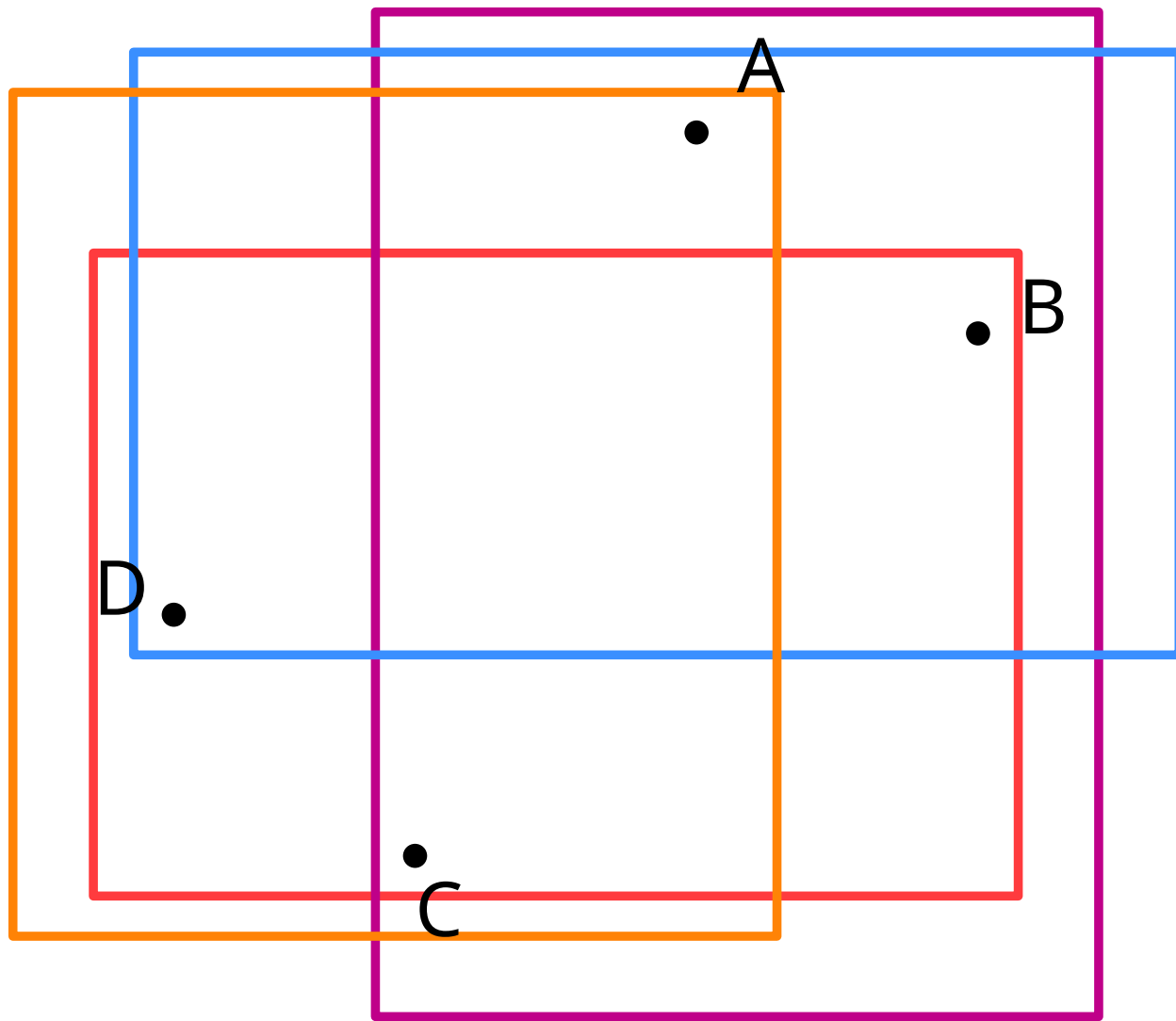
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



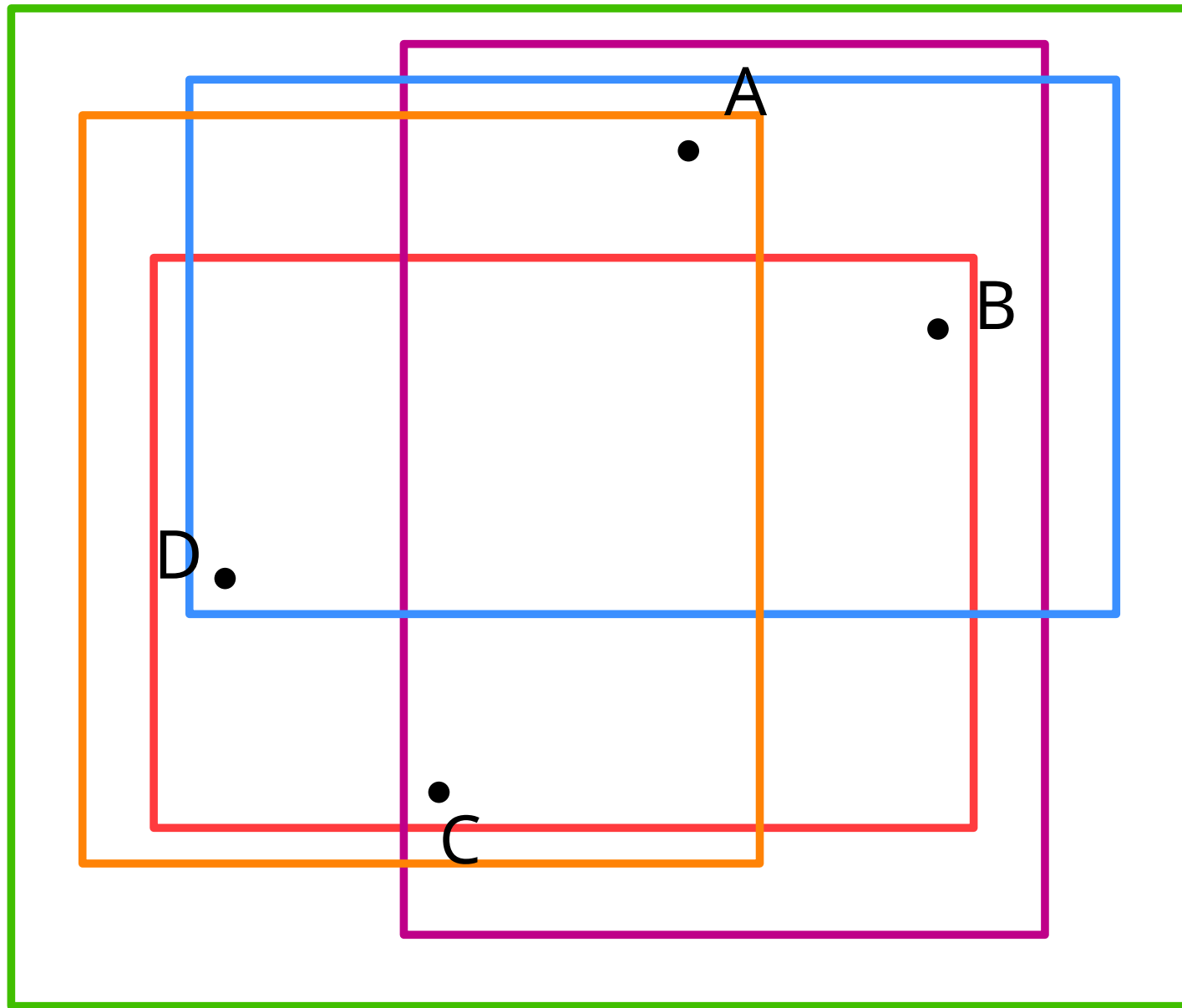
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



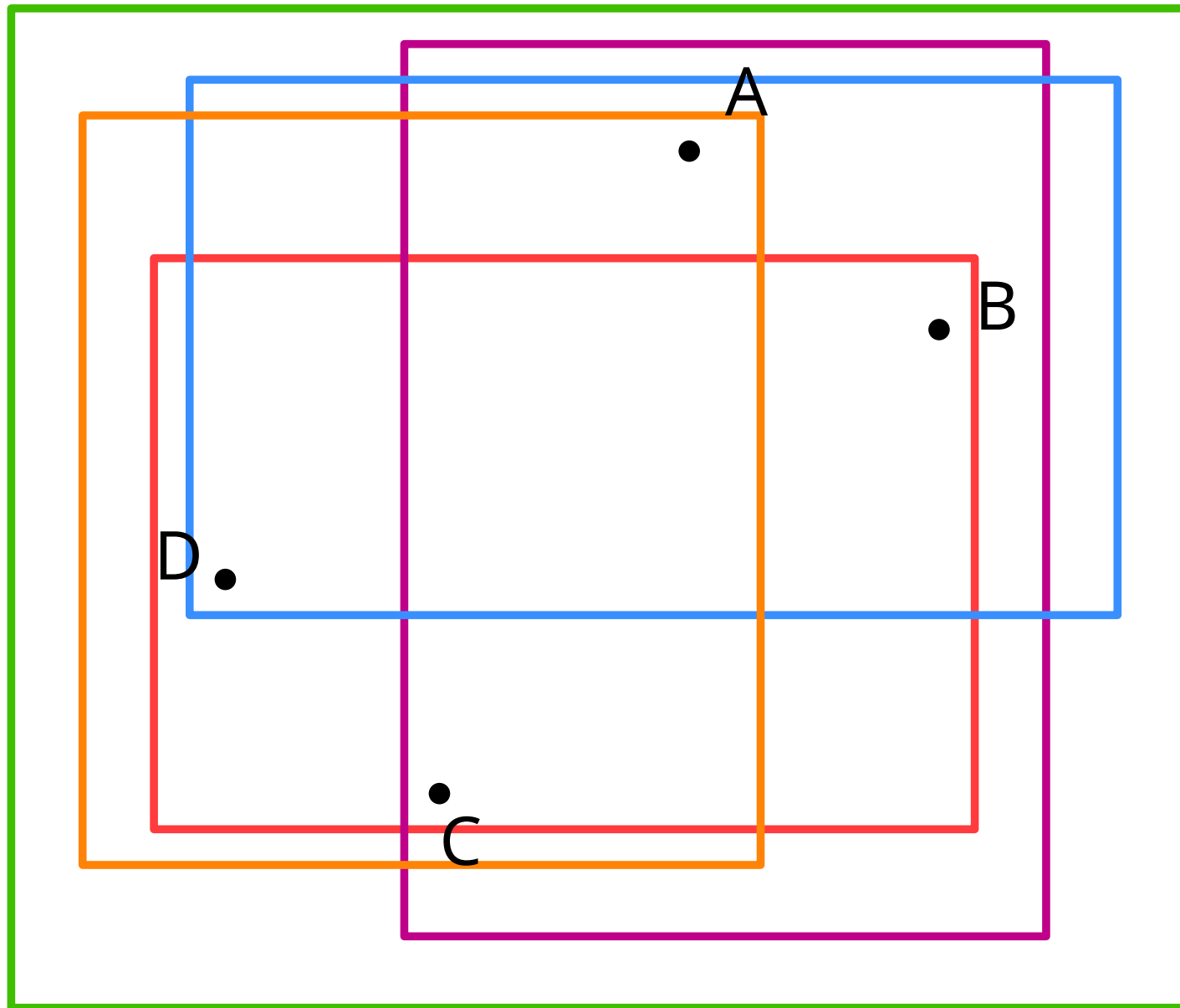
Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



Example: rectangles as ranges

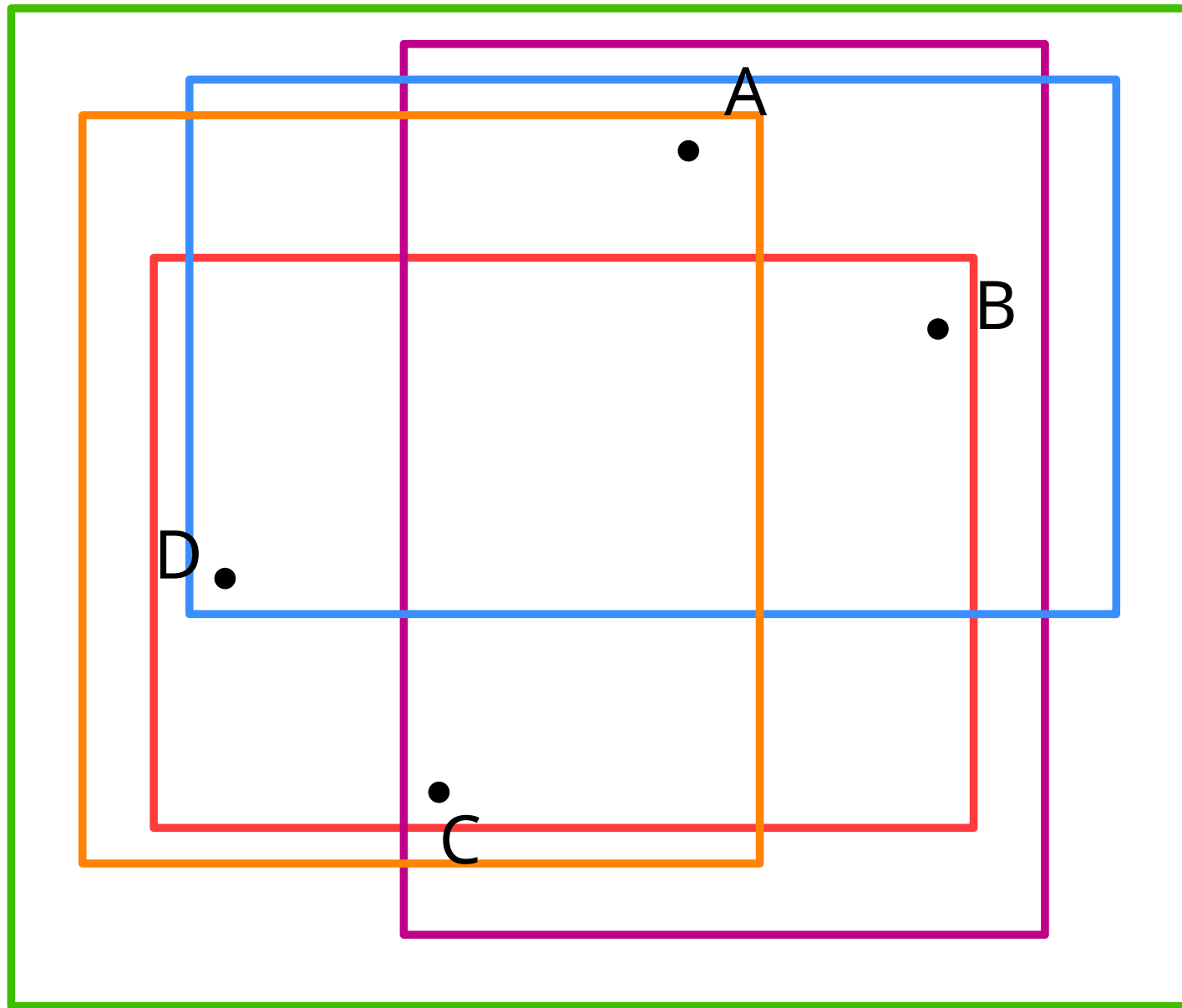
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shattered !

Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



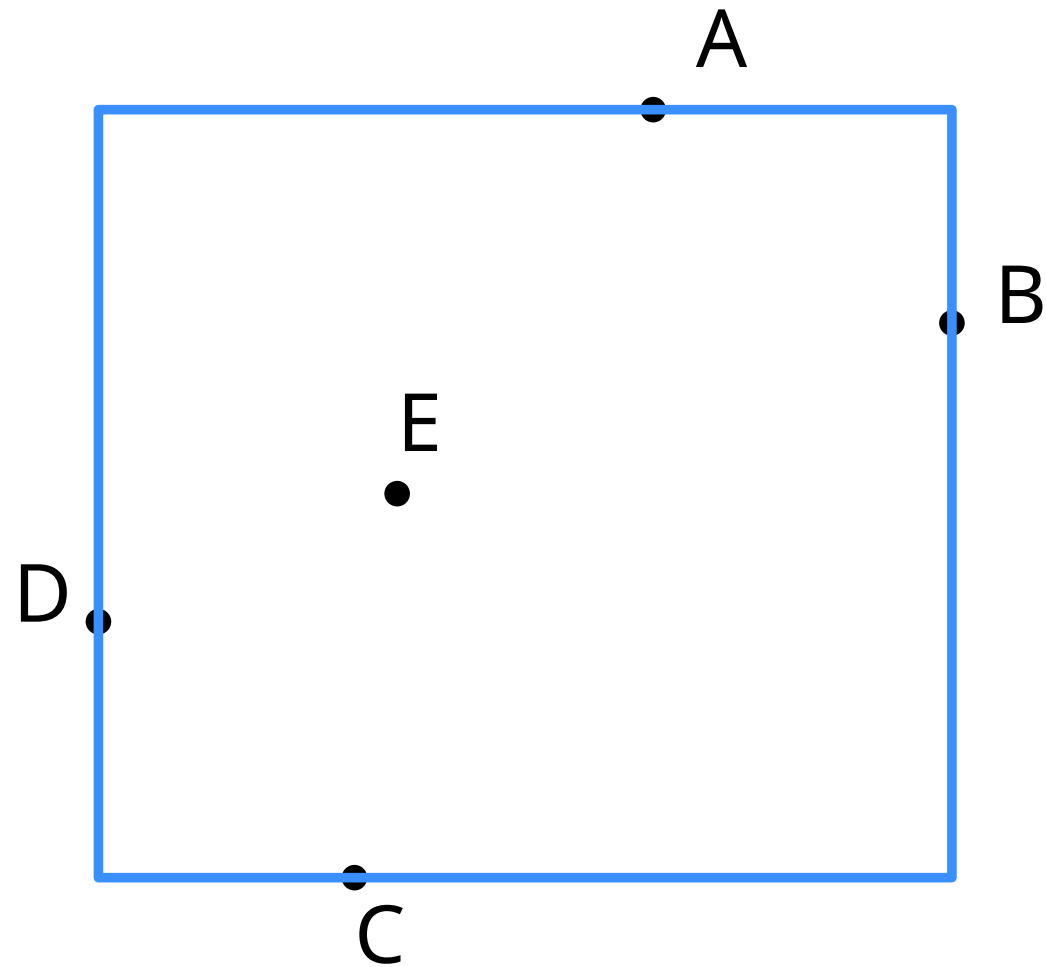
\Rightarrow VC-dimension ≥ 4

shattered !

Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

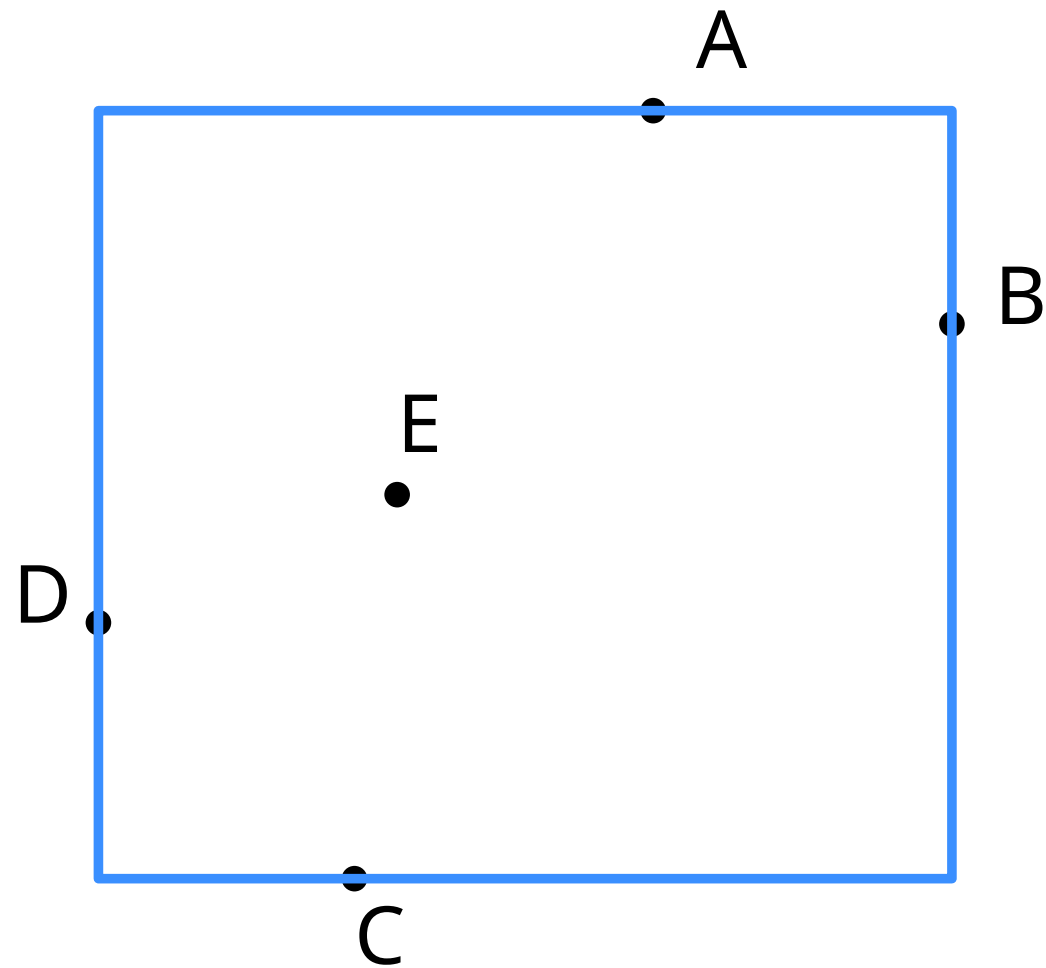
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Example: rectangles as ranges

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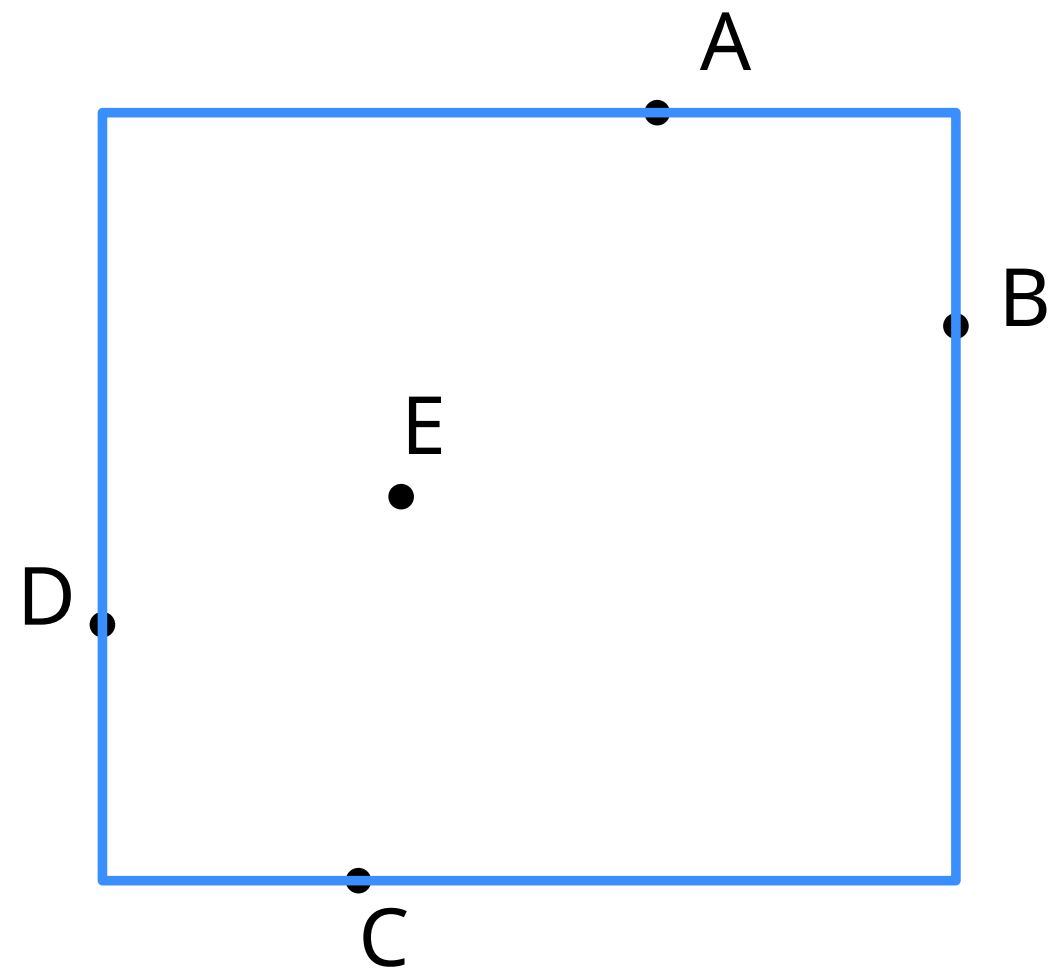
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not shatter !

Example: rectangles as ranges

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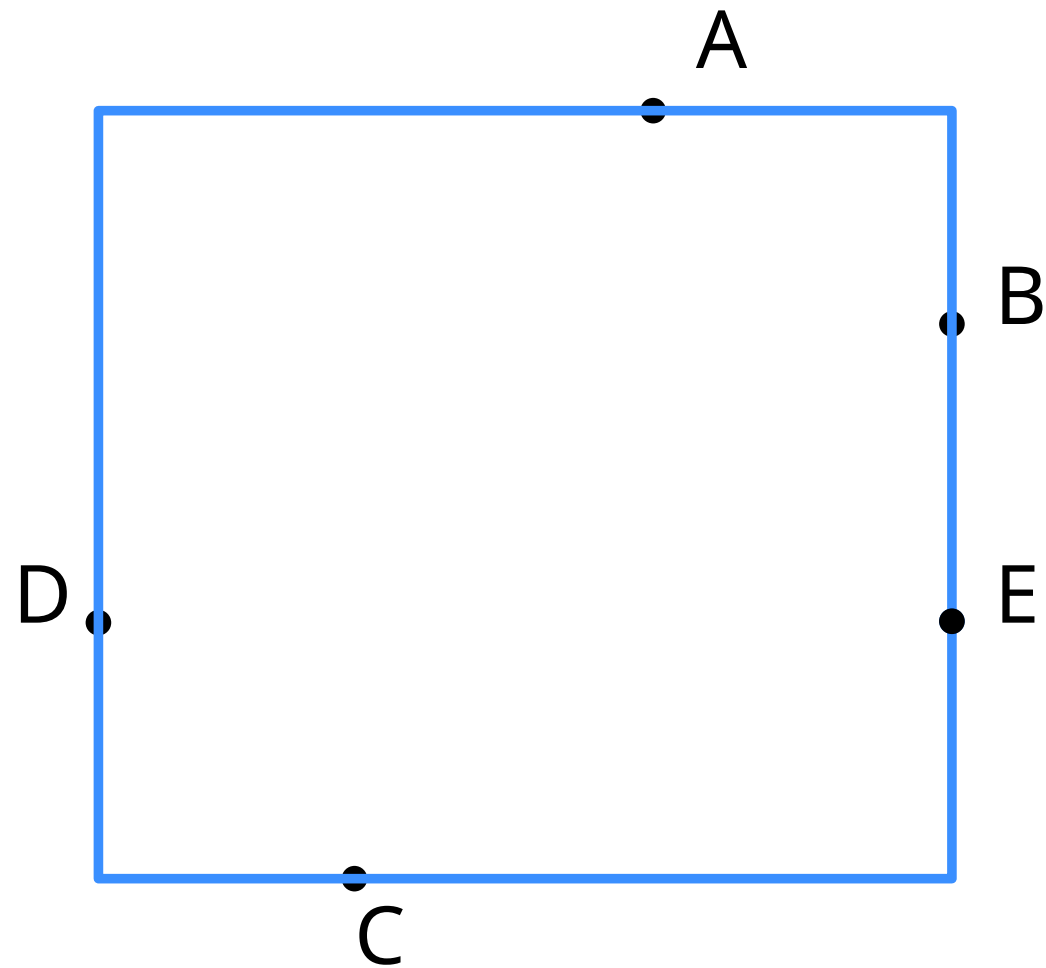
\Rightarrow VC-dimension ≥ 4

case 1: ≥ 1 point inside bounding rectangle

not shatter !

Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



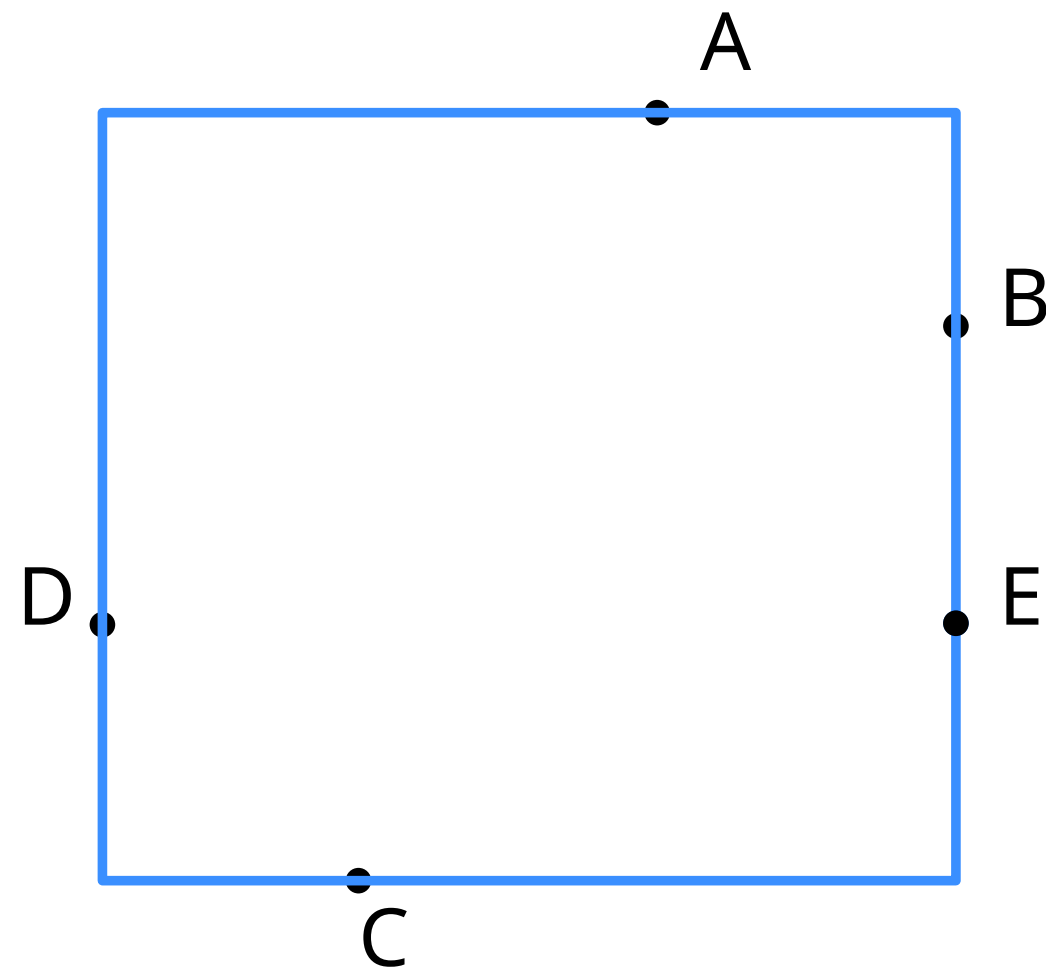
\Rightarrow VC-dimension ≥ 4

case 1: ≥ 1 point inside bounding rectangle

case 2: all points on bounding rectangle

Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



\Rightarrow VC-dimension ≥ 4

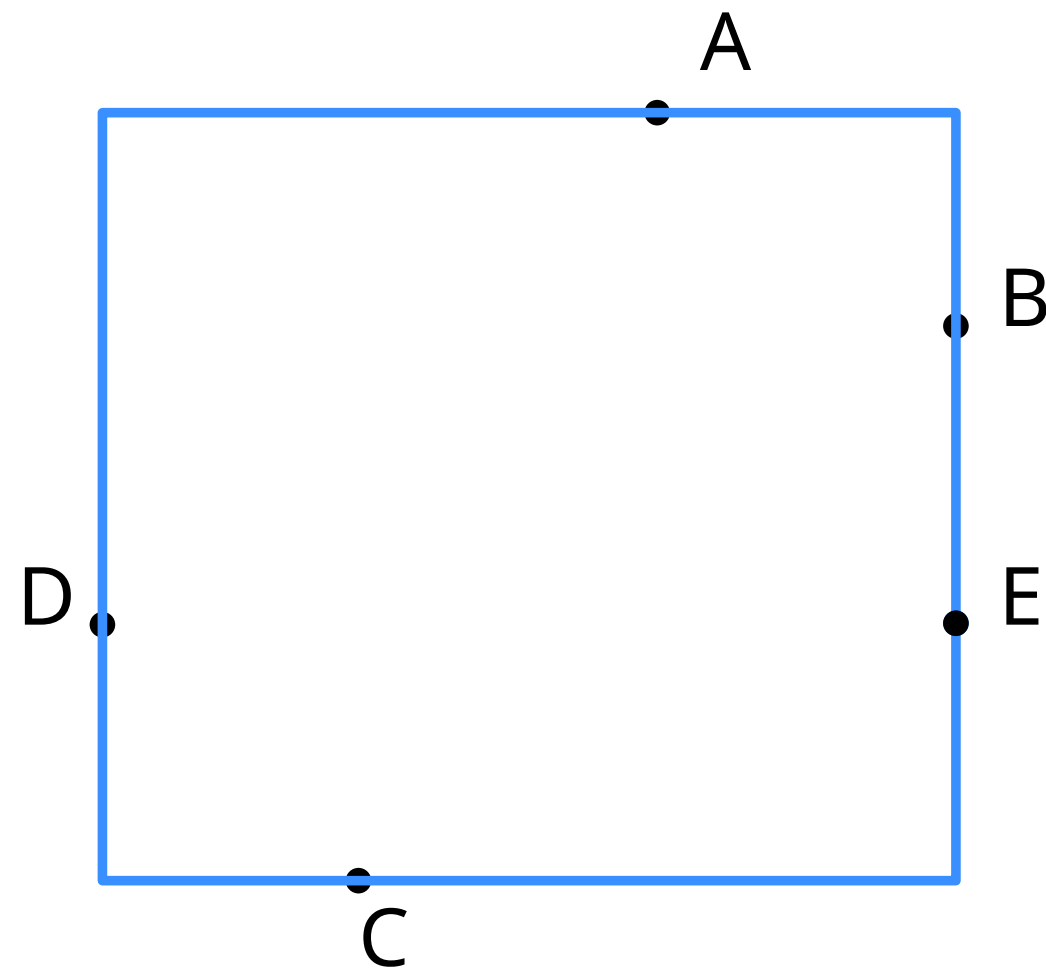
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not shatter !

Example: rectangles as ranges

range space $(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles



\Rightarrow VC-dimension ≥ 4

case 1: ≥ 1 point inside bounding rectangle

case 2: all points on bounding rectangle

\Rightarrow VC-dimension = 4

not shatter !

Summary: VC-dimension of geometric range spaces

range space

VC-dimension

$(\mathbb{R}, \mathcal{I})$, with \mathcal{I} = set of closed intervals

2

$(\mathbb{R}^2, \mathcal{D})$, with \mathcal{D} = set of disks

3

$(\mathbb{R}^2, \mathcal{AR})$, with \mathcal{AR} = set of axis-aligned rectangles

4

$(\mathbb{R}^2, \mathcal{GR})$, with \mathcal{GR} = set of arbitrary oriented rectangles

? ≥ 4

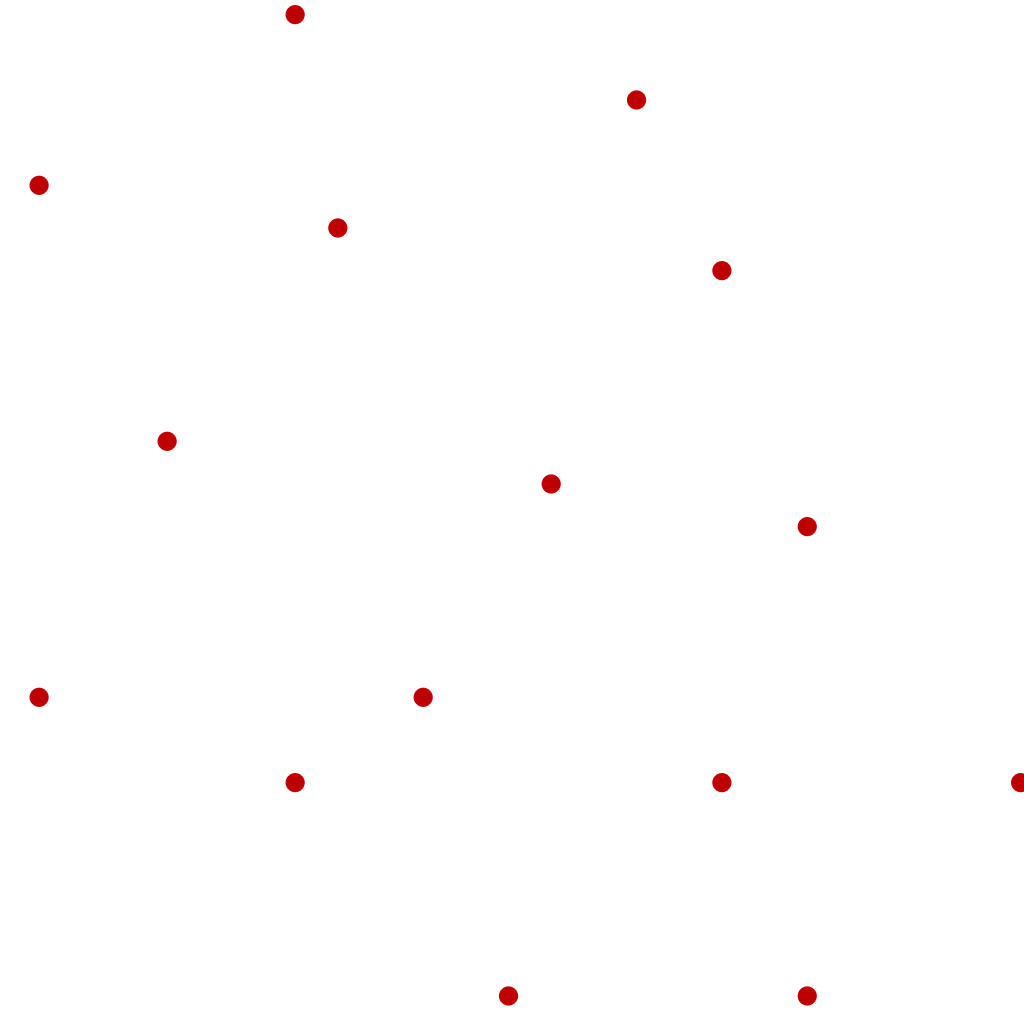
$(\mathbb{R}^2, \mathcal{C})$, with \mathcal{C} = set of closed convex sets

∞

ε -samples

Measure and Estimate

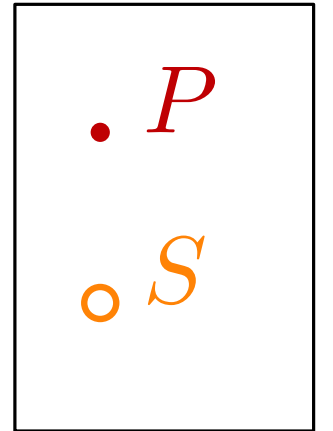
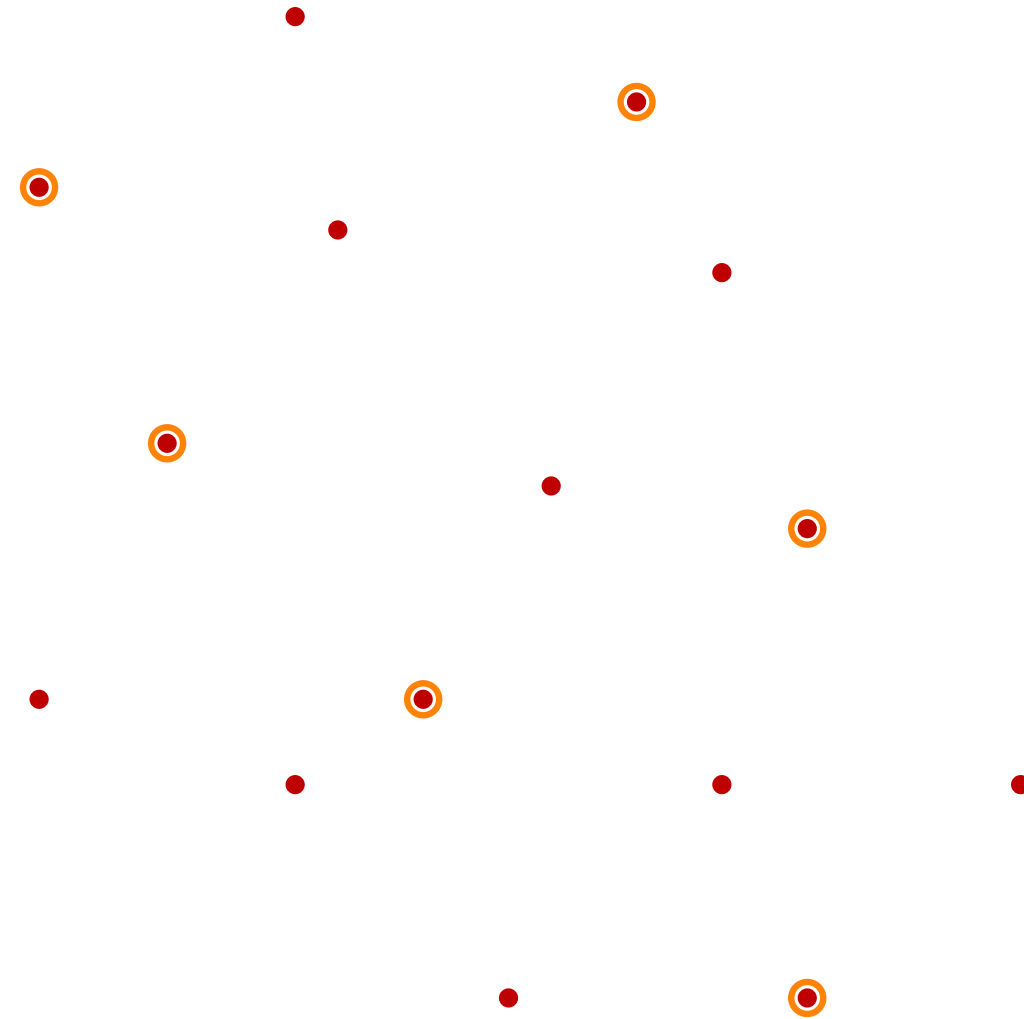
$$\text{Measure: } \mu(r) = \frac{|r \cap P|}{|P|}$$



Measure and Estimate

$$\text{Measure: } \mu(r) = \frac{|r \cap P|}{|P|}$$

$$\text{Estimate: } \hat{\mu}(r) = \frac{|r \cap S|}{|S|}$$



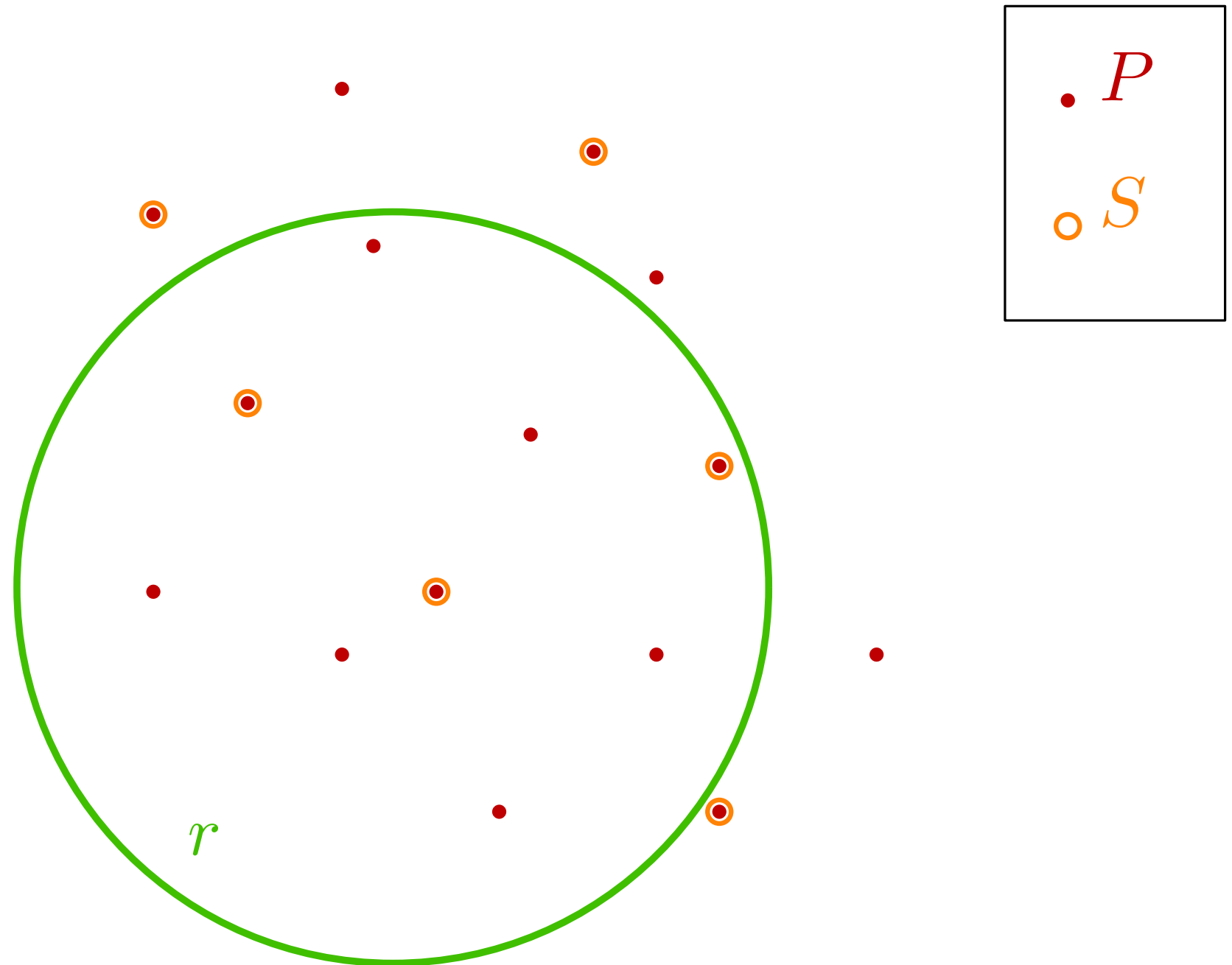
Measure and Estimate

$$\text{Measure: } \mu(r) = \frac{|r \cap P|}{|P|}$$

$$\mu(Q) = \frac{9}{15} = 0.6$$

$$\text{Estimate: } \hat{\mu}(r) = \frac{|r \cap S|}{|S|}$$

$$\hat{\mu}(Q) = \frac{3}{6} = 0.5$$



Measure and Estimate

$$\text{Measure: } \mu(r) = \frac{|r \cap P|}{|P|}$$

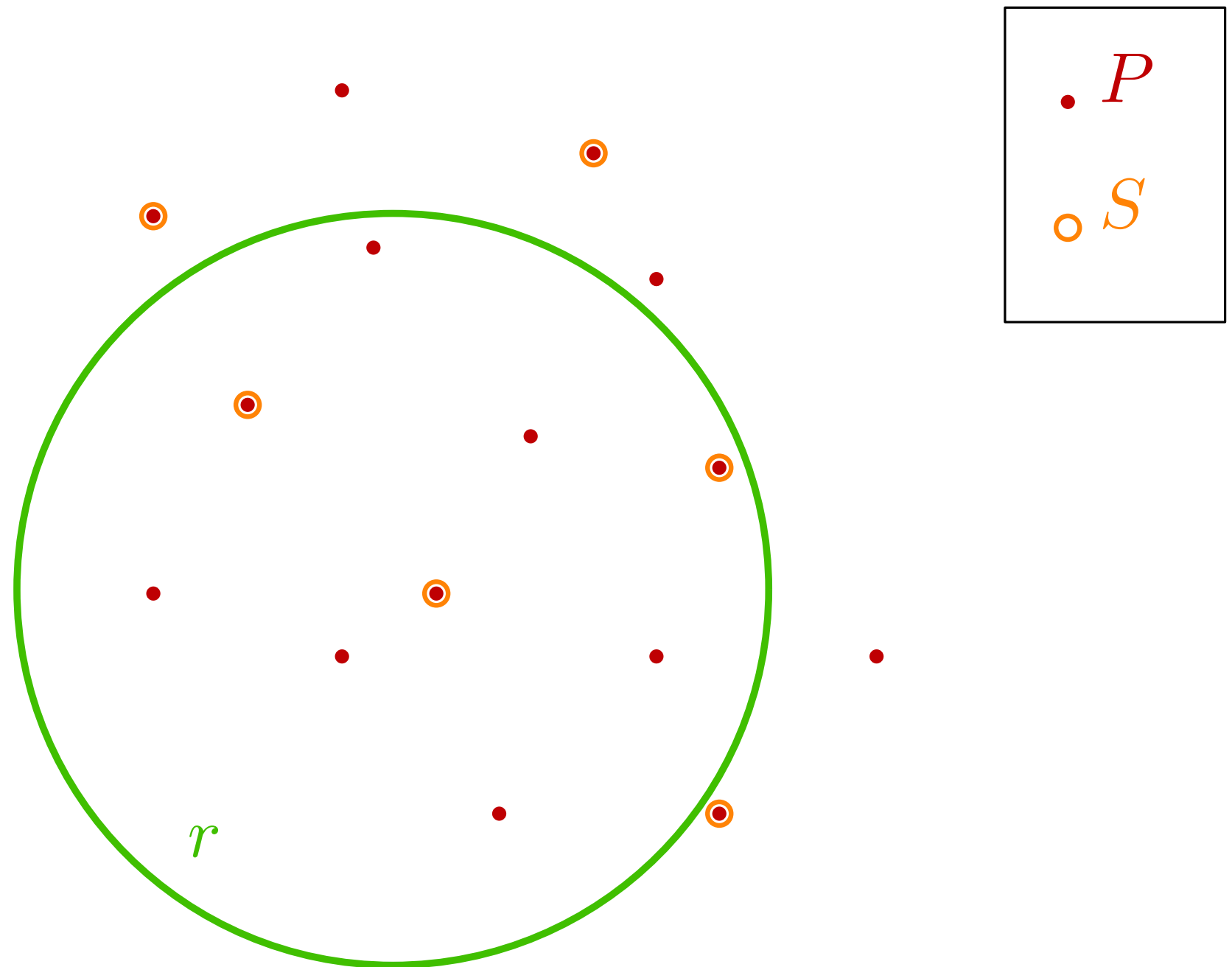
$$\mu(Q) = \frac{9}{15} = 0.6$$

$$\text{Estimate: } \hat{\mu}(r) = \frac{|r \cap S|}{|S|}$$

$$\hat{\mu}(Q) = \frac{3}{6} = 0.5$$

Good Sample S :

for all $r \in \mathcal{R}$, $\hat{\mu}(r) \approx \mu(r)$



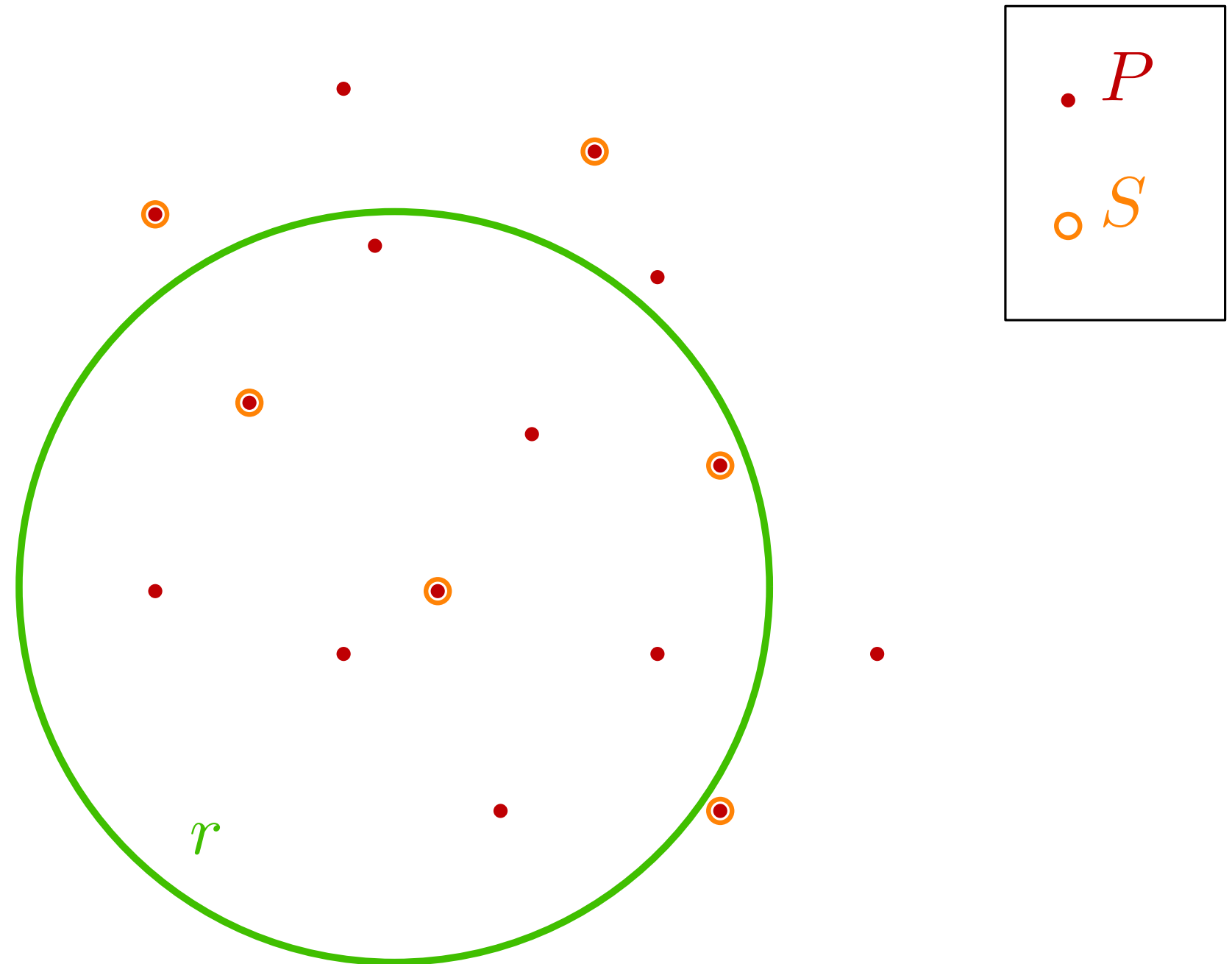
ε -samples

ε -sample S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

$$|\mu(r) - \hat{\mu}(r)| \leq \varepsilon$$



ε -samples

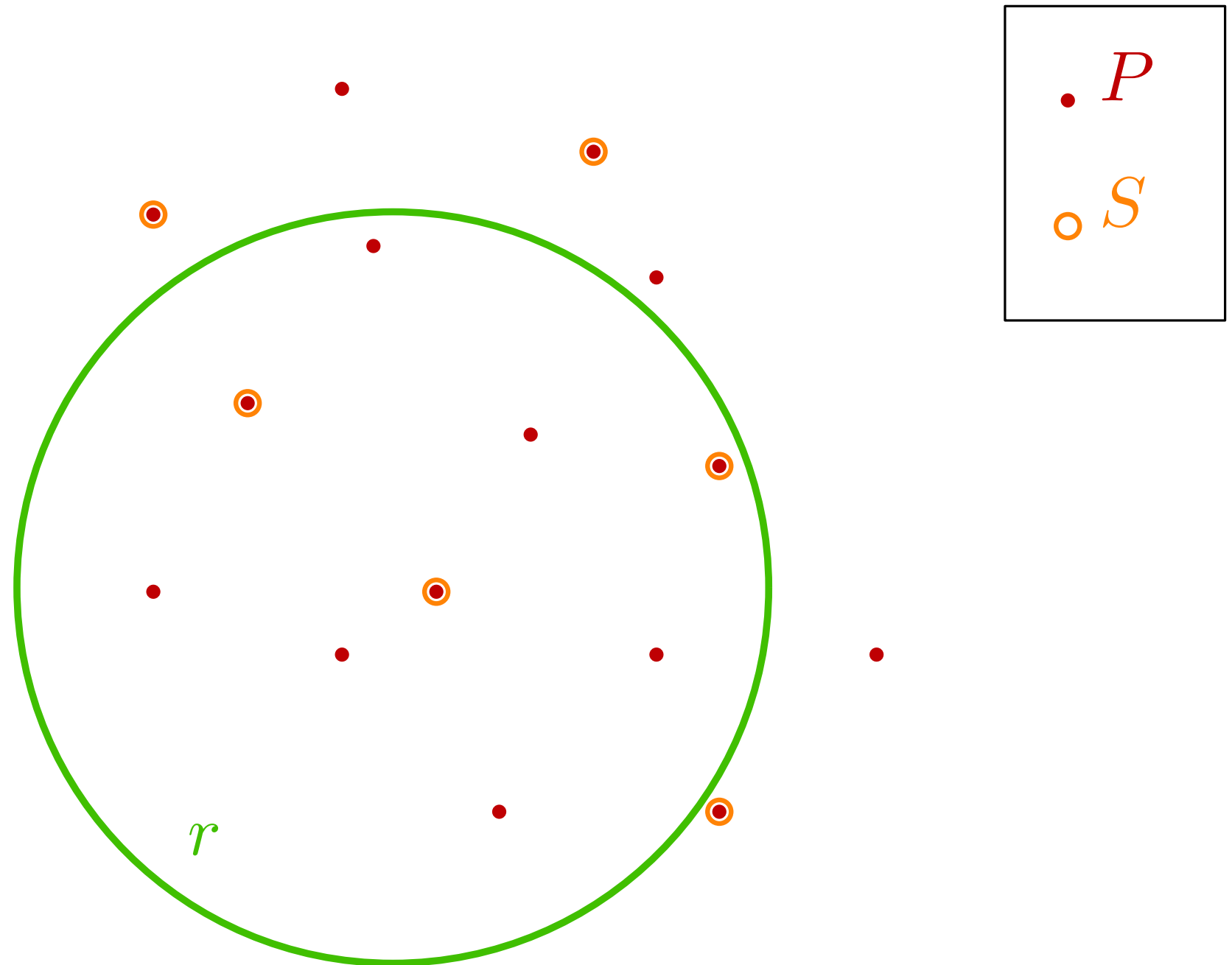
ε -sample S :

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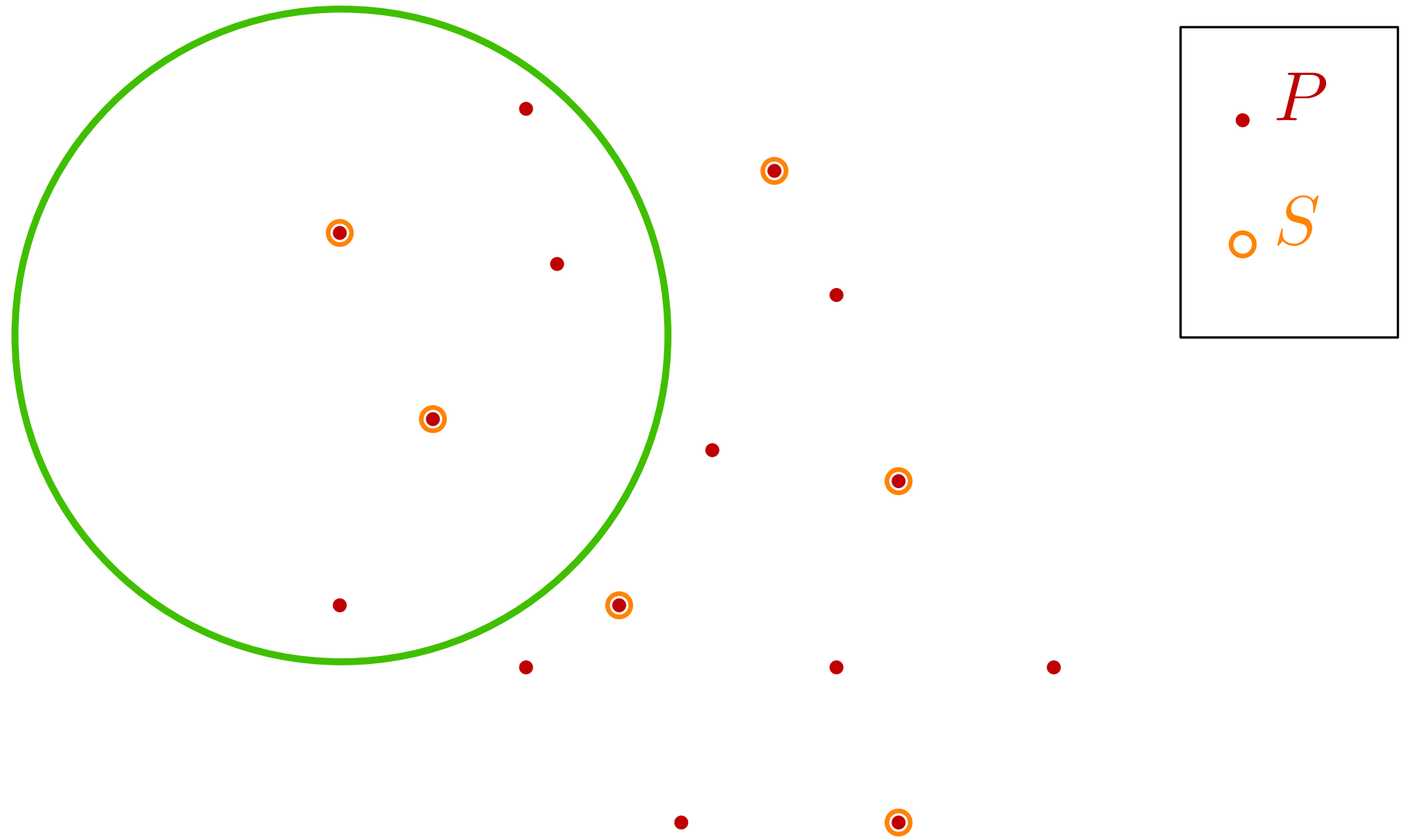
$$|\mu(r) - \hat{\mu}(r)| \leq \varepsilon$$

$$\begin{aligned} |\mu(r) - \hat{\mu}(r)| &= |9/15 - 3/6| \\ &= 0.1 \end{aligned}$$



Quiz

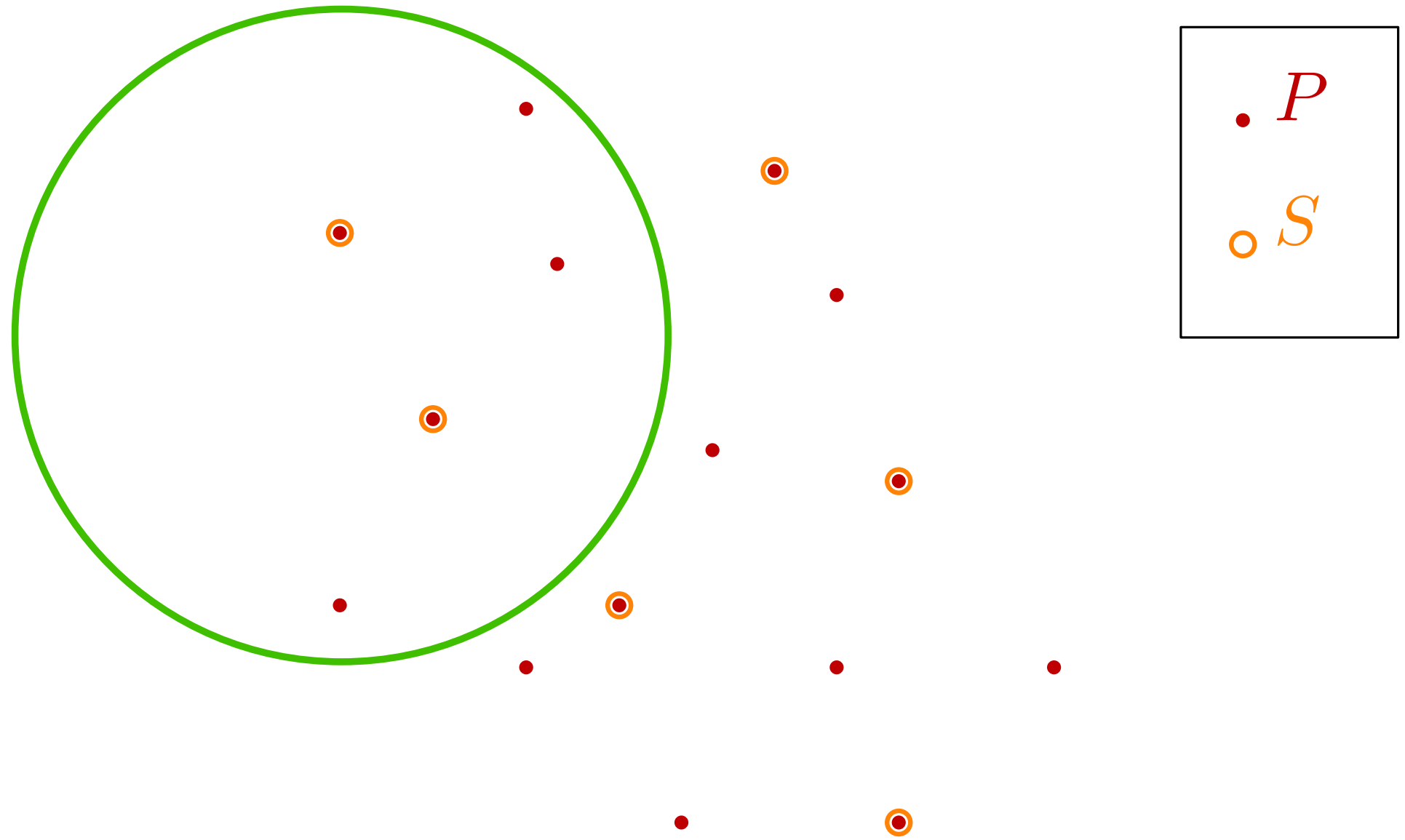
$$|\mu(r) - \hat{\mu}(r)| = \dots ?$$



- A 0.0
- B 0.1
- C 0.2
- D none of the above

Quiz

$$|\mu(r) - \hat{\mu}(r)| = \dots ?$$



- A 0.0 $\frac{2}{6} = \frac{5}{15}$
- B 0.1
- C 0.2
- D none of the above

ε -sample theorem

Let $\varphi, \varepsilon > 0$ be parameters and (X, \mathcal{R}) be a range space with finite X and VC-dimension δ . A sample of size

$$O\left(\frac{1}{\varepsilon^2} (\delta + \log \varphi^{-1})\right)$$

is an ε -sample for (X, \mathcal{R}) with probability $\geq 1 - \varphi$

(we skip the proof)

Example from motivation

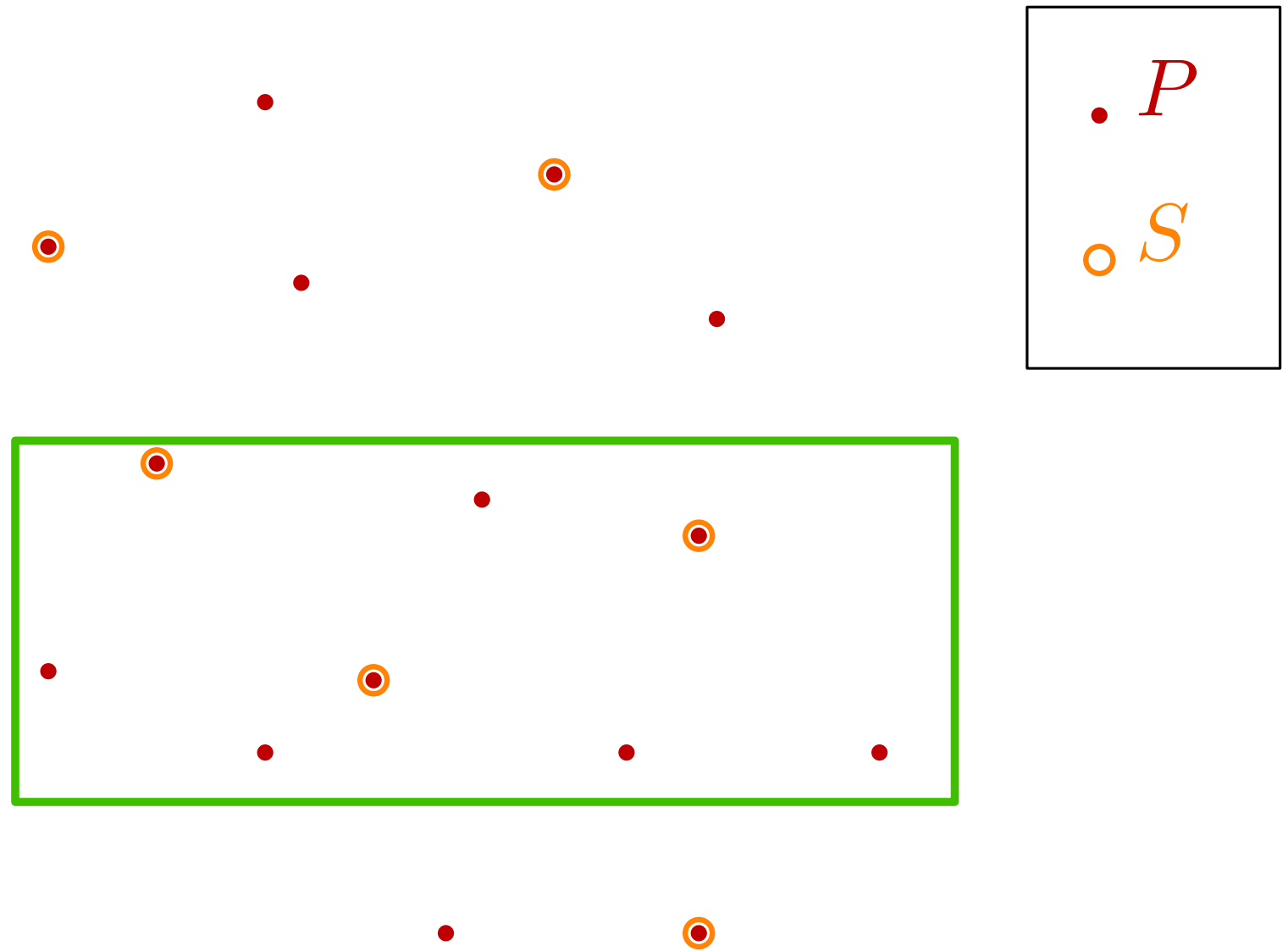
Given P ,

how many points do we need to sample ($S \subset P$), such that

2. for any query rectangle r

$$\left| \frac{|r \cap P|}{|P|} - \frac{|r \cap S|}{|S|} \right| \leq 0.25 \quad ?$$

with probability 0.999



Example from motivation

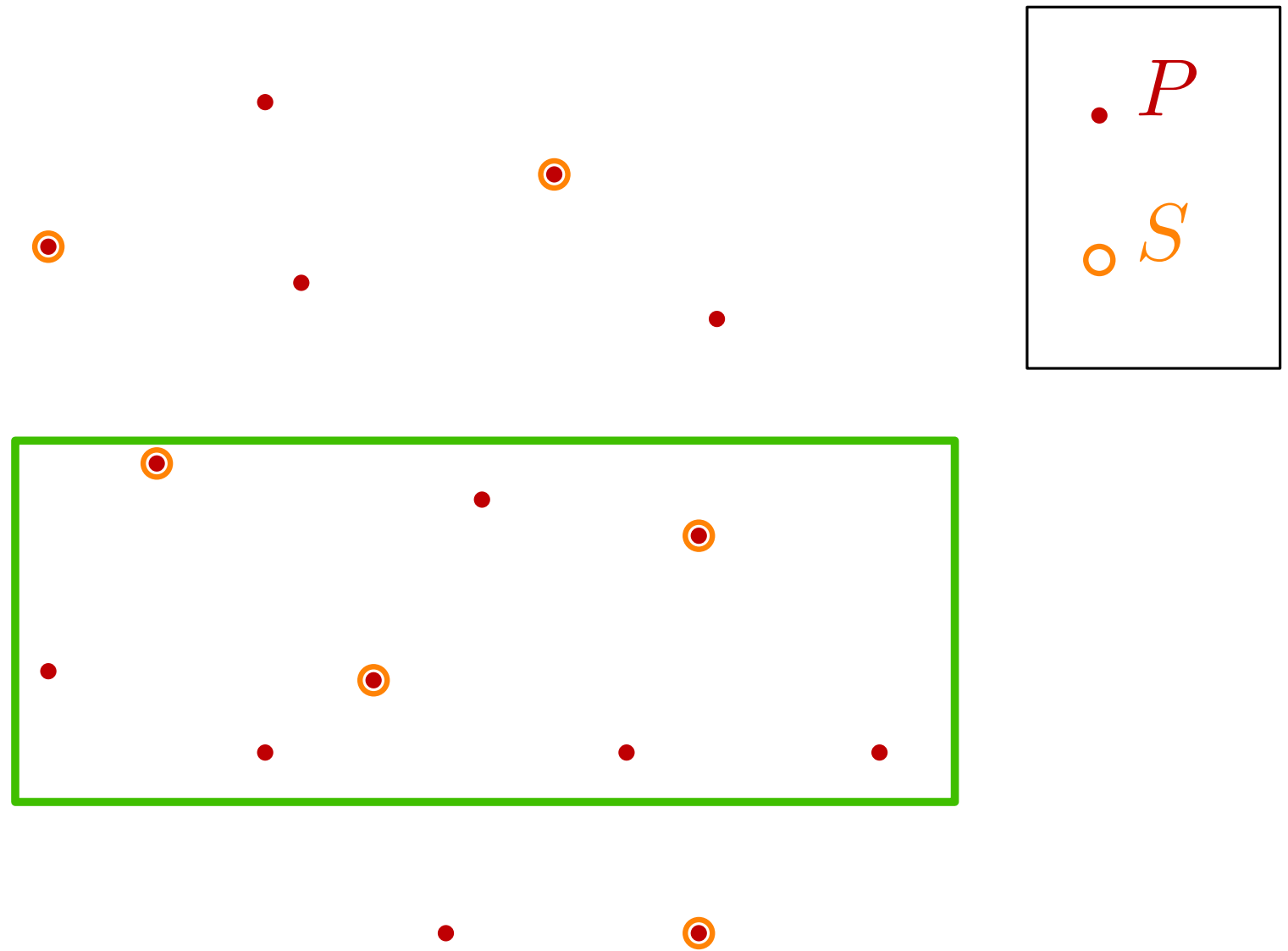
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$$\left| \frac{|r \cap P|}{|P|} - \frac{|r \cap S|}{|S|} \right| \leq 0.25 \boxed{= \varepsilon} ?$$

with probability 0.999



Example from motivation

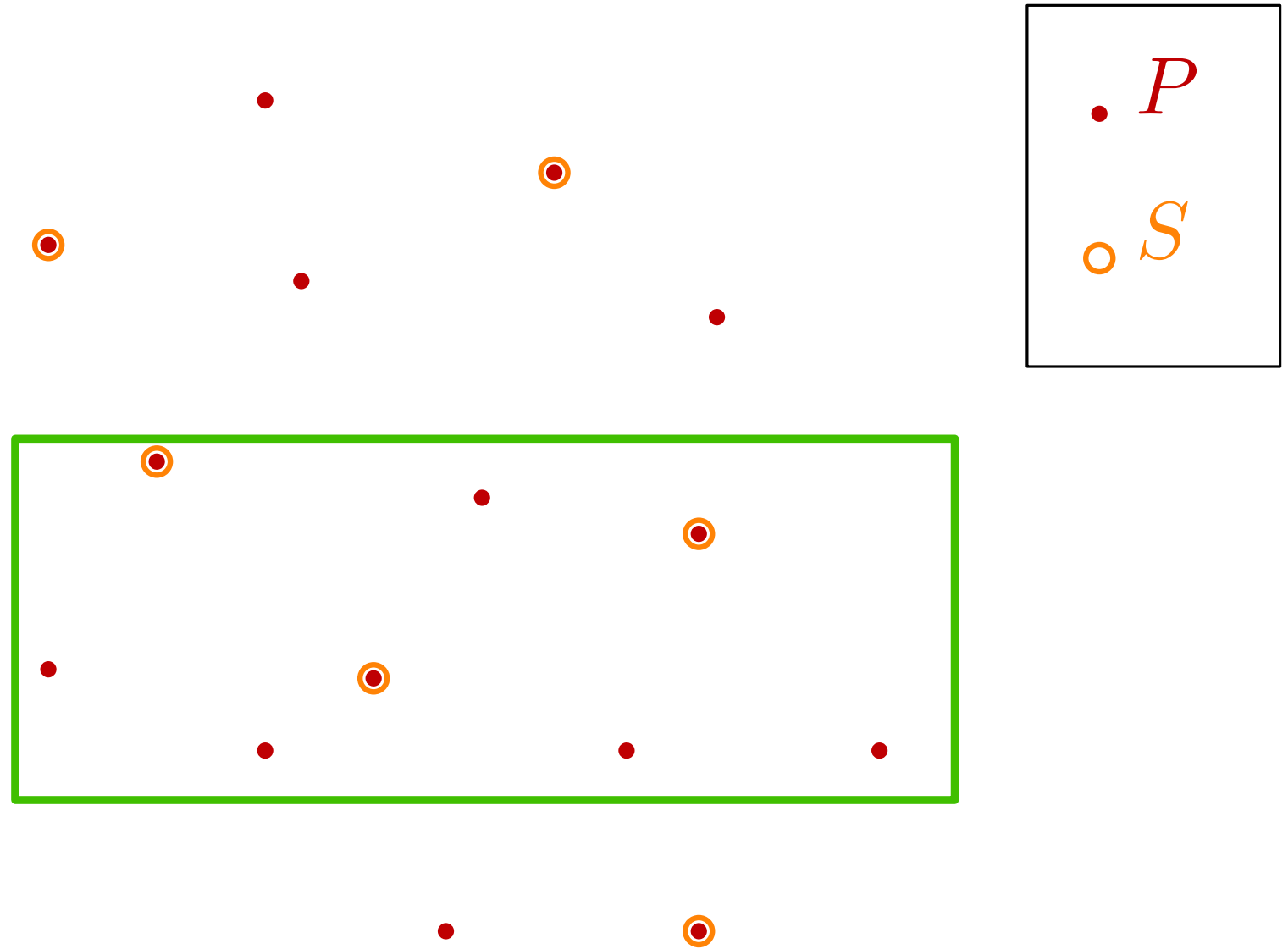
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$$\left| \frac{|r \cap P|}{|P|} - \frac{|r \cap S|}{|S|} \right| \leq 0.25 = \varepsilon?$$

with probability $0.999 = 1 - \varphi$



Example from motivation

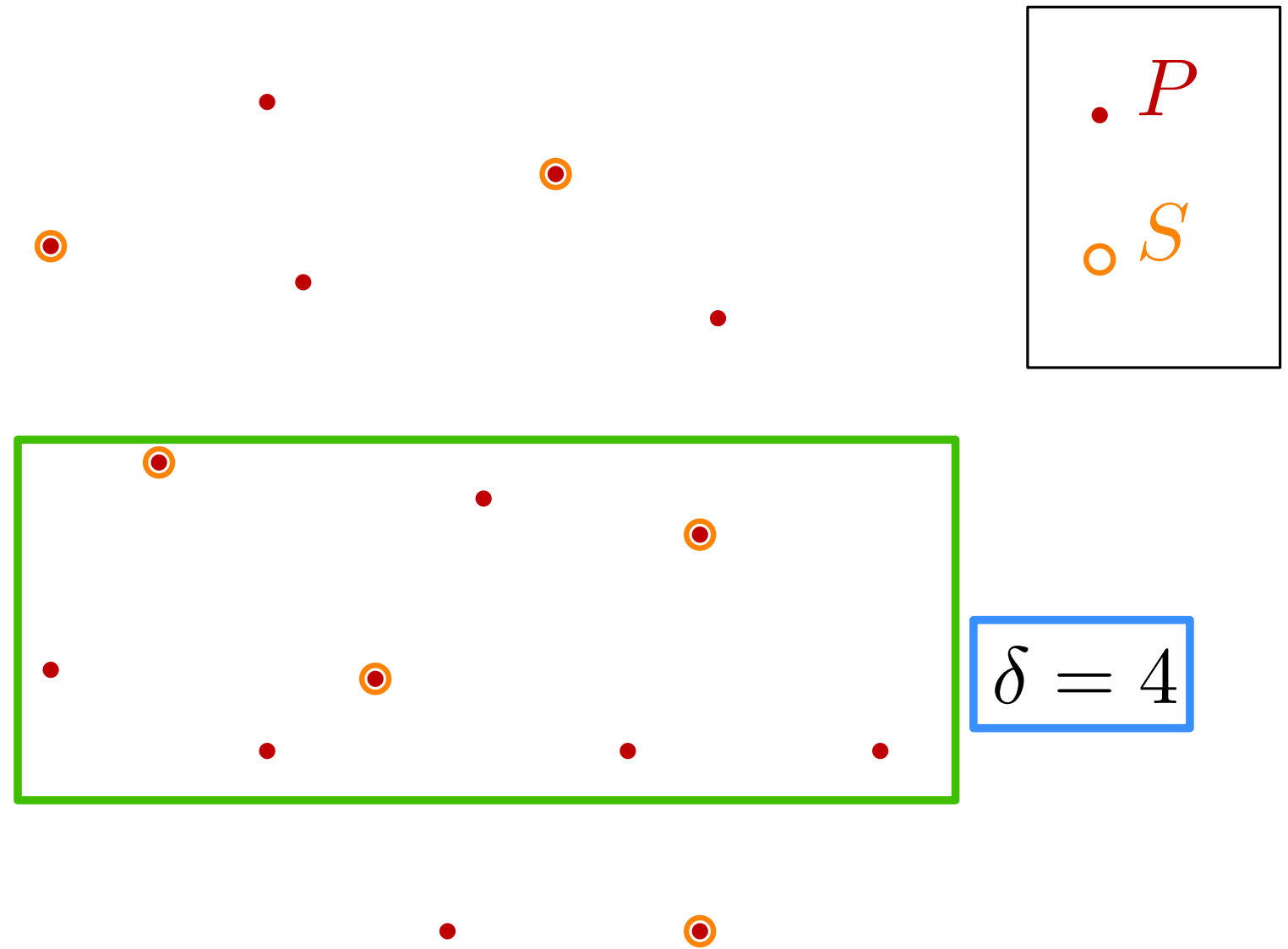
Given P ,

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$$\left| \frac{|r \cap P|}{|P|} - \frac{|r \cap S|}{|S|} \right| \leq 0.25 = \varepsilon?$$

with probability $0.999 = 1 - \varphi$



Example from motivation

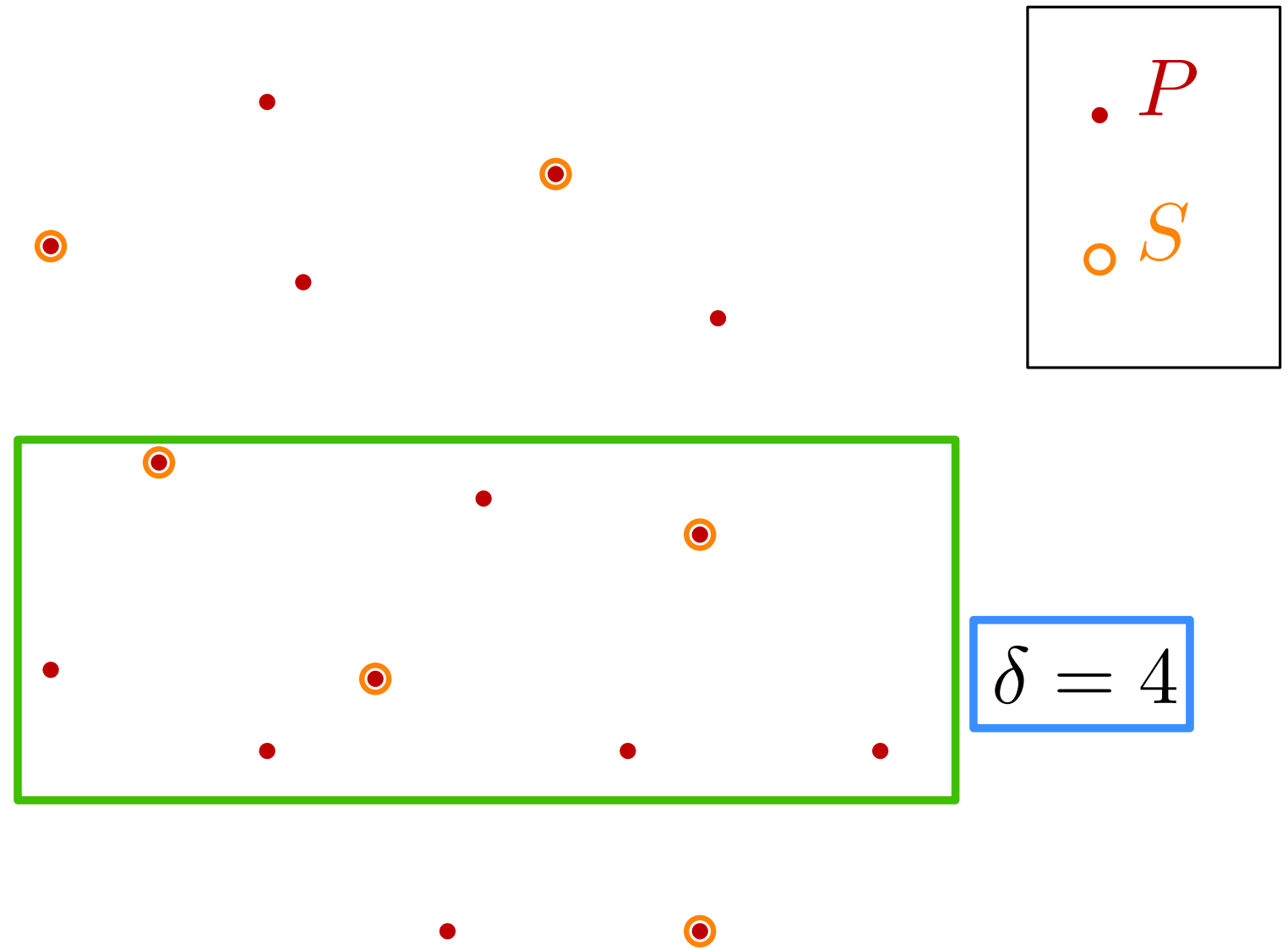
Given P ,

how many points do we need to sample ($S \subset P$), such that

2. for any query rectangle r

$$\left| \frac{|r \cap P|}{|P|} - \frac{|r \cap S|}{|S|} \right| \leq 0.25 \boxed{= \varepsilon} ?$$

with probability $0.999 \boxed{= 1 - \varphi}$



answer: $O\left(\frac{1}{\varepsilon^2} (4 + \log \phi^{-1})\right)$,

in particular $O(1)$ for given ε, φ independent of n

ε -nets

ε -nets

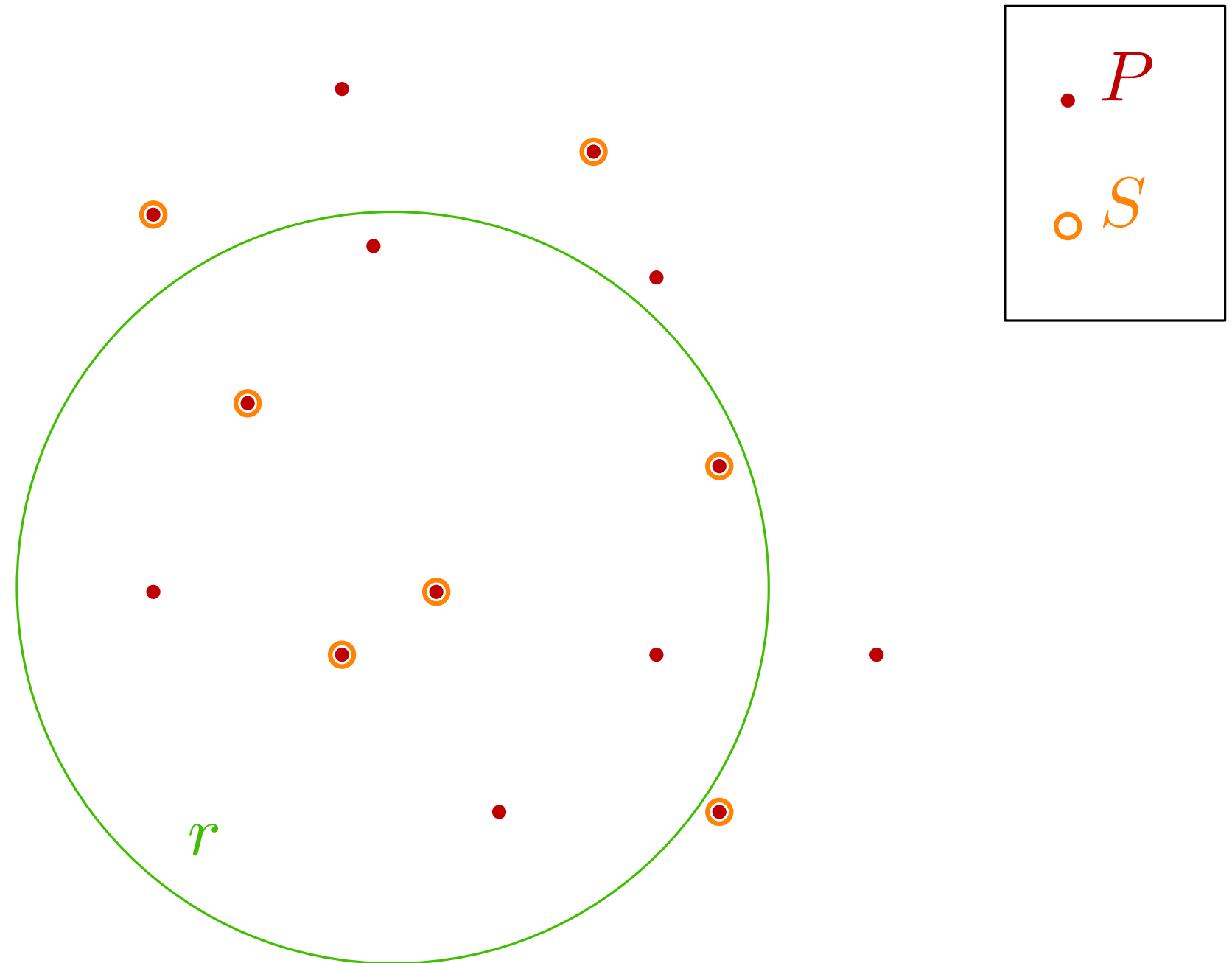
ε -sample S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

if $\mu(r) \geq \varepsilon$ and

$$|\mu(r) - \hat{\mu}(r)| \leq \varepsilon \text{ then } \hat{\mu}(r) > 0$$



ε -nets

ε -sample S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

if $\mu(r) \geq \varepsilon$ and

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weaker notion:

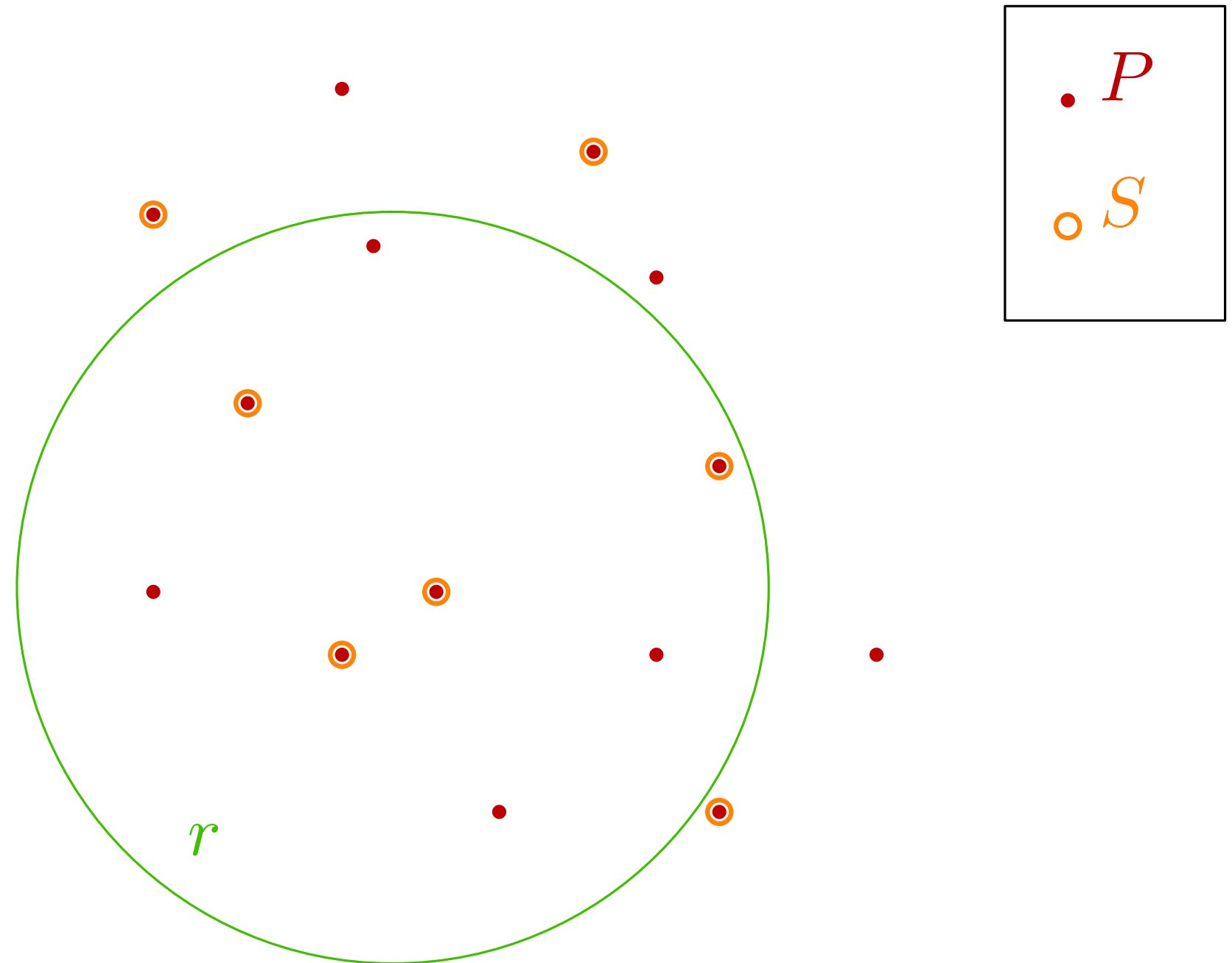
ε -net S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

if $\mu(r) \geq \varepsilon$ then r contains

at least one point of S



ε -nets

ε -sample S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

if $\mu(r) \geq \varepsilon$ and

$$|\mu(r) - \hat{\mu}(r)| \leq \varepsilon \text{ then } \hat{\mu}(r) > 0$$

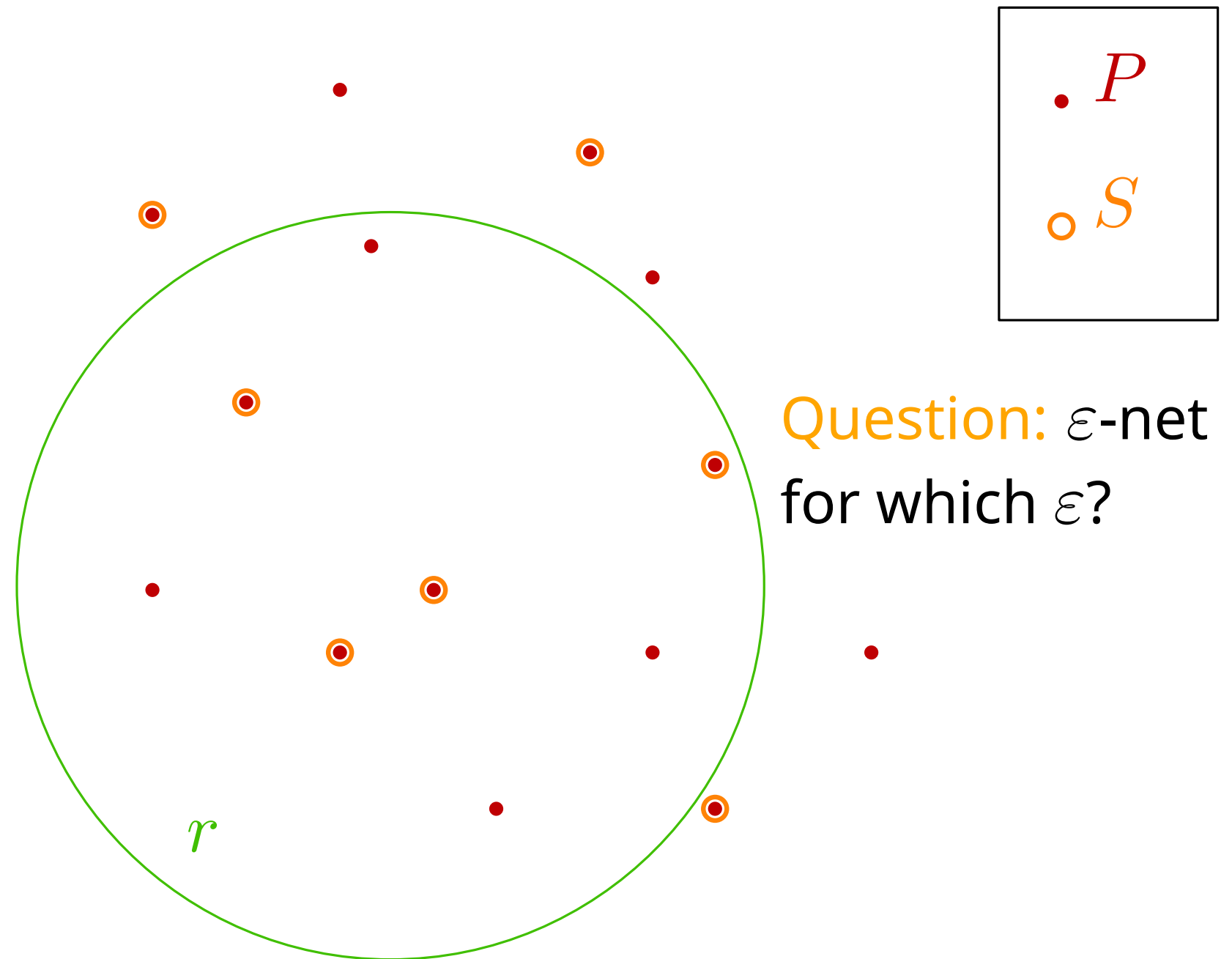
weaker notion:

ε -net S :

for all $r \in \mathcal{R}$ and any

$$0 \leq \varepsilon \leq 1$$

if $\mu(r) \geq \varepsilon$ then r contains
at least one point of S



ε -Net Theorem

Let $\varphi, \varepsilon > 0$ be parameters and (X, \mathcal{R}) be a range space with finite X and VC-dimension δ . A sample obtained by m random draws from X with

$$m \geq \max \left(\frac{4}{\varepsilon} \log \frac{4}{\varphi}, \frac{8\delta}{\varepsilon} \log \frac{16}{\varepsilon} \right)$$

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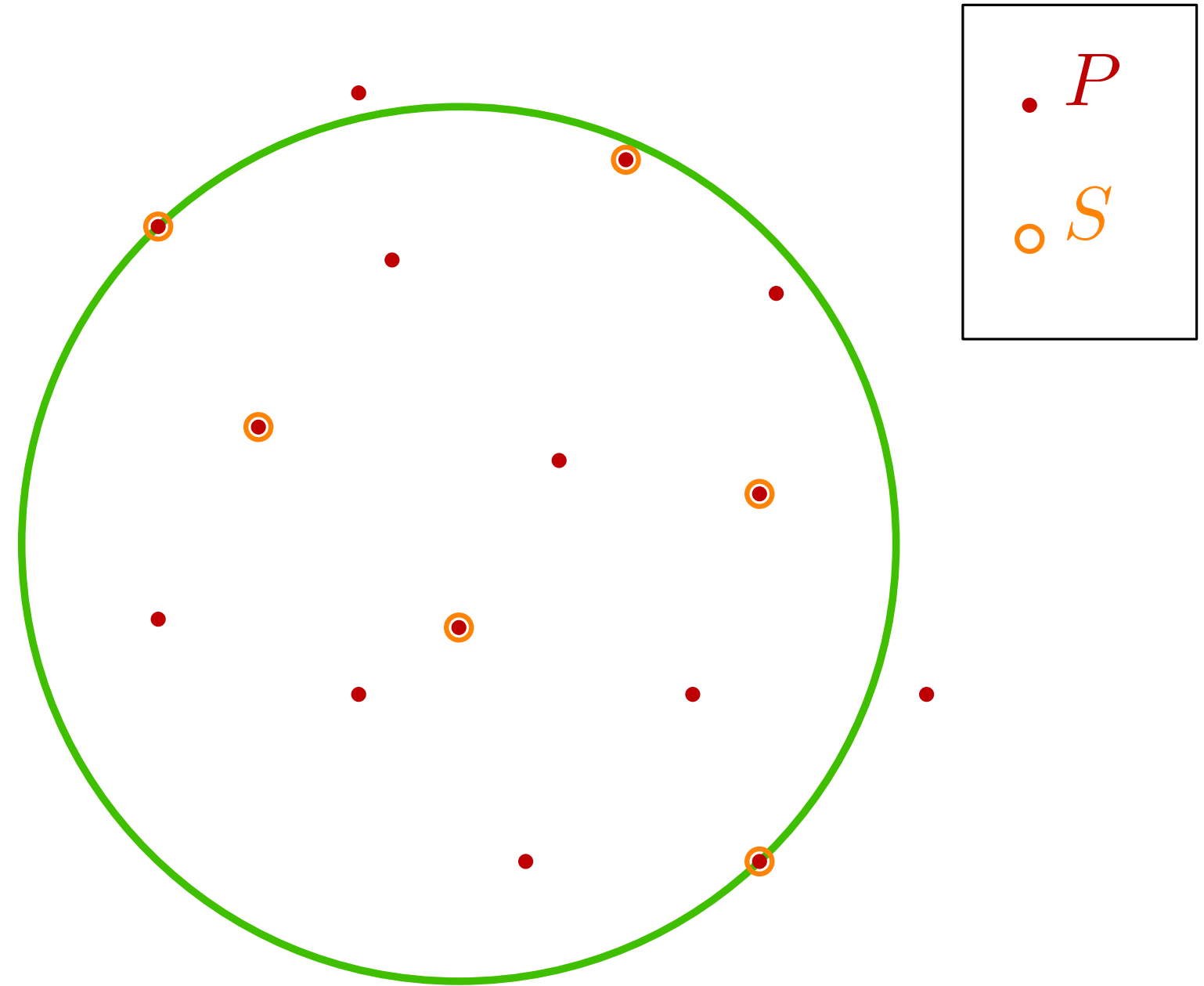
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in short: ε -sample $O\left(\frac{\delta}{\varepsilon^2}\right)$ vs ε -net $O\left(\frac{\delta}{\varepsilon} \log \frac{1}{\varepsilon}\right)$

Motivation: sampling for approximation

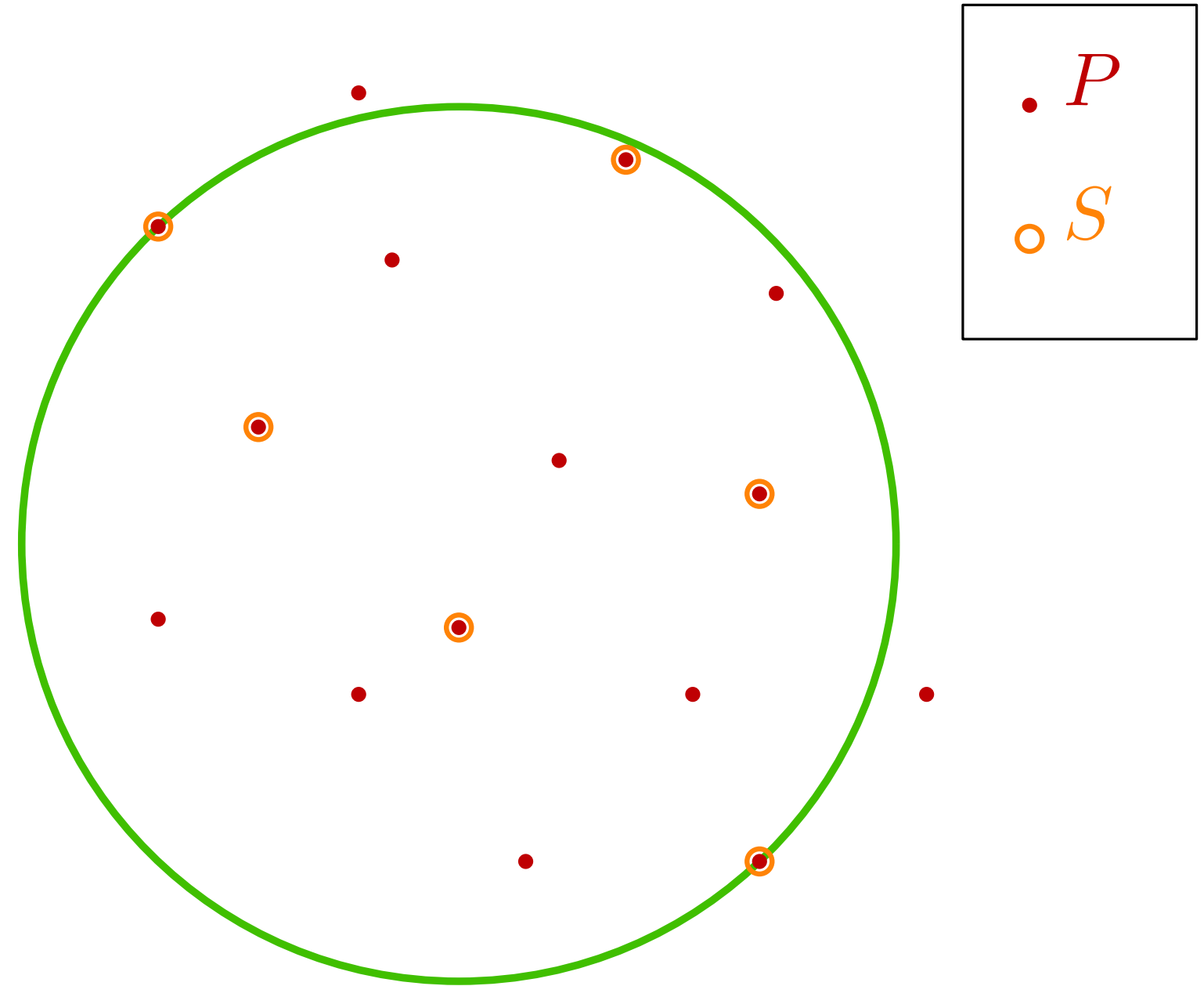
Given P , how many points do we need to sample ($S \subset P$), such that the **smallest enclosing disk** contains 90% of the points in P with probability 0.999



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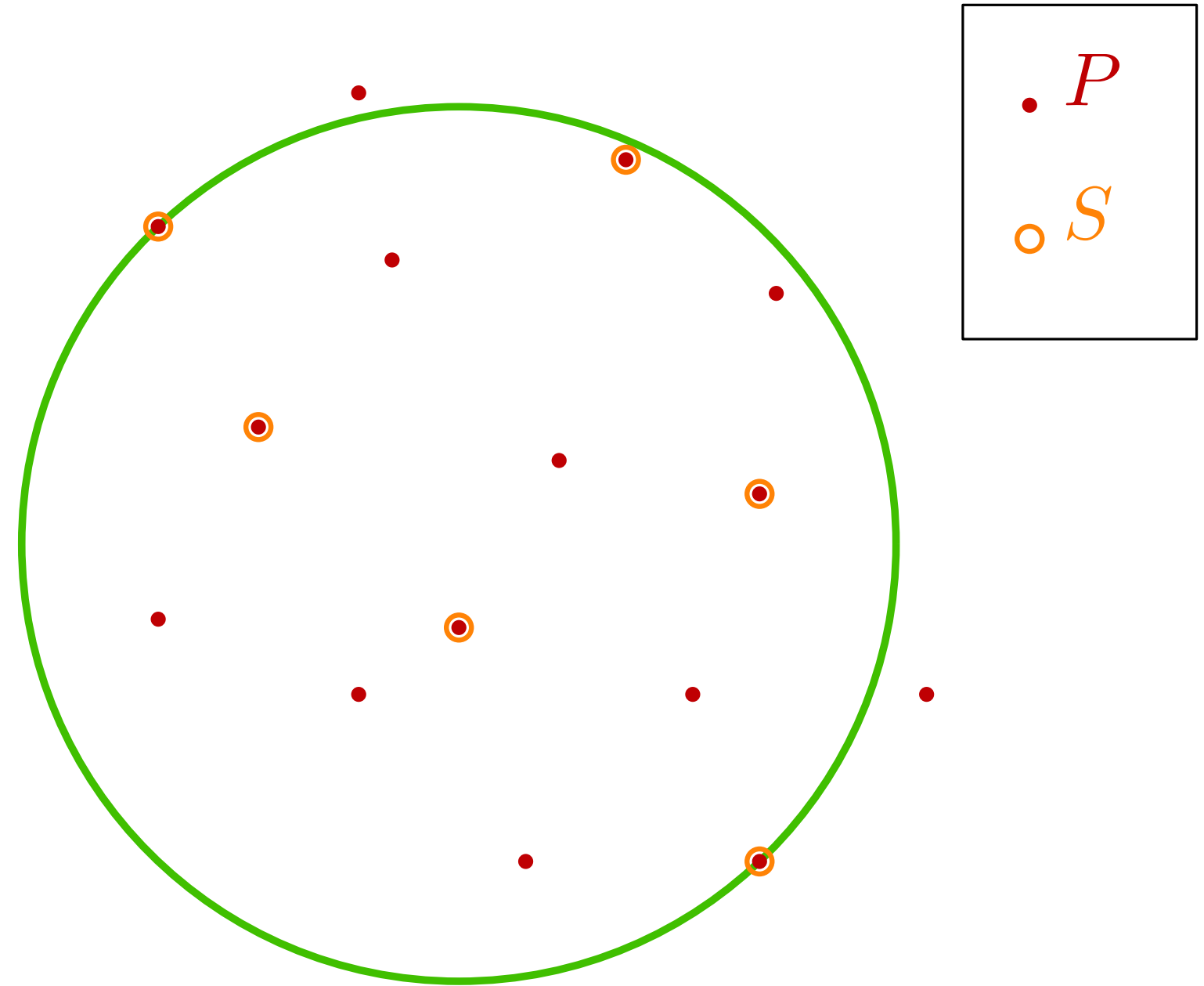


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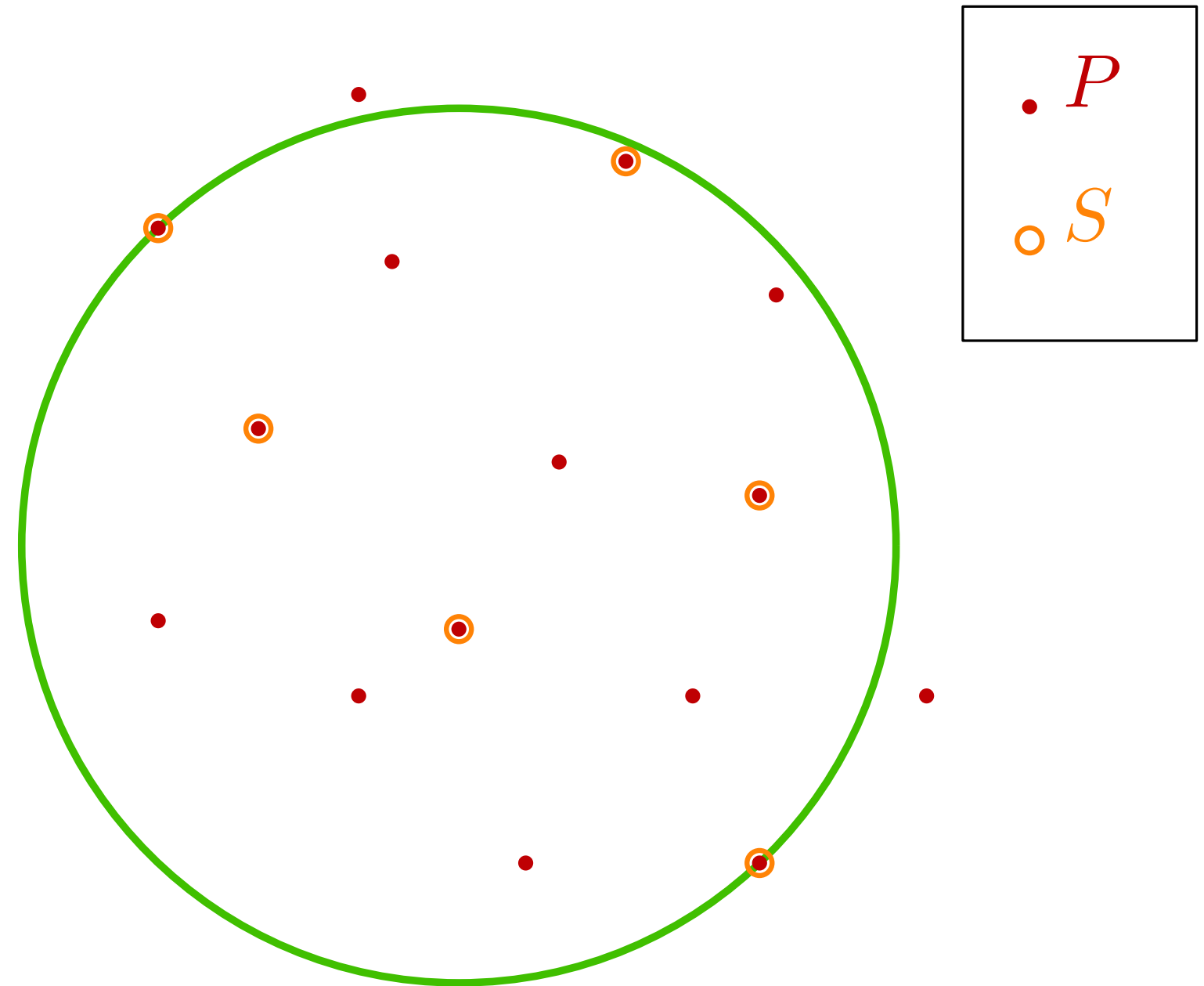
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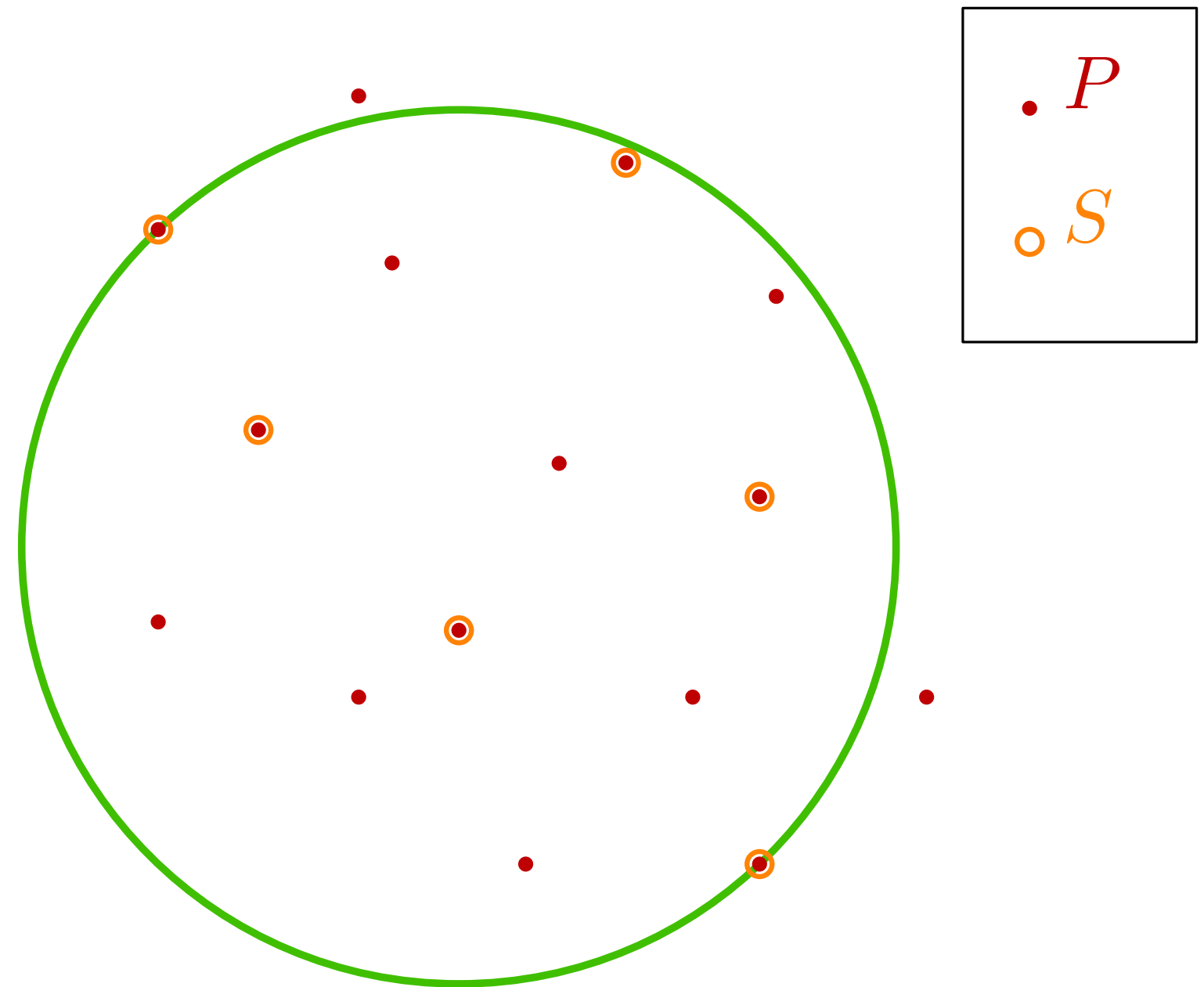
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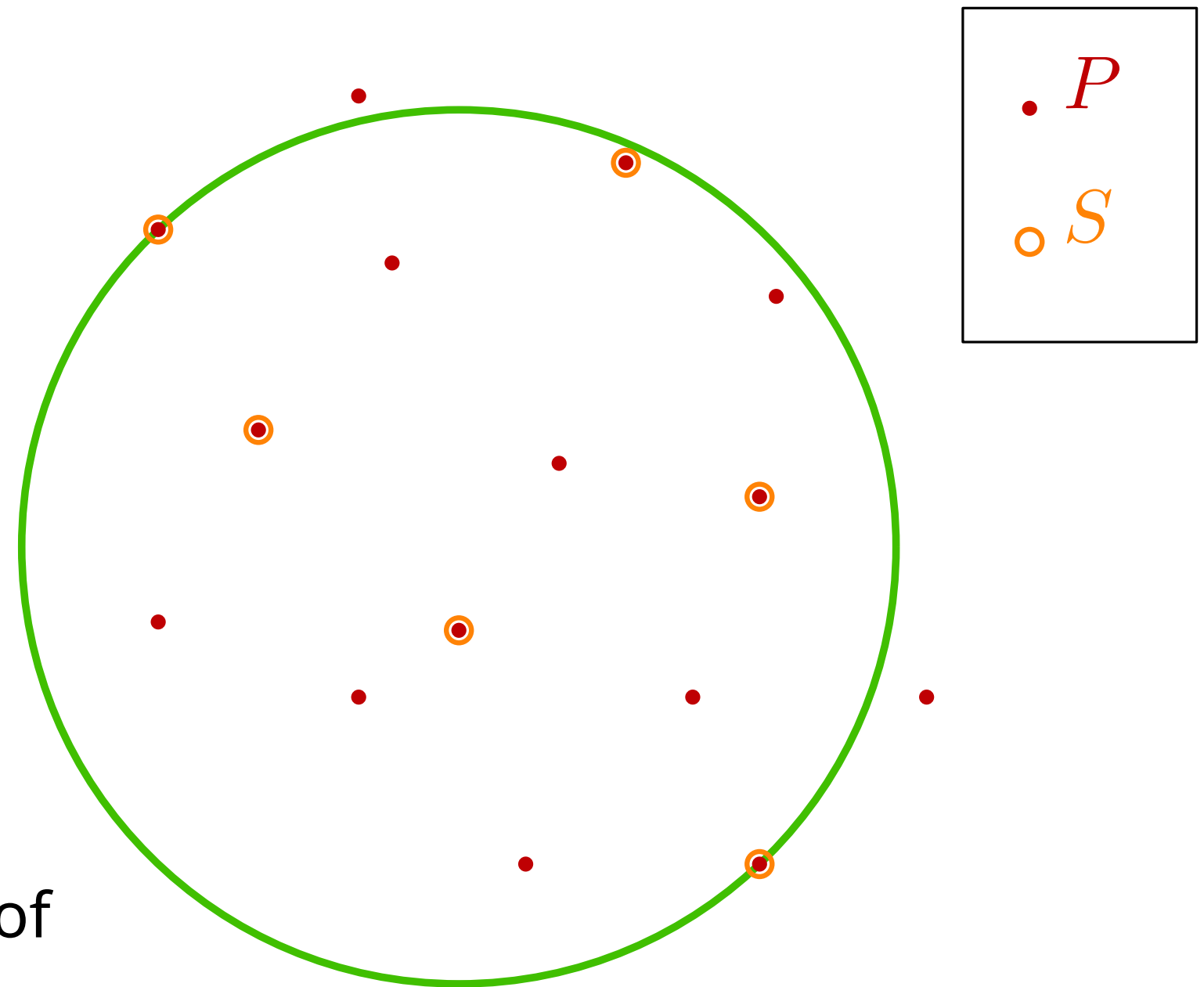
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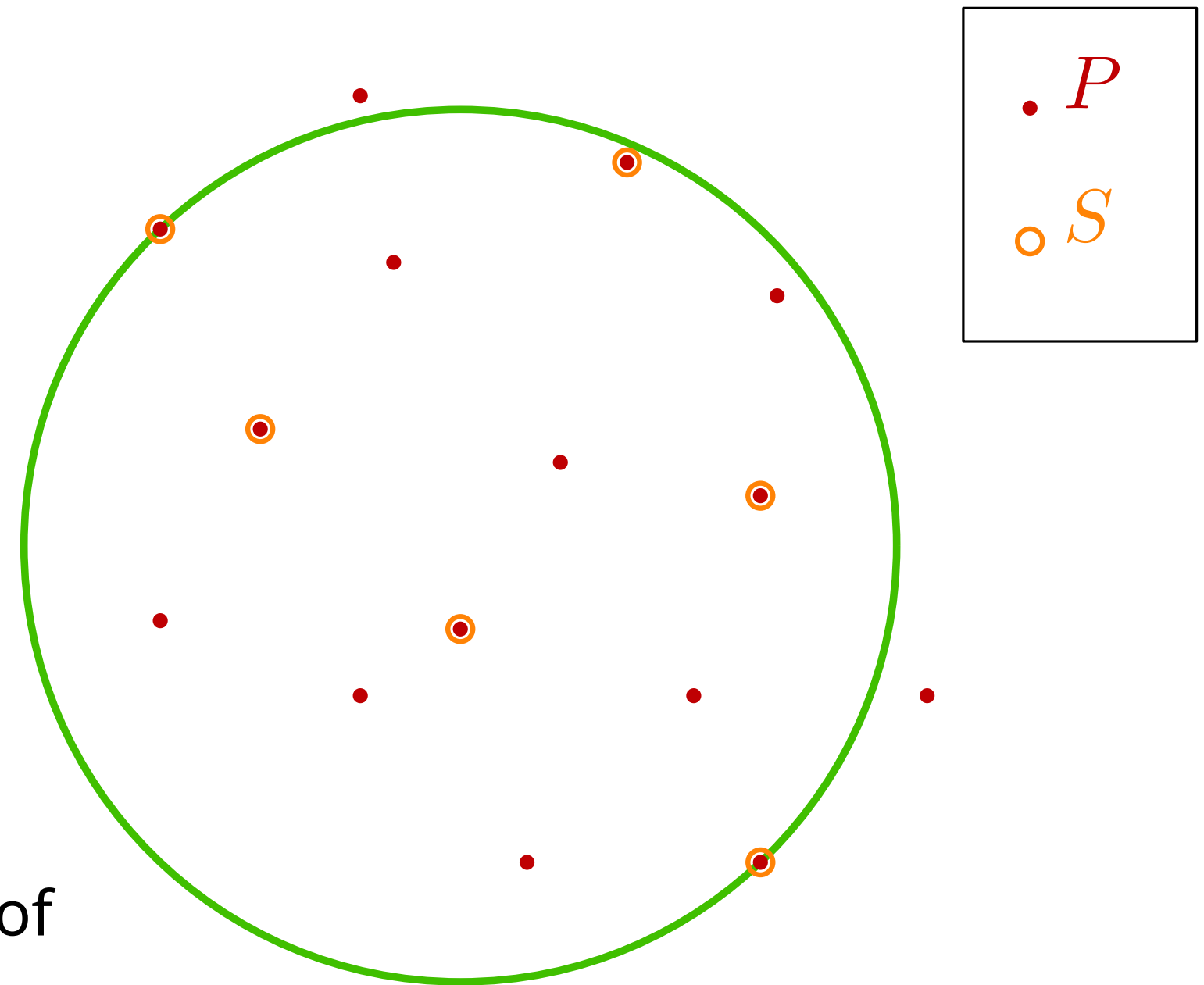
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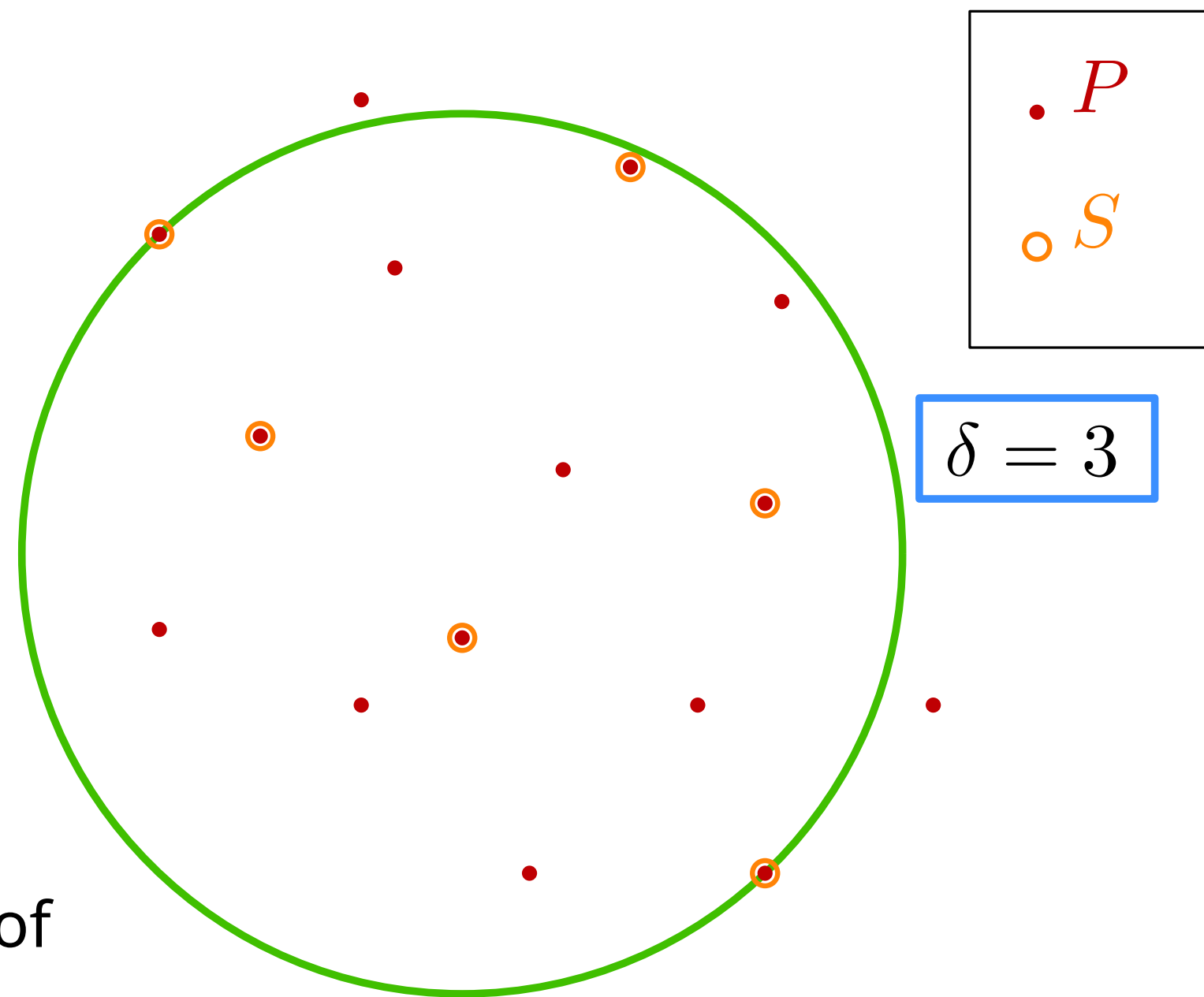
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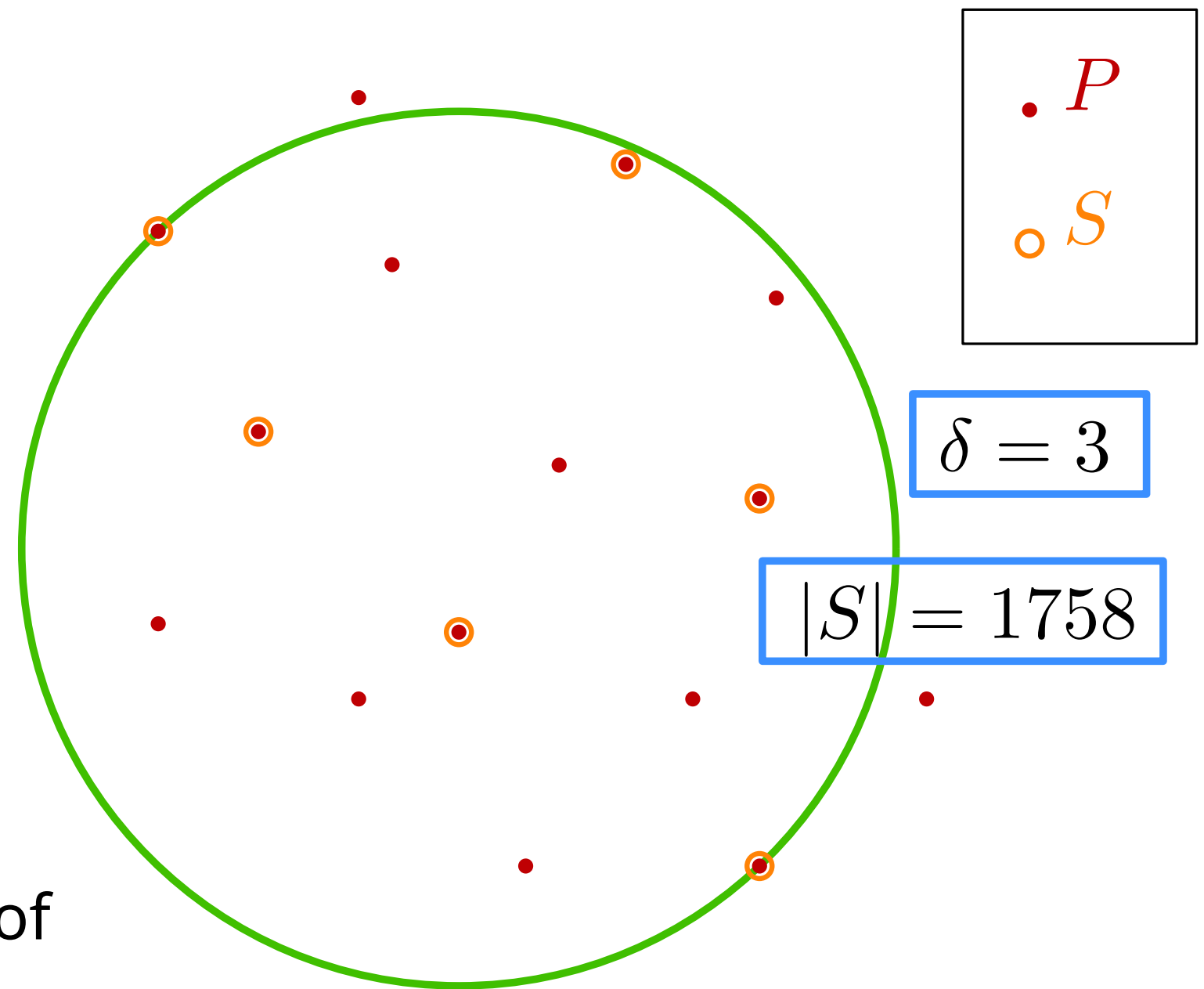
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Question: How large is $\log |\mathcal{R}|$?

Sauer's Lemma

bounding $|\mathcal{R}|$

Number of small subsets

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Intuition: Take element x : subsets don't contain x or do



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Base: $d = 0$ and $n = 0$ trivially true

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Step:

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These are exactly elements in \mathcal{R}_x !

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Which bound on $O\left(\frac{\log |\mathcal{R}|}{\varepsilon^2}\right)$ does the previous lemma give for (X, \mathcal{R}) with $n = |X|$ and VC-dimension δ ?

A $O\left(\frac{\delta}{\varepsilon^2}\right)$

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What does $|\mathcal{R}| = O(n^d)$ imply about the VC-dimension?

Shattering dimension

Shattering Dimension

Given a range space $\mathcal{S} = (X, \mathcal{R})$, its **shatter function** $\pi_{\mathcal{S}}(m)$ is the maximum number of sets that might be created by \mathcal{S} when restricted to subsets of size m . Formally,

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Shattering Dimension

Given a range space $S = (X, \mathcal{R})$, its **shatter function** $\pi_S(m)$ is the maximum number of sets that might be created by S when restricted to subsets of size m . Formally,

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The **shattering dimension** of S is the smallest d such that $\pi_S(m) = O(m^d)$, for all m

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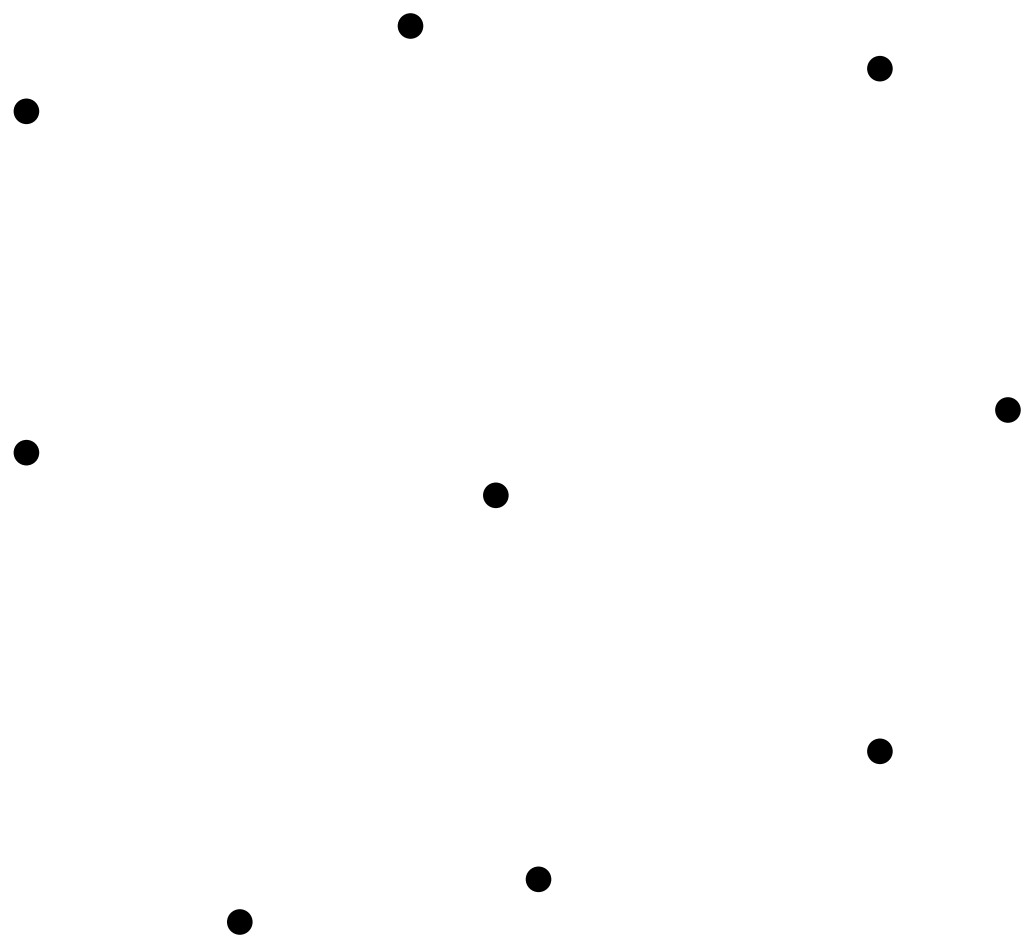
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Sauer's lemma: shattering dimension \leq VC-dimension

Examples of Shattering Dimension

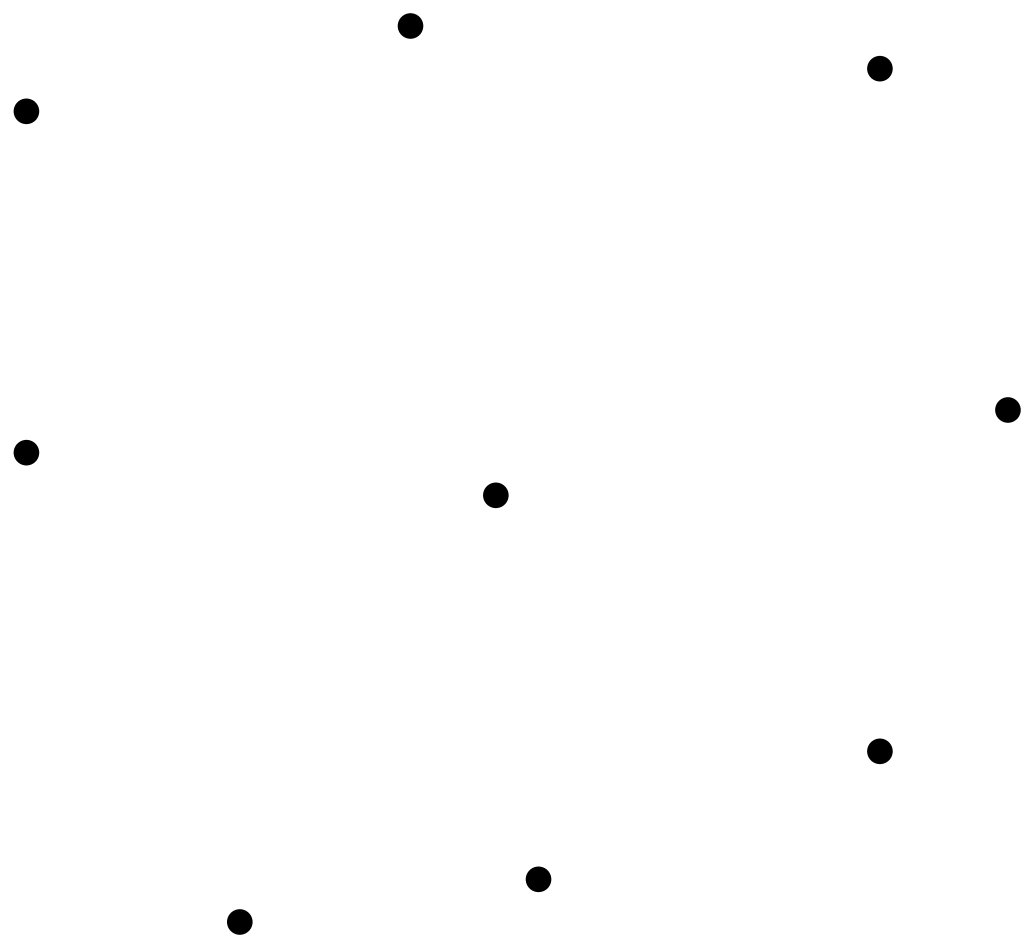
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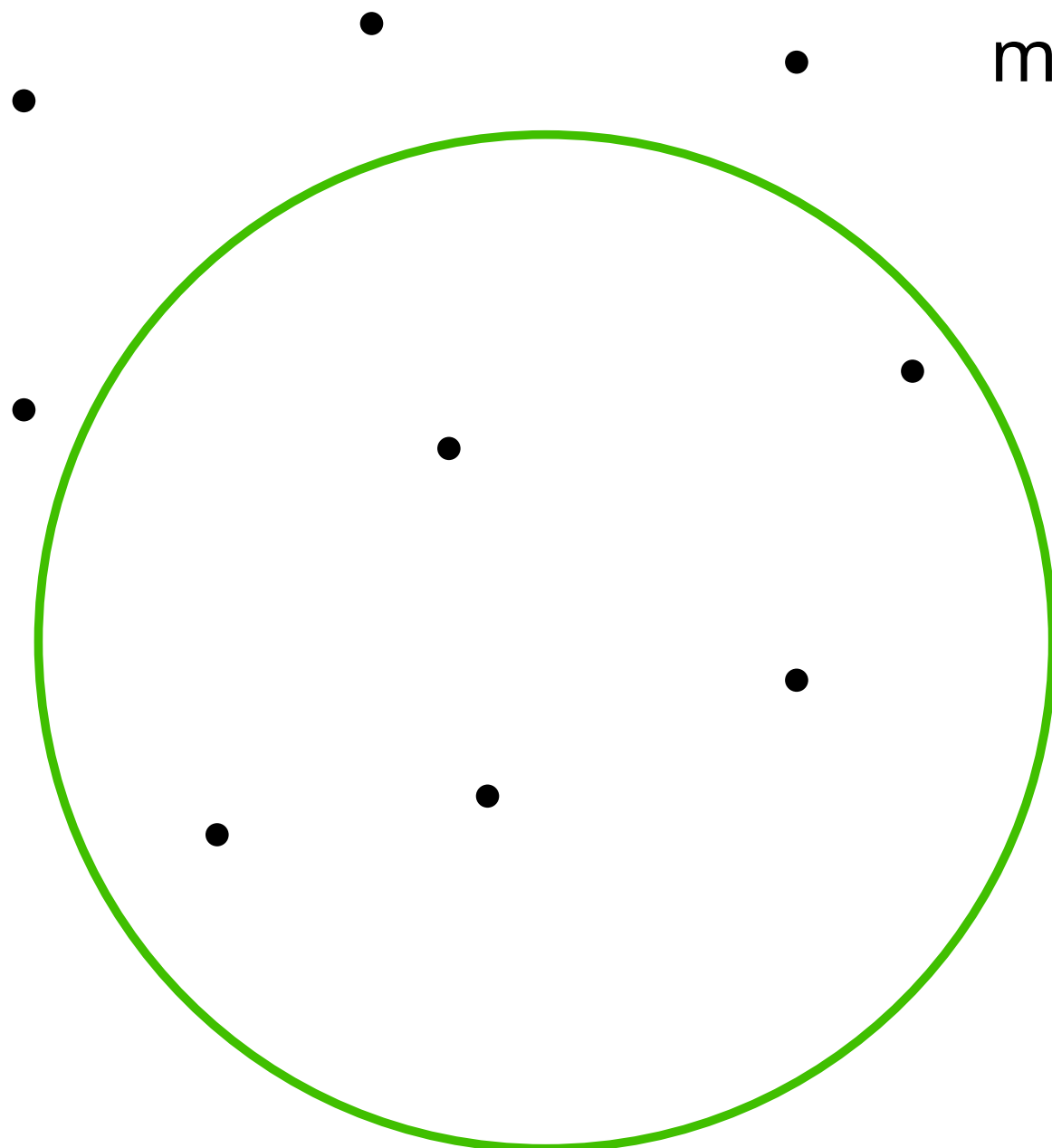
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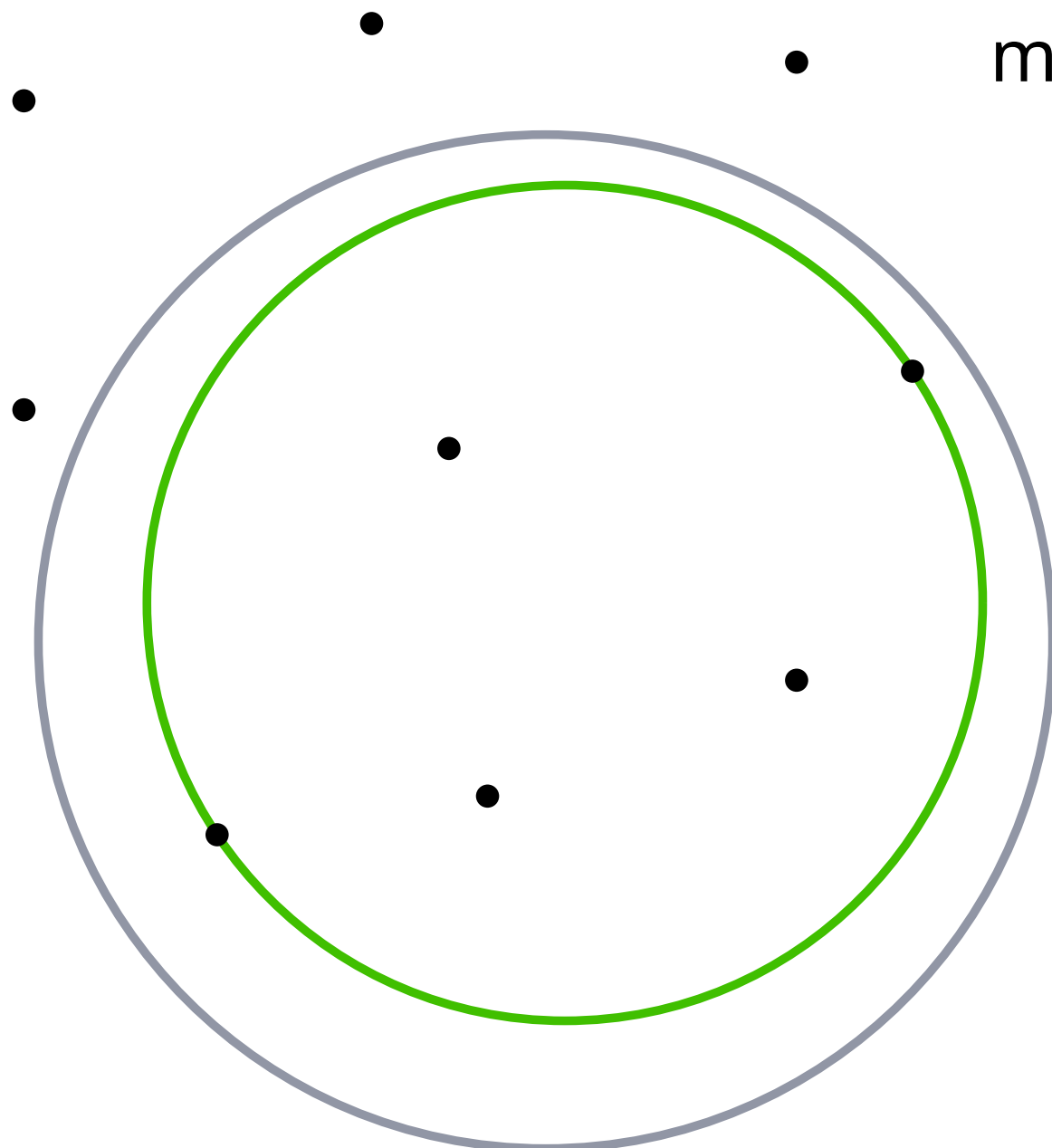


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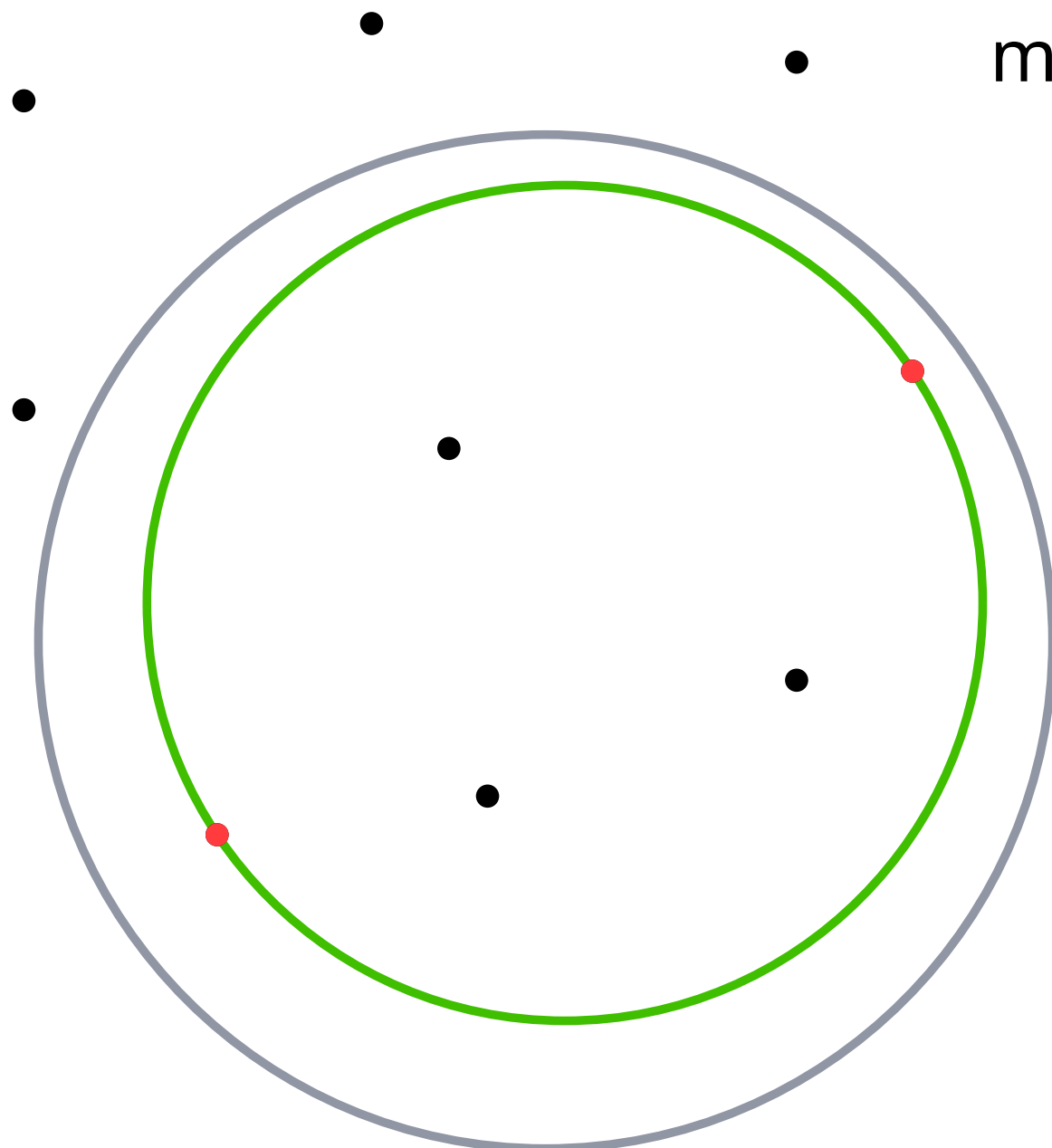
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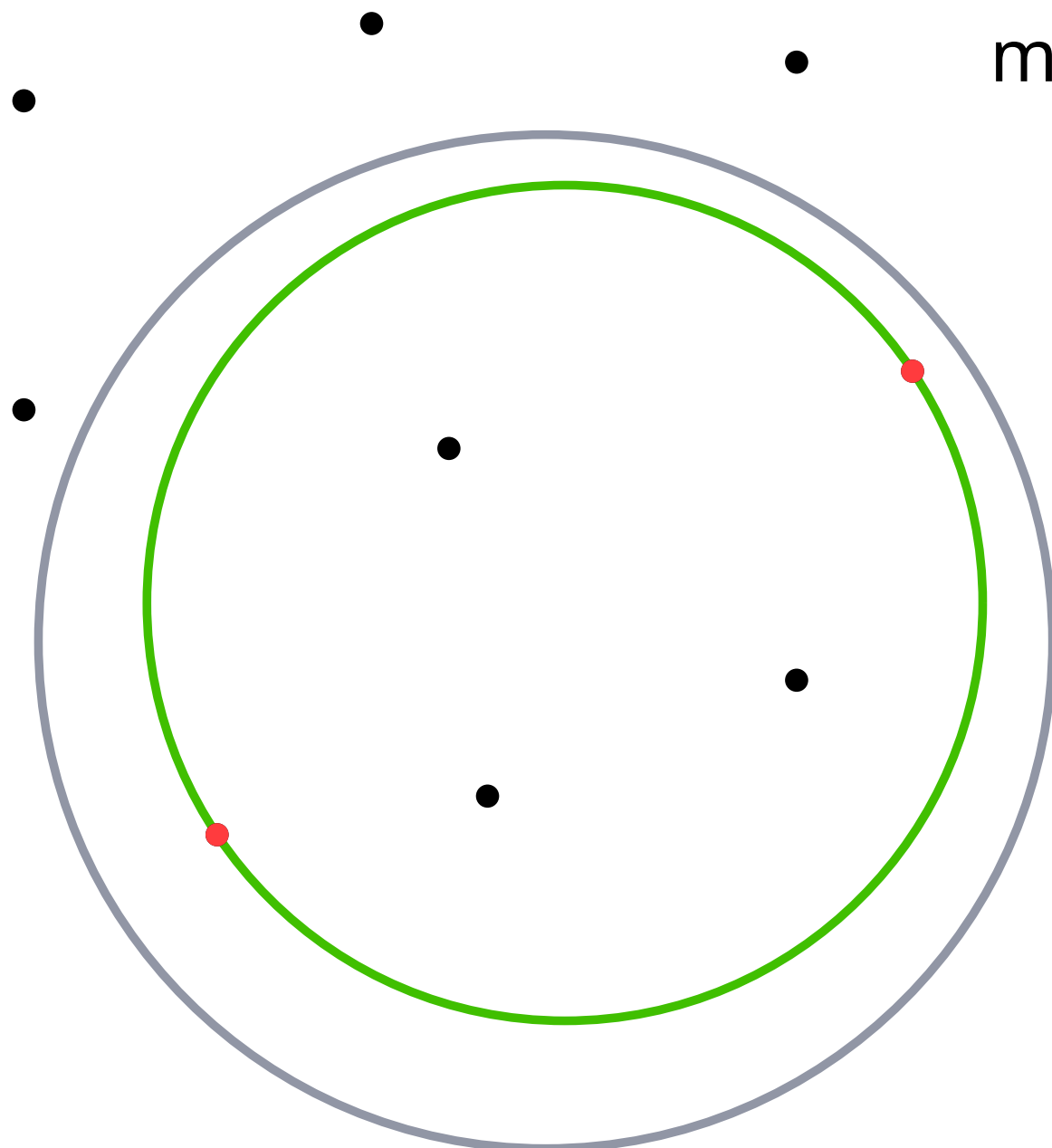
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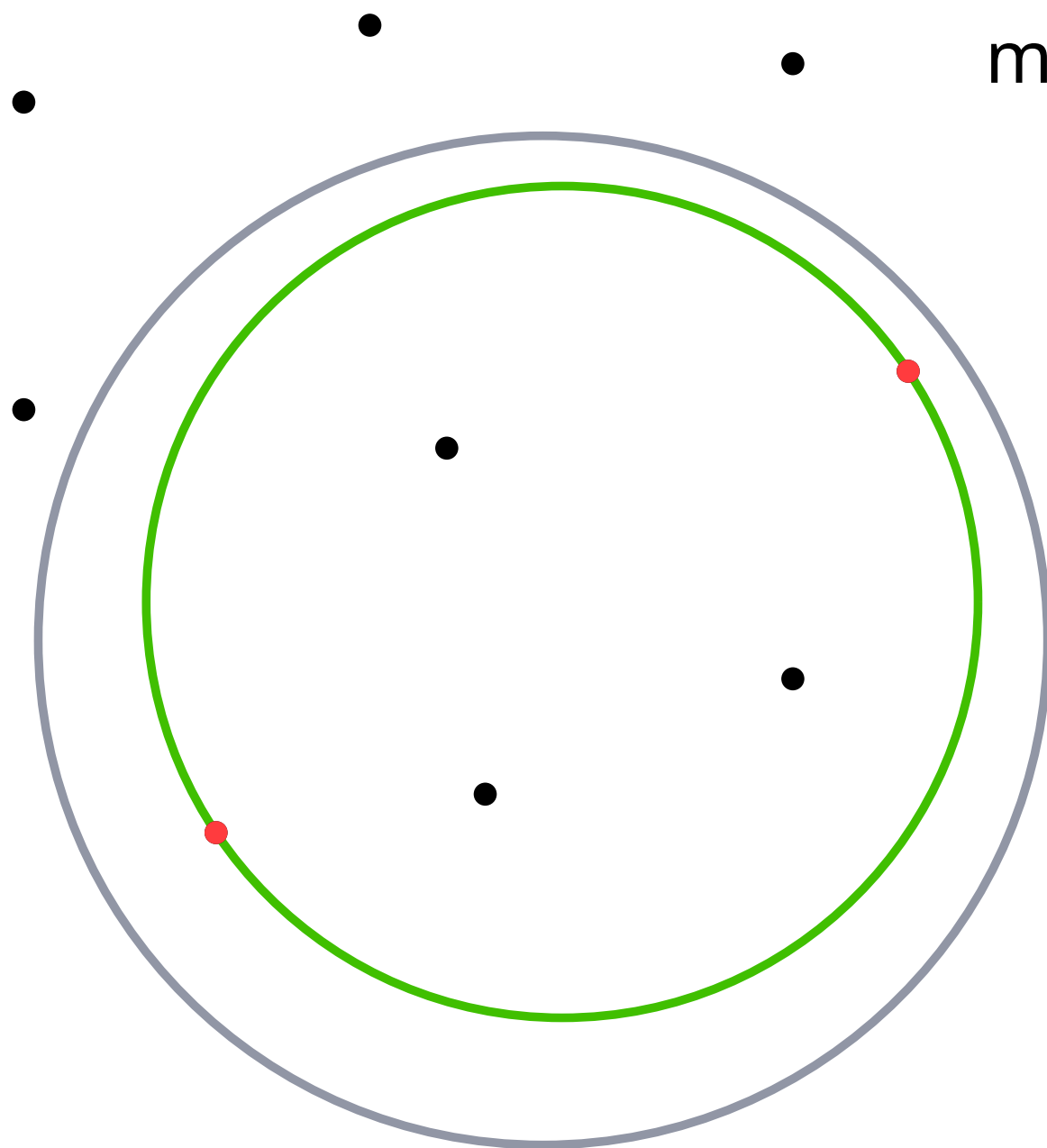
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shattering dim ≤ 3

Shattering dimension of geometric range spaces

shattering dimension \approx how many points determine a range

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range space

$(\mathbb{R}, \mathcal{I})$, with $\mathcal{I} =$ set of closed intervals ?

$(\mathbb{R}^2, \mathcal{D})$, with $\mathcal{D} =$ set of disks

$(\mathbb{R}^2, \mathcal{AR})$, with $\mathcal{AR} =$ set of axis-aligned rectangles

$(\mathbb{R}^2, \mathcal{GR})$, with $\mathcal{GR} =$ set of arbitrary oriented rectangles

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4

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-

Can be easier to compute than VC-dimension

Shattering dimension vs VC-dimension

VC-dimension δ

shattering dimension d

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Consider largest shattered $N \subset X$: $\delta = |N|$

$$2^\delta = |\mathcal{R}|_N \leq c\delta^d$$

$$\delta \leq \log(c) + d \log \delta$$

$$\log \delta \leq \log(\log(c) + d \log \delta) = O(\log(d \log \delta)) = O(\log d + \log \log \delta)$$

Shattering dimension vs VC-dimension

VC-dimension δ

shattering dimension d

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Summary

range space (X, \mathcal{R})

VC-dimension δ

examples of geometric range spaces

ε -sample of size $O\left(\frac{\delta + \log(\varphi^{-1})}{\varepsilon^2}\right)$

ε -net of size $O\left(\frac{\delta \log \varepsilon^{-1} + \log(\varphi^{-1})}{\varepsilon}\right)$

applications for geometric approximation

shattering dimension d

$$d \leq \delta \leq d \log d$$